# THE COERCIVENESS FOR INTEGRO-DIFFERENTIAL QUADRATIC FORMS AND KORN'S INEQUALITY 

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## Introduction

Let $\Omega$ be a bounded open set of $\boldsymbol{R}^{n}(n \geqq 2)$ with a $C^{\infty}$ boundary $\Gamma$ and assume that $a_{\alpha \beta}^{i j}(x)\left(|\alpha|=s_{i},|\beta|=s_{j} ; i, j=1, \cdots, N\right)$ be functions in $C^{\infty}(\bar{\Omega})$ such that $\overline{a_{\alpha \beta}^{2 j}(x)}=a_{\beta \alpha}^{j i}(x)$, where $s_{1}, \cdots, s_{N}$ are integers $\geqq 1$ and $\alpha=\left(\alpha_{1}, \cdots, \alpha_{n}\right), \beta=\left(\beta_{1}, \cdots, \beta_{n}\right)$ are $n$-tuples of non-negative integers with $|\alpha|=\alpha_{1}+\cdots+\alpha_{n},|\beta|=\beta_{1}+\cdots+\beta_{n}$. Then we consider an integrodifferential bilinear form

$$
Q[u, v]=\sum_{i, j=1}^{N} \int_{\Omega} \sum_{|\alpha|=s_{i}} \sum_{|\beta|=s_{j}} a_{\alpha \beta}^{i j}(x) D^{\alpha} u_{i} \overline{D^{\beta} v_{j}} d x
$$

over a Sobolev space

$$
H_{(s)}(\Omega)=\left\{u=\left(u_{1}, \cdots, u_{N}\right) ; u_{j} \in H_{s_{j}}(\Omega), j=1, \cdots, N\right\}
$$

where $D^{\alpha}=D_{1}^{\alpha_{1}} \cdots D_{n}^{\alpha_{n}}$ with $D_{j}=-i \partial / \partial x_{j}(i=\sqrt{-1})$.
We shall say that the quadratic form $Q[u, u]$ is coercive over a subspace $V$ of $H_{(s)}(\Omega)$ if there exist two constants $c_{1}>0$ and $c_{0}$ such that

$$
Q[u, u] \geqq c_{1}\|u\|_{(s)}^{2}-c_{0}\|u\|_{0}^{2}, \quad u \in V,
$$

where

$$
\|u\|_{(s)}^{2}=\sum_{i=1}^{N}\left\|u_{i}\right\|_{s_{i}}^{2} .
$$

It is well-known that $Q[u, u]$ is coercive over $C_{0}^{\infty}(\Omega)^{N}$ (i.e. the Gårding inequality holds) if and only if there exists a constant $c>0$ such that the inequality

Revised April 13, 1978.

$$
\sum_{i, j=1}^{n}\left(\sum_{|\alpha|=s_{i}} \sum_{|\beta|=s_{j}} a_{\alpha \beta}^{i j}(x) \xi^{\alpha+\beta}\right) \eta_{i} \bar{\eta}_{j} \geqq c \sum_{j=1}^{n}|\xi|^{s_{i}}\left|\eta_{j}\right|^{2}
$$

holds for every $x \in \bar{\Omega}$, every $\xi \in \boldsymbol{R}^{n}$ and every $\eta \in \boldsymbol{C}^{N}$ (strong ellipticity).
In applying the variational approach to elliptic boundary value problems, the space $V$ is usually given by a system of differential operators defined on $\Gamma$. Let $B_{(i, p)}^{j}(x, D)\left(p=0, \cdots, s_{i}-1 ; i, j=1, \cdots, N\right)$ be linear partial defferential operators with coefficients in $C^{\infty}(\Gamma)$ homogeneous of order $s_{j}-s_{i}+p$ and assume that this system is normal, i.e., for any $P \in \Gamma$ and any real, non-zero vector $\dot{\xi}$ tangent to $P$ (the totality of such $\dot{\xi}$, we denote by $T_{p}$ ), let us regard $B_{(i, p)}^{j}(P, \dot{\xi}+\tau \nu(P))$ as polynomials in $\tau(\nu(P)$ denotes the unit inner normal vector to $\Gamma$ at $P$ ), then

$$
\sum_{i, p} C_{(i, p)} B_{\langle i, p)}^{j}(P, \xi+\tau \nu(P))=0, \quad j=1, \cdots, N
$$

only if the constants $C_{(i, p)}$ are all zero, where summation $\sum_{i, p}$ means $\sum_{i=1}^{N} \sum_{p=0}^{s_{i}-1}$. Let $S_{1}, S_{2}$ be two subsets of the set

$$
M=\bigcup_{i=1}^{N}\left\{(i, p) ; p=0, \cdots, s_{i}-1\right\}
$$

and $\Gamma_{1}, \Gamma_{2}$ be the disjoint open portions of $\Gamma$ such that $\bar{\Gamma}_{1} \cup \bar{\Gamma}_{2}=\Gamma$ and $\gamma=\bar{\Gamma}_{1} \cap \bar{\Gamma}_{2}$ is a $C^{\infty}$-manifold of dimension $n-2$. Then we introduce the closed subspace of $H_{(s)}(\Omega)$ as follows:

$$
V\left(S_{1}, S_{2}\right)=\bigcap_{\alpha=1,2}\left\{u \in H_{(s)}(\Omega) ; \sum_{j=1}^{N} B_{(i, p)}^{j}(x, D) u_{j}=0 \text { on } \Gamma_{\alpha} \text { for }(i, p) \in S_{\alpha}\right\} .
$$

The mixed boundary value problems for strongly elliptic differential systems lead naturally to the investigation of coerciveness for quadratic forms $Q$ over $V\left(S_{1}, S_{2}\right)$. In [4], we have already studied this problem in the case $N=1$ and $s_{1}=m$. By a slight improvement of the argument used in [4], we can characterize the coerciveness for $Q$ over $V\left(S_{1}, S_{2}\right)$. We shall state briefly the main result in the following.

For any point $P$ fixed on $\Gamma$, denoting by $Q^{P}$ the form obtained by replacing $a_{\alpha \beta}^{i j}(x)$ with $a_{\alpha \beta}^{i j}(P)$ in the form $Q$ and integrating by part, we have Green's formula

$$
\begin{aligned}
Q^{P}[u, v]= & \int_{a} \sum_{i, j=1}^{N} A^{i j}(P, D) u_{i} \cdot \bar{v}_{j} d x \\
& +\int_{\Gamma} \sum_{j, q} \sum_{i=1}^{N} N_{(j, q)}^{i}(P, D) u_{i} \overline{D_{v}^{q} v_{j}} d \sigma,
\end{aligned}
$$

where

$$
A^{i j}(P, D)=\sum_{|\alpha|=s_{i}} \sum_{|\beta|=s_{j}} a_{\alpha \beta}^{i j}(P) D^{\alpha+\beta}
$$

and $N_{(j, q)}^{i}(P, D)$ are the differential operators on $\Gamma$ homogeneous of order $s_{i}+s_{j}-q-1$. For any $P \in \Gamma$, any $\dot{\xi} \in T_{P}$ and any $(i, p) \in M$, we denote $h_{j}^{(i, p)}(\dot{\xi}, t)(j=1, \cdots, N)$ the exponentially decaying solution of the Dirichlet problem

$$
\begin{cases}\sum_{j=1}^{N} A^{i j}\left(P, \dot{\xi}+\nu(P) D_{t}\right) u_{j}=0 & \text { in } t>0 \\ D_{t}^{q} u_{j}=\delta_{(j, \psi)}^{(i, p)} & \text { for }(j, q) \in M \text { on } t=0\end{cases}
$$

where $\delta_{(j, q)}^{(i, p)}$ denotes Kronecker's delta. For any $(i, p),(j, q) \in M$, we set

$$
b_{(j, q)}^{(i, p)}(P, \dot{\xi})=\left.\sum_{k=1}^{N} N_{(j, q)}^{k}\left(P, \dot{\xi}+\nu(P) D_{t}\right) h_{k}^{(i, \nu)}(\dot{\xi}, t)\right|_{t=0} .
$$

The normality of the system $\left\{B_{(i, p)}^{j}\right\}$ guarantees that for each $(i, p),(j, q)$ $\in M$ there exists a number $e_{(i, 2, p)}^{(j, q)}(P, \dot{\xi})$ such that, for any $u(t)$,

$$
\begin{array}{r}
D_{i}^{p} u_{i}(t)=\sum_{j, q} e_{(i, p)}^{(j, q)}(P, \dot{\xi}) \sum_{k=1}^{N} B_{(j, q)}^{k}\left(P, \dot{\xi}+\nu(P) D_{t}\right) u_{k}(t) \\
\text { on } t=0, p=0, \cdots, s_{i}-1 .
\end{array}
$$

For a subset $S$ of $M$ and a $\dot{\xi} \in T_{P}$, we introduce a subspace of $C^{s}\left(s=s_{1}\right.$ $+\cdots+s_{N}$ ) as follows;

$$
\begin{gathered}
L_{\xi}^{P}(S)=\left\{\left(\sum_{j, q} e_{(i, p)}^{(j, q)}(P, \dot{\xi}) b_{(j, q)}\right)_{(i, p) \in M} ; b \in C^{s}\right. \text { such that } \\
\left.b_{(j, q)}=0 \text { for }(j, q) \in S\right\} .
\end{gathered}
$$

Then we have
Theorem. In order that the $Q[u, u]$ be coercive over $V\left(S_{1}, S_{2}\right)$, it is necessary and sufficient that for every $P$ on $\bar{\Gamma}_{\alpha}(\alpha=1,2)$ there exists a constant $c>0$ such that for any $\dot{\xi},|\dot{\xi}|=1$, in $T_{P}$ the inequality

$$
\sum_{i, p} \sum_{j, q} b_{(j, q)}^{(i, p)}(P, \dot{\xi}) a_{(i, p)}(\dot{\xi}) \overline{a_{(j, q)}(\xi)} \geqq c \sum_{(i, p)}\left|a_{(i, p)}(\dot{\xi})\right|^{2}
$$

holds for every $\left(\alpha_{(i, p)}(\dot{\xi})\right) \in L_{\xi}^{P}\left(S_{\alpha}\right)$.
In this paper, we shall confine ourself to the proof of the theorem in which $s_{1}=\cdots=s_{N}=1$, because this special case remains the essen-
tial part of the proof and the general case has nothing but a further complication. As its application, we shall give an another proof of Korn's inequality which is fundamental in the boundary value problem of linear elastostatics.

In section 1, we shall reduce the problem to the coerciveness problem for quadratic forms with constant coefficients over some space contained in $H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$. With this reduced problem we deal in Section 2 (see Theorem 1). The algebraic condition for coerciveness is given in Section 3 (see Theorem 2). Section 4 is devoted to quadratic forms with variable coefficients and the main theorem (Theorem 3) is proved there. In Section 5, we shall apply this theorem to a formally positive quadratic form (see Theorem 4) and, as an example, deduce Korn's inequality.

## § 1. Localization of the problem

We consider the integro-differential quadratic form

$$
\begin{equation*}
Q[u, u]=\int_{\Omega} \sum_{i, j=1}^{n}\left\langle a_{i j}(x) D_{i} u, D_{j} u\right\rangle d x \tag{1.1}
\end{equation*}
$$

on the closed subspace $V$ of $H_{1}(\Omega)^{N}$ which contains $C_{0}^{\infty}(\Omega)$, where $a_{i j}(x)$ ( $i, j=1, \cdots, n$ ) are $N$-square matrices with entries in $C^{\infty}(\bar{\Omega}), u=\left(u_{1}, \cdots\right.$, $\left.u_{N}\right) \in V$ and

$$
\langle a, b\rangle=\sum_{j=1}^{N} a_{j} \bar{b}_{j} \quad \text { for } a, b \in \boldsymbol{C}^{N} .
$$

Here we can assume that

$$
\begin{equation*}
a_{i j}(x)^{*}=a_{j i}(x), \quad i, j=1, \cdots, n \tag{1.2}
\end{equation*}
$$

hold for every $x \in \Omega\left(a_{i j}(x)^{*}\right.$ denotes the adjoint matrix of $\left.a_{i j}(x)\right)$ and that there exists a constant $c>0$ such that the inequality

$$
\begin{equation*}
\left\langle\left(\sum_{i, j=1}^{n} a_{i j}(x) \xi_{i} \xi_{j}\right) a, a\right\rangle \geqq c|\xi|^{2}|a|^{2} \tag{1.3}
\end{equation*}
$$

holds for every $x \in \bar{\Omega}$, every $\xi \in R^{n}$ and every $a \in C^{N}$, as far as the coerciveness over $V$ is concerned (see Lecture 14 of [1]). We further assume that $V$ satisfies the property:

$$
\begin{equation*}
\zeta u \in V \text { for any } u \in V \text { and } \zeta \in C^{\infty}(\bar{\Omega}) . \tag{1.4}
\end{equation*}
$$

By freezing any point $P$ on $\Gamma$, we introduce a quadratic form with constant matrices $a_{i j}(P)$ :

$$
Q^{P}[u, u]=\int_{\Omega} \sum_{i, j=1}^{N}\left\langle a_{i j}(P) D_{i} u, D_{j} u\right\rangle d x
$$

Then we have
Proposition 1.1. In order that the form (1.1) be coercive over $V$, it is necessary and sufficient that

$$
\left\{\begin{array}{l}
\text { for every } P \in \Gamma \text {, there exists an } n \text {-dimensional open neighbour- } \\
\text { hood } G \text { of } P \text { such that } Q^{P}[u, u] \text { is coercive over a closed sub- }  \tag{1.5}\\
\text { space } V_{G} \text { of } V \text { : } \\
\qquad V_{G}=\{u \in V ; \operatorname{supp}[u] \subset G\}
\end{array}\right.
$$

Let $y=\left(y_{1}, \cdots, y_{n}\right)$ be a Cartesian coordinate system such that $y^{\prime}$ $=\left(y_{1}, \cdots, y_{n-1}\right)$ represents a coordinate systems of the tangent hyperplane through $P$ and $y_{n}$ a coordinate of the direction of inner normal to $\Gamma$ at $P$, and assume that the generic point $x \in \boldsymbol{R}^{n}$ can be written as $x=P$ $+S y$ with an orthogonal matrix $S$. It then follows that there exists an open neighbourhood $G$ of $P$ and a $C^{\infty}$-function $f_{P}\left(y^{\prime}\right)$ such that $\Gamma \cap G$ is represented by $y_{n}-f_{P}\left(y^{\prime}\right)=0$ and $f_{P}\left(y^{\prime}\right)$ together with $\partial f_{P} / \partial y_{j}(j=1$, $\cdots, n-1)$ vanishes at $y^{\prime}=0$. Therefore, by the coordinate transformation

$$
\chi_{P}:\left\{\begin{array}{l}
z_{j}=y_{j}, \quad i=1, \cdots, n-2  \tag{1.6}\\
z_{n-1}=y_{n-1}-g_{P}\left(y_{1}, \cdots, y_{n-2}\right) \\
z_{n}=y_{n}-f_{P}\left(y_{1}, \cdots, y_{n-1}\right)
\end{array}\right.
$$

$G \cap \Omega$ is mapped in a one-to-one way onto an open portion of a half space $\boldsymbol{R}_{+}^{n}=\left\{z \in \boldsymbol{R}^{n} ; z_{n}>0\right\}$ and $G \cap \Gamma$ is transformed onto an open portion of $z_{n}=0$, where $g_{P}$ is a $C^{\infty}$-function and together with $\partial g_{P} / \partial y_{j}(j=1$, $\cdots, n-2$ ) vanishes at ( $y_{1}, \cdots, y_{n-2}$ ) $=0$.

For $u \in V_{G}$, we define a function $\tilde{u}(z)$ on a half space $z_{n} \geqq 0$ by

$$
\tilde{u}(z)= \begin{cases}u\left(P+S \chi_{P}^{-1}(z)\right), & z \in \chi_{P}(G \cap \bar{\Omega}) \\ 0, & z \notin \chi_{P}(G \cap \bar{\Omega}), \quad z_{n} \geqq 0\end{cases}
$$

and set $\tilde{V}_{G}=\left\{\tilde{u} ; u \in V_{G}\right\}$. Then, by $Q_{1}^{P}[\tilde{u}, \tilde{u}]$ we denote the form

$$
\begin{equation*}
Q_{1}^{P}[\tilde{u}, \tilde{u}]=\int_{z_{n} \geqq 0} \sum_{i, j=1}^{N}\left\langle\tilde{a}_{i j}(P) D_{i} \tilde{u}, D_{j} \tilde{u}\right\rangle d z, \tag{1.7}
\end{equation*}
$$

where

$$
\tilde{a}_{i j}(P)=\sum_{k, \ell=1}^{n} s_{k i} a_{k \ell}(P) s_{\ell j}, \quad D_{j}=-i \partial / \partial z_{j},
$$

with $S=\left(s_{i j}\right)$. Since the coerciveness is invariant under coordinate transformations, we can establish

Proposition 1.2. In Proposition 1.1, we can replace (1.5) with $\left\{\begin{array}{l}\text { for every } P \in \Gamma, \text { there exists an open neighbourhood } G \text { of } P \text { such } \\ \text { that the form (1.7) is coercive over } \tilde{V}_{G} .\end{array}\right.$

For the proof of Propositions 1.1 and 1.2, we refer Propositions 3.1 and 3.2 of [4].

Now we introduce the spaces $V$ associated to mixed boundary value problems. Let $S_{1}, S_{2}$ be two subsets of the set $\{1,2, \cdots, N\}, \Gamma_{1}, \Gamma_{2}$ be the disjoint open portions of $\Gamma$ such that $\bar{\Gamma}_{1} \cup \bar{\Gamma}_{2}=\Gamma$ and $\gamma=\bar{\Gamma}_{1} \cap \bar{\Gamma}_{2}$ is a $C^{\infty}$-manifold of dimension $n-2$, and $b_{j}(x)(j=1, \cdots, N)$ be the given $N$-vectors with components in $C^{\infty}(\Gamma)$ which are linearly independent at each $x \in \bar{\Omega}$. We define as $V$ the closed subspace of $H_{1}(\Omega)^{N}$ :

$$
\begin{equation*}
V\left(S_{1}, S_{2}\right)=\bigcap_{\alpha=1,2}\left\{u \in H_{1}(\Omega)^{N} ;\left\langle\boldsymbol{b}_{j}(x), u\right\rangle=0 \text { on } \Gamma_{\alpha} \text { for } j \in S_{\alpha}\right\} \tag{1.9}
\end{equation*}
$$

Obviously it satisfies property (1.4).
In the below, we shall localize the boundary conditions. We set, for $P \in \Gamma_{\alpha}(\alpha=1,2)$

$$
V_{R}^{P}=\left\{u \in H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N} \cap \mathscr{E}_{R}^{\prime} ;\left\langle\boldsymbol{b}_{j}(P), u\right\rangle=0 \text { on } z_{n}=0 \text { for } j \in S_{\alpha}\right\},
$$

and for $P \in \gamma$

$$
V_{R}^{P}=\bigcap_{\alpha=1,2}\left\{u \in H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N} \cap \mathscr{E}_{R}^{\prime} ;\left\langle\boldsymbol{b}_{j}(P), u\right\rangle=0 \text { on } H_{\alpha} \text { for } j \in S_{\alpha}\right\},
$$

where and in the following we write, for simplicity, $\tilde{u}$ as $u$ and $\mathscr{E}^{\prime}\left(\Sigma_{R}\right)$ as $\mathscr{E}_{R}^{\prime \prime}$ with

$$
\Sigma_{R}=\left\{z \in R^{n} ;|z|<R, z_{n} \geqq 0\right\}
$$

and

$$
H_{1}\left(\text { resp. } H_{2}\right)=\left\{z \in \boldsymbol{R}^{n} ; z_{n}=0, z_{n-1}>0\left(\text { resp. } z_{n-1}<0\right)\right\} .
$$

Proposition 1.3. In order that the form (1.1) satisfying (1.2) and (1.3) be coercive over $V\left(S_{1}, S_{2}\right)$, it is necessary and sufficient that $\left\{\begin{array}{l}\text { for every } P \in \Gamma \text {, there exists a number } R>0 \text { such that the } \\ \text { form } Q_{1}^{P}[u, u] \text { defined by (1.7) is coercive over } V_{R}^{P} .\end{array}\right.$

Proof. Let $P$ be in $\Gamma_{\alpha}$ and $G$ be an open neighbourhood of $\Gamma$ such that $G \cap \Gamma=G \cap \Gamma_{\alpha}$ and assume that $G$ is contained in the definition domain of the transformation (1.6) with $g_{P}=0$. Then we get

$$
\begin{array}{r}
\tilde{V}_{G}=\left\{u \in H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N} ; \operatorname{supp}[u] \subset \chi_{P}(G \cap \bar{\Omega}),\left\langle\tilde{\boldsymbol{b}}_{j}\left(z^{\prime}\right), u\right\rangle=0\right. \\
\text { on } \left.z_{n}=0 \text { for } j \in S_{\alpha}\right\},
\end{array}
$$

where $\tilde{\boldsymbol{b}}_{j}\left(z^{\prime}\right)=\boldsymbol{b}_{j}\left(P+S_{P}^{-1}\left(z^{\prime}, 0\right)\right)$ and $z^{\prime}=\left(z_{1}^{\prime}, \cdots, z_{n-1}\right)$. If $P$ is in $\gamma$, we choose $\chi_{P}$ and $g_{P}$ so that $\chi_{P}(G \cap \gamma)$ is represented by $z_{n}=z_{n-1}=0$, and $\chi_{P}\left(G \cap \Gamma_{1}\right)\left(\right.$ resp. $\left.\chi_{P}\left(G \cap \Gamma_{2}\right)\right)$ by $z_{n-1}>0, z_{n}=0\left(\right.$ resp. $\left.z_{n-1}<0, z_{n}=0\right)$. Thus we have

$$
\begin{array}{r}
\bar{V}_{G}=\bigcap_{\alpha=1,2}\left\{u \in H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N} ; \operatorname{supp}[u] \subset \chi_{P}(G \cap \bar{\Omega}),\left\langle\boldsymbol{b}_{j}\left(z^{\prime}\right), u\right\rangle=0\right. \\
\text { on } \left.H_{\alpha} \text { for } j \in S_{\alpha}\right\}
\end{array}
$$

Now we shall prove the equivalence of (1.8) and (1.10) for $V$ $=V\left(S_{1}, S_{2}\right)$ which is defined by (1.9). Let $P$ be any point on $\Gamma$.
(i) (1.8) $\Rightarrow$ (1.10). Let $R$ be a positive number such that $\Sigma_{R} \subset$ $\chi_{P}(G \cap \bar{\Omega})$. We set

$$
\phi_{j}\left(z^{\prime}\right)=\left\langle\tilde{\boldsymbol{b}}_{j}\left(z^{\prime}\right)-\tilde{\boldsymbol{b}}_{j}(0), u\right\rangle \quad \text { on } z_{n}=0(j=1, \cdots, N)
$$

for $u$ in $V_{R}^{P}$. It then easily follows that there exists a $v \in H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N} \cap \mathscr{E}^{\prime}{ }_{R}$ such that

$$
\left\langle\tilde{\boldsymbol{b}_{j}}\left(z^{\prime}\right), v\right\rangle= \begin{cases}\phi_{j}\left(z^{\prime}\right) & \text { on } z_{n}=0, j \in S_{1} \cup S_{2} \\ 0 & \text { on } z_{n}=0, j \notin S_{1} \cup S_{2}\end{cases}
$$

and

$$
\begin{equation*}
\|v\|_{1} \leqq C \sum_{j \in S_{1} \cup S_{2}}\left\|\phi_{j}\right\|_{1 / 2}, \tag{1.11}
\end{equation*}
$$

$C$ being a positive constant not depending on $u, v$. Remembering that $\phi_{j}(0)=0$ for $j=1, \cdots, N$, we can establish that for any $\varepsilon>0$ there exists a number $R>0$ such that for every $j \in S_{1} \cup S_{2}$

$$
\begin{equation*}
\left\|\phi_{j}\right\|_{1 / 2} \leqq \varepsilon\|u\|_{1}, \quad u \in V_{R}^{P} \tag{1.12}
\end{equation*}
$$

Obviously $u-v$ is in $\tilde{V}_{G}$. Accordingly it follows from (1.8) that

$$
Q_{1}^{P}[u-v, u-v] \geqq c_{1}\|u-v\|_{1}^{2}-c_{0}\|u-v\|_{0}^{2}
$$

with some constants $c_{1}>0$ and $c_{0}$. So that

$$
\begin{aligned}
Q_{1}^{P}[u, u] & \geqq c_{1}\|u-v\|_{1}^{2}-c_{0}\|u-v\|_{0}^{2}-K_{1}\left(\|u\|_{1}\|v\|_{1}+\|v\|_{1}^{2}\right) \\
& \left.\geqq c_{1}\|u\|_{1}^{2}-c_{0}\|u\|_{0}^{2}-K_{2}\|u\|_{1}\|v\|_{1}+\|v\|_{1}^{2}\right) \\
& \geqq \frac{c_{1}}{2}\|u\|_{1}^{2}-c_{0}\|u\|_{0}^{2}-K_{3}\|v\|_{1}^{2},
\end{aligned}
$$

where $K_{1}, K_{2}, \cdots$ denote appropriate constants. Using (1.11) and (1.12), we can obtain

$$
Q_{1}^{P}[u, u] \geqq \frac{c_{1}}{4}\|u\|_{1}^{2}-c_{0}\|u\|_{0}^{2}
$$

for every $u \in V_{R}^{P}$ if $\varepsilon$ is sufficient small. That is, (1.10) holds for $R=R_{\varepsilon}$.
(ii) (1.10) $\Rightarrow$ (1.8). Let $G$ be a neighbourhood of $P$ such that $\chi_{P}(G \cap \bar{\Omega}) \subset \Sigma_{R}$. For $u \in \tilde{V}_{G}$, we can choose a $v$ in $H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N} \cap \mathscr{E}_{R}^{\prime}$ so that (1.11) and

$$
\left\langle\tilde{\boldsymbol{b}}_{j}(0), v\right\rangle= \begin{cases}-\phi_{j}\left(z^{\prime}\right) & \text { on } z_{n}=0, j \in S_{1} \cup S_{2} \\ 0 & \text { on } z_{n}=0, j \notin S_{1} \cup S_{2}\end{cases}
$$

are valid. Thus by the same argument as in (i), we can conclude (1.8) from (1.10).

## § 2. Coercive forms with constants coefficients in a half space

Let there be given the integro-differential bilinear form in the half space $\boldsymbol{R}_{+}^{n}=\left\{x \in \boldsymbol{R}^{n} ; x_{n}>0\right\}$ :

$$
\begin{equation*}
Q_{0}[u, v]=\int_{i>0} \sum_{i, j=1}^{n}\left\langle a_{i j} D_{i} u, D_{j} v\right\rangle d x, \tag{2.1}
\end{equation*}
$$

where $a_{i j}(i, j=1, \cdots, n)$ are $N$-square matrices with complex constant entries and satisfy (1.2) and (1.3), and $t=x_{n}, D_{j}=-i \partial / \partial x_{j}$. Integrating by parts, we obtain

$$
\begin{equation*}
Q_{0}[u, v]=\int_{t>0}\langle A(D) u, v\rangle d x+\int_{t=0}\langle N(D) u, v\rangle d x^{\prime}, \tag{2.2}
\end{equation*}
$$

where $x^{\prime}=\left(x_{1}, \cdots, x_{n-1}\right)$ and

$$
A(D) u=\sum_{i, j=1}^{n} a_{i j} D_{i} D_{j} u, \quad N(D) u=-i \sum_{j=1}^{n} a_{j n} D_{j} u
$$

For $\lambda$ real, we set

$$
Q_{\lambda}[u, v]=Q_{0}[u, v]+\lambda^{2}(u, v)
$$

with

$$
(u, v)=\int_{t\rangle 0}\langle u, v\rangle d x .
$$

Putting $A_{\lambda}(D)=A(D)+\lambda^{2} I$ ( $I$ denotes the identity $N$-matrix), we have by (2.2)

$$
\begin{equation*}
Q_{\lambda}[u, v]=\left(A_{\lambda} u, v\right)+\int_{t=0}\langle N(D) u, v\rangle d x^{\prime} . \tag{2.3}
\end{equation*}
$$

For $\lambda \neq 0$ and $\phi\left(x^{\prime}\right)$ in $\mathscr{S}^{N}\left(\mathscr{S}\right.$ is the $S$ chwartz space on $\boldsymbol{R}^{n-1}$ ), we denote by $u_{\lambda}(x)$ the unique solution of the Dirichlet problem

$$
\begin{cases}A_{\lambda}(D) u=0 & \text { in } t>0  \tag{2.4}\\ u=\phi & \text { on } t=0\end{cases}
$$

in $H_{2}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$. Substituting $u_{\lambda}$ for $u, v$ in (2.3), we have

$$
Q_{\lambda}\left[u_{\lambda}, u_{\lambda}\right]=\int_{t=0}\left\langle N(D) u_{\lambda}, u_{\lambda}\right\rangle d x^{\prime}
$$

By the Fourier transformation in the variable $x^{\prime}$ and Parseval's formula, we can obtain

$$
\begin{equation*}
Q_{\lambda}\left[u_{\lambda}, u_{\lambda}\right]=(2 \pi)^{1-n} \int_{t=0}\left\langle\left. N\left(\eta, D_{t}\right) \hat{u}_{\lambda}(\eta, t)\right|_{t=0}, \hat{u}_{\lambda}(\eta, 0)\right\rangle d \eta, \tag{2.5}
\end{equation*}
$$

where

$$
\hat{u}_{\lambda}(\eta, t)=\int e^{-i\left\langle\left\langle x^{\prime}, \eta\right\rangle\right.} u_{\lambda}\left(x^{\prime}, t\right) d x^{\prime}, \quad \eta \in \boldsymbol{R}^{n-1}
$$

is a solution of the initial value problem

$$
\begin{cases}A_{\lambda}\left(\eta, D_{t}\right) \hat{u}=0 & \text { in } t>0  \tag{2.6}\\ \hat{u}=\hat{\phi}(\eta) & \text { on } t=0\end{cases}
$$

and exponentially decays as $t \rightarrow \infty$.
For any $(\eta, \lambda) \neq 0$, let $u^{(h)}(\eta, \lambda, t)$ be the exponentially decaying solution of (2.6) with the initial condition $u^{(h)}(\eta, \lambda, 0)=e_{h}\left(e_{h}\right.$ is the $N$-vector
whose $h$-th component is 1 and others zero). Then we have
Proposition 2.1. (i) The $u^{(h)}(n, \lambda, t)(h=1, \cdots, N)$ are analytic in $(\eta, \lambda)$ and have the homogeneity property:

$$
\begin{equation*}
u^{(h)}\left(\theta^{-1} \eta, \theta^{-1} \lambda, \theta t\right)=u^{(h)}(\eta, \lambda, t), \quad \theta>0 \tag{2.7}
\end{equation*}
$$

(ii) The exponential decaying solution of (2.6) is given by

$$
\begin{equation*}
\hat{u}(\eta, \lambda, t)=\sum_{h=1}^{N} u^{(h)}(\eta, \lambda, t) \hat{\phi}_{h}(\eta) \tag{2.8}
\end{equation*}
$$

and the inequality

$$
\begin{equation*}
\int_{0}^{\infty} d t \int\left\{\left(\left.\eta\right|^{2}+\lambda^{2}\right)|\hat{u}|^{2}+\left|\frac{d \hat{u}}{d t}\right|^{2}\right\} d \eta \leqq C \int\left(|\eta|^{2}+\lambda^{2}\right)^{1 / 2}|\hat{\phi}|^{2} d \eta \tag{2.9}
\end{equation*}
$$

is satisfied with a suitable constant $C>0$ independent of $\lambda$.
(iii) The inverse Fourier transformation of $\hat{u}(\eta, \lambda, t)$ :

$$
u_{2}\left(x^{\prime}, t\right)=(2 \pi)^{1-n} \int e^{i\left\langle x^{\prime}, \eta\right\rangle} \hat{u}(\eta, \lambda, t) d \eta
$$

is the solution of (2.4) in $H_{2}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$ if $\lambda \neq 0$.
Proof. By the theory of ordinary differential equations, (i) is immediately obtained. Differentiating (2.7), we obtain

$$
\theta^{j}\left(d_{t}^{j} u\right)\left(\theta^{-1} \eta, \theta^{-1} \lambda, \theta t\right)=d_{t}^{j} u(\eta, \lambda, t), \quad \theta>0,
$$

where $d_{t}=d / d t$. For brevity, we put $\theta=\theta(\eta, \lambda)=\left(|\eta|^{2}+\lambda^{1}\right)^{1 / 2}$. It then follows from (2.8) that, for $j=0,1$,

$$
\begin{aligned}
\int_{0}^{\infty} d t \int \theta^{2(1-j)}\left|d_{t} \hat{u}\right|^{2} d \eta & \leqq N \int_{0}^{\infty} d t \int \theta^{2(1-j)} \sum_{n=1}^{N}\left|d_{i}^{j} u^{(h)}(\eta, \lambda, t) \hat{\phi}_{h}(\eta)\right|^{2} d \eta \\
& \leqq N \int_{0}^{\infty} d s \int \theta \sum_{h=1}^{N}\left|d_{t}^{j} u^{(h)}\left(\theta^{-1} \eta, \theta^{-1} \lambda, s\right)\right|^{2}\left|\hat{\phi}_{h}(\eta)\right|^{2} d \eta \\
& \leqq N \sup _{\theta=1} \int\left|d_{s}^{j} u^{(h)}(\eta, \lambda, s)\right|^{2} d s \int \theta\left|\hat{\phi}_{h}(\eta)\right|^{2} d \eta
\end{aligned}
$$

This completes (2.9). By the same way, we can obtain, for $j=0,1,2$,

$$
\int_{0}^{\infty} d t \int \theta^{2(2-j)}\left|d_{t}^{j} \hat{u}\right|^{2} d \eta \leqq C \int \theta^{3}|\hat{\phi}(\eta)|^{2} d \eta
$$

which guarantees that $u_{2}\left(x^{\prime}, t\right)$ is in $H_{2}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$.
Q.E.D.

Now we return (2.5). Since $\hat{u}_{\lambda}(\eta, t)=\hat{u}(\eta, \lambda, t)$, we have

$$
\begin{equation*}
\left.N\left(\eta, D_{t}\right) \hat{u}_{\lambda}(\eta, t)\right|_{t=0}=B(\eta, \lambda) \hat{\phi}(\eta), \tag{2.10}
\end{equation*}
$$

provided that $B(\eta, \lambda)$ is the $N$-square matrix whose $(j, h)$-entry $b_{j h}(\eta, \lambda)$ is equal to the $j$-component of the $N$-vector $\left.N\left(\eta, D_{t}\right) \iota^{(h)}(\eta, \lambda, t)\right|_{t=0}$. Consequently, (2.5) becomes

$$
\begin{equation*}
Q_{\lambda}\left[u_{\lambda}, u_{\lambda}\right]=(2 \pi)^{1-n} \int\langle B(\eta, \lambda) \hat{\phi}(\eta), \hat{\phi}(\eta)\rangle d \eta \tag{2.11}
\end{equation*}
$$

Here note that each entry $b_{j n}(\eta, \lambda)$ is analytic for $(\eta, \lambda) \neq 0$ and homogeneous of degree 1. In fact, this follows immediately from (2.7).

Let $V_{0}$ be a closed subspace of $H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$ and assume that for every $\varepsilon>0$

$$
\begin{equation*}
u(x) \in V_{0} \Rightarrow u^{(\varepsilon)}(x)=u(x / \varepsilon) \in V_{0} . \tag{2.12}
\end{equation*}
$$

Then we can prove
Proposition 2.2. If the quadratic form $Q_{0}[u, u]$ of the form (2.1) is coercive over $V_{0}$ satisfying (2.12), then there exists a constant $c>0$ independent of $\lambda$ such that for every $\lambda$

$$
\begin{equation*}
\int\langle B(\eta, \lambda) U(\eta), U(\eta)\rangle d \eta \geqq c \int|\eta|\langle U(\eta), U(\eta)\rangle d \eta, U \in \sigma\left(\hat{V}_{0}\right), \tag{2.13}
\end{equation*}
$$

where

$$
\sigma\left(\hat{V}_{0}\right)=\left\{U(\eta)=\left.\int e^{-i\left\langle x^{\prime}, r\right\rangle} u\left(x^{\prime}, t\right) d x^{\prime}\right|_{t=0}, u \in V_{0}\right\} .
$$

Proof. Let $\lambda \neq 0$ and let $u_{\lambda}$ be the solution of the Dirichlet problem (2.4) with $\phi \in H_{1 / 2}\left(\boldsymbol{R}^{n-1}\right)$ such that $\hat{\phi} \in \sigma\left(\hat{V}_{0}\right)$. Then we have $u_{2} \in V_{0}$ and note that, for the $u_{\lambda}$, (2.11) is also valid. Then, the coerciveness of $Q_{0}$ and (2.11) guarantee that

$$
\begin{equation*}
\int\langle B(\eta, \lambda) U(\eta), U(\eta)\rangle d \eta \geqq c_{1} \int\left(1+|\eta||U(\eta)|^{2} d \eta-c_{0}\left\|u_{\lambda}\right\|_{0}^{2},\right. \tag{2.14}
\end{equation*}
$$

where $c_{1}>0$ and $c_{0}$ are constants independent of $\lambda$, and we put $\hat{\phi}=U$ and used the well-known inequality

$$
\int(1+|\eta|)|U(\eta)|^{2} d \eta \leqq \text { const. }\left\|u_{\lambda}\right\|_{1}^{2}
$$

By (2.12), we have $u_{i}^{(c)} \in V_{0}(\varepsilon>0)$ and

$$
\left\{\begin{array}{l}
A(D) u_{\lambda}^{(t)}(x)=-\left(\frac{\lambda}{\varepsilon}\right)^{2} u_{\lambda}^{(\varepsilon)}(x) \\
u_{\lambda}^{(e)}\left(x^{\prime}, 0\right)=\phi\left(\frac{x^{\prime}}{\varepsilon}\right)
\end{array}\right.
$$

Noting

$$
\widehat{\phi\left(\frac{x^{\prime}}{\varepsilon}\right)}=\varepsilon^{n-1} U(\varepsilon \eta)
$$

and applying (2.14) for $u_{\lambda}^{(e)}$, we can immediately obtain

$$
\varepsilon^{2 n-2} \int\left\langle B\left(\eta, \frac{\lambda}{\varepsilon}\right) U(\varepsilon \eta), U(\varepsilon \eta)\right\rangle d \eta \geqq \varepsilon^{2 n-2} c_{1} \int\left(1+|\eta||U(\varepsilon \eta)|^{2} d \eta-c_{0}\left\|u_{\lambda}^{(e)}\right\|_{0}^{2}\right.
$$

Devising the both side by $\varepsilon^{n-2}$ and tending $\varepsilon$ to zero, we can conclude (2.13) for $\lambda \neq 0$ and hence also for $\lambda=0$.
Q.E.D.

Proposition 2.3. In Proposition 2.2, if (2.13) is valid for $\lambda=0$, then $Q_{0}[u, u]$ is coercive over $V_{0}$.

Proof. Let $u \in V_{0}$. We can choose a sequence $u_{c}, \varepsilon>0$, in $C_{0}^{\infty}\left(\overline{\boldsymbol{R}}_{+}^{n}\right)^{N}$ such that $u_{\varepsilon} \rightarrow u$ in $H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$ as $\varepsilon \rightarrow 0$. Let $w_{\lambda}$ be in $H_{2}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$ and be a solution of (2.4) with $\phi=\left.u_{s}\right|_{t=0}$ and with $\lambda \neq 0$, and set $v_{s}=u_{s}-w_{\lambda}$.

By (2.9) in Proposition 2.1, we have

$$
\int_{0}^{\infty} d t \int\left\{\left(\left.\eta\right|^{2}+\lambda^{2}\right)\left|\hat{w}_{\lambda}\right|^{2}+\left|\frac{d \hat{w}_{2}}{d t}\right|^{2}\right\} d \eta \leqq C \int\left(|\eta|^{2}+\lambda^{2}\right)^{1 / 2}\left|U_{c}(\eta)\right|^{2} d \eta,
$$

where $U_{\epsilon}(\eta)=\left.\hat{u}_{\epsilon}\right|_{t=0}$ and $C$ is a constant $>0$ independent of $\lambda$ and $\varepsilon$. Writing here the left hand side as $\left|w_{\lambda}\right|_{1, \lambda}^{2}$, we have

$$
\begin{equation*}
\left|v_{c}\right|_{1, \lambda}^{2} \geqq \frac{1}{2}\left|u_{\epsilon}\right|_{1, \lambda}^{2}-C \int\left(|\eta|^{2}+\lambda^{2}\right)^{1 / 2}\left|U_{\theta}(\eta)\right|^{2} d \eta \tag{2.15}
\end{equation*}
$$

Substituting $w_{\lambda}$ in place of $u_{\lambda}$ in (2.11), we obtain

$$
\begin{equation*}
Q_{\lambda}\left[u_{t}-v_{t}, u_{t}-v_{t}\right]=(2 \pi)^{1-n} \int\left\langle B(\eta, \lambda) U_{t}(\eta), U_{t}(\eta)\right\rangle d \eta . \tag{2.16}
\end{equation*}
$$

Since $v_{\epsilon}=0$ on $t=0$ and $A_{2} u_{\epsilon}=A_{i} v_{\epsilon}$ in $t>0$, we can calculate as follows:

$$
\begin{aligned}
Q_{\lambda}\left[u_{c}-v_{c}, u_{s}-v_{c}\right] & =Q_{\lambda}\left[u_{c}, u_{c}\right]+Q_{\lambda}\left[v_{c}, v_{c}\right]-2 \operatorname{Re}\left(A_{\lambda} u_{c}, v_{c}\right) \\
& =Q_{\lambda}\left[u_{c}, u_{s}\right]+Q_{\lambda}\left[v_{s}, v_{s}\right]-2 \operatorname{Re}\left(A_{\lambda} v_{c}, v_{s}\right)
\end{aligned}
$$

$$
=Q_{\lambda}\left[u_{t}, u_{\varepsilon}\right]-Q_{\lambda}\left[v_{c}, v_{s}\right]
$$

Therefore, it follows from (2.15), (2.16) and the ellipticity condition (1.3) that for any $\delta, 0<\delta \leqq 1$,

$$
\begin{aligned}
Q_{\lambda}\left[u_{t}, u_{s}\right] \geqq & \delta Q_{\lambda}\left[v_{s}, v_{\epsilon}\right]+Q_{\lambda}\left[u_{\epsilon}-v_{\epsilon}, u_{s}-v_{c}\right] \\
\geqq & \left.\delta C_{1} \int_{0}^{\infty} d t \int\left\{|\eta|^{2}+\lambda^{2}\right)\left|\hat{u}_{s}\right|^{2}+\left|\frac{d u_{s}}{d t}\right|^{2}\right\} d \eta \\
& -\delta C_{2} \int\left(|\eta|^{2}+\lambda^{2}\right)^{1 / 2}\left|U_{t}(\eta)\right|^{2} d \eta \\
& +(2 \pi)^{1-n} \int\left\langle B(\eta, \lambda) U_{t}(\eta), U_{s}(\eta)\right\rangle d \eta
\end{aligned}
$$

where $C_{1}$ and $C_{2}$ are constants $>0$ independent of $\varepsilon$ and $\lambda$. Tending $\varepsilon \rightarrow 0$ and using (2.13) with $\lambda=0$, we obtain

$$
Q_{0}[u, u] \geqq \delta C_{1} \int_{0}^{\infty} d t \int\left(|\eta|^{2}|\hat{u}|^{2}+\left|\frac{d \hat{u}}{d t}\right|^{2}\right) d \eta+\left((2 \pi)^{1-n} c-\delta C_{2}\right) \int|\eta \| U(\eta)|^{2} d \eta
$$

If we choose $\delta$ so that $(2 \pi)^{1-n} c-\delta C_{2} \geqq 0$, then we can conclude that $Q_{0}[u, u]$ is coercive over $V_{0}$.
Q.E.D.

Thus, combining Propositions 2.2 and 2.3, we have
THEOREM 1. An integro-differential quadratic form $Q_{0}[u, u]$ of the form (2.1) with properties (1.2) and (1.3) is coercive over a closed subspace $V_{0}$ of $H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N}$ satisfying (2.12), if and only if

$$
\left\{\begin{array}{l}
\text { there exists a constant } c>0 \text { such that }  \tag{2.17}\\
\quad \int\langle B(\eta) U(\eta), U(\eta)\rangle d \eta \geqq c \int|\eta|\langle U(\eta), U(\eta)\rangle d \eta, \quad U \in \hat{V}_{0} \\
\text { where } B(\eta)=B(\eta, 0) \text { and } B(\eta, \lambda) \text { is the } N \text {-square matrix defined } \\
\text { by (2.10). }
\end{array}\right.
$$

## §3. Algebraic characterization

Let $\boldsymbol{b}_{j}, j=1, \cdots, N$, be $N$-vectors with complex components (i.e., $\boldsymbol{b}_{j} \in \boldsymbol{C}^{N}$ ) which are linearly independent, and let $S_{+}, S_{-}$be two subsets of the set $\{1, \cdots, N\}$. In this section we shall consider the problem of coerciveness for the quadratic form (2.1) over

$$
V_{0}\left(S_{+}, S_{-}\right)=\left\{u \in H_{1}\left(\boldsymbol{R}_{+}^{n}\right)^{N} ;\left\langle\boldsymbol{b}_{j}, u\right\rangle=0 \text { on } \Gamma_{ \pm} \text {for } j \in S_{ \pm}\right\},
$$

which clearly satisfies (2.12) and where

$$
\Gamma_{ \pm}=\left\{\left(x_{1}, \cdots, x_{n-1}, 0\right) \in \boldsymbol{R}^{n} ; x_{n-1} \gtrless 0\right\} .
$$

Here and in the following, the signs $\pm$ and $\gtrless$ are taken in the same order. For a subset $S$ of the set $\{1, \cdots, N\}$, we introduce the subspace $L(S)$ of $C^{N}$ as follows:

$$
L(S)=\left\{a \in \boldsymbol{C}^{N} ;\left\langle\boldsymbol{b}_{j}, a\right\rangle=0 \text { for } j \in S\right\}
$$

THEOREM 2. An integro-differential quadratic form $Q_{0}[u, u]$ of the form (2.1) with properties (1.2) and (1.3) is coercive over $V_{0}\left(S_{+}, S_{-}\right)$if and only if
$\left\{\begin{array}{l}\text { there exists a constant } c>0 \text { such that for every } \eta \in \boldsymbol{R}^{n-1}, \eta \neq 0, \\ \langle B(\eta) a, a\rangle \geqq c|\eta|\langle a, a\rangle, \quad a \in L\left(S_{+}\right) \cup L\left(S_{-}\right) \\ \text {holds, where } B(\eta) \text { is the same matrix as in Theorem } 1 .\end{array}\right.$
Proof. For the proof we have only to establish the equivalence of (3.1) and (2.17) with $V_{0}=V_{0}\left(S_{+}, S_{-}\right)$.

For $u \in V_{0}\left(S_{+}, S_{-}\right)$, we set $w_{j}\left(x^{\prime}\right)=\left.\left\langle\boldsymbol{b}_{j}, u\right\rangle\right|_{t=0}$ for $j=1, \cdots, N$. Clearly we have $w_{j} \in H_{1 / 2}\left(\boldsymbol{R}^{n-1}\right)$ and, in particular, $w_{j} \in H_{1 / 2}^{\mp}\left(\boldsymbol{R}^{n-1}\right)$ for $j \in S_{ \pm}$, where

$$
H_{s}^{ \pm}\left(\boldsymbol{R}^{n-1}\right)=\left\{\phi \in H_{s}\left(\boldsymbol{R}^{n-1}\right) ; \phi=0 \Gamma_{\mp}\right\} .
$$

Conversely, for any $w_{j} \in H_{1 / 2}\left(\boldsymbol{R}^{n-1}\right)(j=1, \cdots, N)$ such that $w_{j} \in H_{1 / 2}^{\mp}\left(\boldsymbol{R}^{n-1}\right)$ for $j \in S_{ \pm}$, we can find a $u$ in $V_{0}\left(S_{+}, S_{-}\right)$satisfying $w_{j}\left(x^{\prime}\right)=\left.\left\langle\boldsymbol{b}_{j}, u\right\rangle\right|_{t=0}$ for $j=1, \cdots, N$. Then we denote by $E$ a non-singular $N$-square matrix with constant entries such that $u\left(x^{\prime}, 0\right)=E w\left(x^{\prime}\right)$, where $w\left(x^{\prime}\right)$ $=\left(w_{1}\left(x^{\prime}\right), \cdots, w_{N}\left(x^{\prime}\right)\right)$.

Set

$$
\hat{H}_{s}\left(\boldsymbol{R}^{n-1}\right)\left(\operatorname{resp} . \hat{H}_{s}^{ \pm}\left(\boldsymbol{R}^{n-1}\right)\right)=\left\{\hat{\phi} ; \phi \in H_{s}\left(\boldsymbol{R}^{n-1}\right)\left(\text { resp. } \phi \in H_{s}^{ \pm}\left(\boldsymbol{R}^{n-1}\right)\right\}\right.
$$

and

$$
\mathscr{W}=\left\{W=\left(\hat{w}_{1}, \cdots, \hat{w}_{N}\right) \in \hat{H}_{1 / 2}\left(\boldsymbol{R}^{n-1}\right)^{N} ; w_{j} \in H_{1 / 2}^{\mp}\left(\boldsymbol{R}^{n-1}\right) \quad \text { for } j \in S_{ \pm}\right\}
$$

Then (2.17) may be rewritten by

$$
\begin{equation*}
\int\left\langle E^{*} \mathscr{B}(\eta) E W(\eta), W(\eta)\right\rangle d \eta \geqq 0, \quad W \in \mathscr{H}, \tag{3.2}
\end{equation*}
$$

where $\mathscr{B}(\eta)=B(\eta)-c|\eta| I$ and $E^{*}$ is the adjoint matrix of $E$. If we
set

$$
\Psi=\left\{\psi=\left(\psi_{1}, \cdots, \psi_{N}\right) \in \hat{H}_{0}\left(\boldsymbol{R}^{n-1}\right)^{N} ; \psi_{j} \in \hat{H}_{0}^{\mp}\left(\boldsymbol{R}^{n-1}\right) \text { for } j \in S_{ \pm}\right\}
$$

and, for $\varepsilon \geqq 0$,

$$
\rho_{j}^{(e)}(\eta)= \begin{cases}\left(\eta_{ \pm} \pm i \varepsilon\right)^{-1 / 2}, & j \in S_{ \pm}-\left(S_{+} \cap S_{-}\right), \\ (\varepsilon+|\eta|)^{-1 / 2}, & j \notin S_{+} \cup S_{-} \text {or } j \in S_{+} \cap S_{-} .\end{cases}
$$

it then follows from the theorem of the Hilbert transformation that for any $\psi \in \Psi$ and any $\varepsilon>0$

$$
\left(\rho_{1}^{(s)}(\eta) \psi_{1}(\eta), \cdots, \rho_{N}^{(e)}(\eta) \psi_{N}(\eta)\right) \in \mathscr{W} .
$$

Substituting this in (3.2) and letting $\varepsilon \rightarrow 0$, we obtain

$$
\begin{equation*}
\int\left\langle\mathscr{B}_{0}(\eta) \psi(\eta), \psi(\eta)\right\rangle d \eta \geqq 0, \quad \psi \in \Psi, \tag{3.3}
\end{equation*}
$$

where $\mathscr{B}_{0}(\eta)$ is the matrix defined by

$$
\mathscr{B}_{0}(\eta)=P(\eta) * E * \mathscr{B}(\eta) E P(\eta),
$$

with

$$
P(\eta)=\left[\rho_{j}(\eta) \delta_{j k}\right]_{j, k=1}^{N}\left(\rho_{j}(\eta)=\rho_{j}^{(0)}(\eta)\right)
$$

Note that every entry of $\mathscr{B}_{0}(\eta)$ is homogeneous of degree zero in $\eta$. Thus we can assert that (3.2) implies (3.3). Conversely (3.3) implies (3.2), for if $W \in \mathscr{W}$ then we have

$$
\left(\rho_{1}(\eta)^{-1} W_{1}(\eta), \cdots, \rho_{N}(\eta)^{-1} W_{N}(\eta)\right) \in \Psi
$$

Now it remains to prove the equivalence of (3.1) and (3.3). But this can be really done by the same argument as in [4, pp. 131-133].
Q.E.D.

Set, for $F(t) \in H_{1}\left(\boldsymbol{R}_{+}\right)^{N}$,

$$
\begin{align*}
Q_{n}[F, F]=\int_{0}^{\infty} & \left\{\left\langle a_{n n} D_{t} F, D_{t} F\right\rangle+\sum_{i=1}^{n-1}\left\langle a_{i n} \eta_{i} F, D_{t} F\right\rangle\right.  \tag{3.4}\\
& \left.+\sum_{i=1}^{n-1}\left\langle a_{n i} D_{t} F, \eta_{i} F\right\rangle+\sum_{i, j=1}^{n-1}\left\langle a_{i j} \eta_{i} \eta_{j} F, F\right\rangle\right\} d t
\end{align*}
$$

Then we have
Corollary 1. The form $Q_{0}$ is coercive over $V_{0}\left(S_{+}, S_{-}\right)$if and only if the following is satisfied for every $\eta \in \boldsymbol{R}^{n-1}, \eta \neq 0$ : Any function $F_{+}(t)$
(resp. $\left.\boldsymbol{F}_{-}(s)\right) \in H_{1}\left(\boldsymbol{R}_{+}\right)$satisfying

$$
\begin{cases}A\left(\eta, D_{t}\right) F(t)=0 & \text { in } t>0  \tag{3.5}\\ \left\langle\boldsymbol{b}_{j}, F(t)\right\rangle=0 & \text { on } t=0, j \in S_{+}\left(\text {resp. } S_{-}\right)\end{cases}
$$

vanishes in $t>0$ if

$$
\begin{equation*}
Q_{\eta}\left[F_{ \pm}, F_{ \pm}\right] \leqq 0 . \tag{3.6}
\end{equation*}
$$

Proof. Let $F_{ \pm}(t) \in H_{1}\left(\boldsymbol{R}_{+}\right)$and assume (3.5) and (3.6). Integrating by parts we find by (3.4)

$$
Q_{\eta}\left[F_{ \pm}, F_{ \pm}\right]=\left\langle N\left(\eta, D_{t}\right) F_{ \pm}(t), F_{ \pm}(t)\right\rangle_{t=0} .
$$

Now suppose (3.1) to be valid. By setting $a^{ \pm}=F^{ \pm}(0)$, it then follows that

$$
(2 \pi)^{n-1} Q_{\eta}\left[F_{ \pm}, F_{ \pm}\right]=\left\langle B(\eta) a^{ \pm}, a^{ \pm}\right\rangle \geqq c|\eta|\left\langle a^{ \pm}, a^{ \pm}\right\rangle,
$$

since $a^{ \pm} \in L\left(S_{ \pm}\right)$. Here, the signs + , - are taken in the same order. Accordingly we have $a^{ \pm}=0$ by (3.6). Hence $F_{ \pm}(t)=0$ for $t>0$.

Conversely, we suppose that (3.1) is not valid. Then, we can assume without loss of generality that there exist $\eta_{0} \in R^{n-1},\left|\eta_{0}\right|=1$, and $a^{(0)} \in L\left(S_{+}\right)$such that $\left|a^{0}\right|=1$ and

$$
\begin{equation*}
\left\langle B\left(\eta_{0}\right) a^{(0)}, a^{(0)}\right\rangle \leqq 0 \tag{3.7}
\end{equation*}
$$

Let $F(t)$ be in $H_{1}\left(\boldsymbol{R}_{+}\right)^{N}$ and satisfy

$$
\begin{cases}A\left(\eta_{0}, D_{t}\right) F=0 & \text { in } t>0, \\ F(0)=a^{(0)} & \text { on } t=0 .\end{cases}
$$

It then follows from (3.7) that $Q_{\eta_{0}}[F, F] \leqq 0$. But it is easily seen that $F(t)$ does not vanish identically.
Q.E.D.

Before ending this section, we shall state another corollary which will be used in the proof of the main theorem (Theorem 3 in §4).

Corollary 2. The form $Q_{0}$ is coercive over $V_{0}\left(S_{+}, S_{-}\right)$if it is coercive over $V_{0}\left(S_{+}, S_{-}\right) \cap \mathscr{E}_{R}^{\prime}$ for some positive number $R$.

Proof. Suppose that $Q_{0}$ is coercive over $V_{0}\left(S_{+}, S_{-}\right) \cap \mathscr{E}_{R}^{\prime \prime}$ for a positive number $R$. Then we would like to prove that $Q_{0}$ is coercive over $V_{0}\left(S_{+}, S_{-}\right)$. We assume for the moment that $Q_{0}$ is not coercive over $V_{0}\left(S_{+}, S_{-}\right)$. Using Corollary 1, we can assume without loss of generality
that there exists a $\eta_{0} \in R^{n-1}, \eta_{0} \neq 0$ and a function $F_{+}(t)$ which fulfils (3.5) and (3.6) for $\eta=\eta_{0}$ but does not identically vanish in $t>0$.

For $\mu>0$, we put

$$
u_{\mu}\left(x^{\prime}, t\right)=e^{i\left\langle x^{\prime}, \mu \eta_{0}\right\rangle} F_{+}(\mu t)
$$

Let $\zeta(x) \in C_{0}^{\infty}\left(\Sigma_{R}\right)$ and further assume that $\zeta(x)$ is written in the form $\zeta_{1}(t) \zeta_{2}\left(x^{\prime}\right)$ where $\zeta_{1}(t)=1$ in a neighbourhood of $t=0$ and $\zeta_{2}\left(x^{\prime}\right)=0$ in $x_{n-1}<0$. Then we have $\zeta(x) u_{\mu}\left(x^{\prime}, t\right) \in V_{0}\left(S_{+}, S_{-}\right) \cap \mathscr{E}_{R}^{\prime}$. Accordingly

$$
\begin{equation*}
Q_{0}\left[\zeta u_{\mu}, \zeta u_{\mu}\right] \geqq c_{1}\left\|\zeta u_{\mu}\right\|_{1}^{2}-c_{0}\left\|\zeta u_{\mu}\right\|_{0}^{2} \tag{3.8}
\end{equation*}
$$

holds for all $\mu>0$. But we can immediately show that $Q_{0}\left[\zeta u_{\mu}, \zeta u_{\mu}\right]$ and $\left\|\zeta u_{\mu}\right\|_{0}^{2}$ are bounded when $\mu \rightarrow \infty$ but $\left\|\zeta u_{\mu}\right\|_{1}^{2}$ tends to infinity as $\mu \rightarrow \infty$. This contradicts (3.8). Thus we can assert that $Q_{0}$ is coercive over $V_{0}\left(S_{+}, S_{-}\right)$.

## §4. Main theorem

Now we can state the main theorem. Let $Q[u, u]$ be a quadratic form of the form (1.1) satisfying (1.2) and (1.3). If $u \in H_{2}(\Omega)^{N}$ and $v \in H_{1}(\Omega)^{N}$, integrating by parts we find

$$
\begin{equation*}
Q[u, v]=\int_{\Omega}\langle A(x, D) u, v\rangle d x+\int_{\Gamma}\langle N(x, D) u, v\rangle d \sigma \tag{4.1}
\end{equation*}
$$

where $d \sigma$ denotes the Lebesgue measure on $\Gamma$ and

$$
\begin{gathered}
A(x, D) u=\sum_{i, j=1}^{n} D_{j}\left(a_{i j}(x) D_{i} u\right), \quad x \in \Omega, \\
N(x, D) u=-i \sum_{i, j=1}^{n} \nu_{j}(x) \alpha_{i j}(x) D_{i} u, \quad x \in \Gamma,
\end{gathered}
$$

$\nu(x)=\left(\nu_{1}(x), \cdots, \nu_{n}(x)\right)$ being the unit inner normal vector to $\Gamma$ at $x \in \Gamma$.
Let $P$ be arbitrarily fixed on $\Gamma$. We denote by $T_{P}$ the totality of real vectors $\dot{\xi} \neq 0$ parallel to $\Gamma$ at $P$. Let $\dot{\xi} \in T_{P}$. For any $\phi \in \mathscr{S}\left(\boldsymbol{R}^{n-1}\right)$, we denote by $u_{\dot{\phi}}(\dot{\xi}, t)$ an exponentially decaying solution of the Dirichlet problem

$$
\begin{cases}A^{0}\left(P, \dot{\xi}+\nu D_{t}\right) u=0 & \text { in } t>0 \\ u=\hat{\phi}(\dot{\xi}) & \text { on } t=0\end{cases}
$$

where $\nu=\nu(P)$ and $A^{0}$ is the leading part of $A$. Following the same process as in (2.10), we can define the $N$-square matrix $B(P, \dot{\xi})$ such that

$$
\begin{equation*}
\left.N\left(P, \dot{\xi}+\nu D_{t}\right) u_{\phi}(\dot{\xi}, t)\right|_{t=0}=B(P, \dot{\xi}) \hat{\phi}(\dot{\xi}) . \tag{4.2}
\end{equation*}
$$

Let $V\left(S_{1}, S_{2}\right)$ be the closed subspace of $H_{1}(\Omega)^{N}$ which is defined by (1.9). For a subset $S$ of the set $\{1, \cdots, N\}$, we introduce a subspace of $C^{N}$ as follows:

$$
L^{P}(S)=\left\{a \in \boldsymbol{C}^{N} ;\left\langle\boldsymbol{b}_{j}(P), a\right\rangle=0 \text { for } j \in S\right\} .
$$

Then we can obtain
ThEOREM 3. Let $Q[u, u]$ be an integro-differential quadratic form of the form (1.1) which satisfies (1.2) and (1.3), and whose coefficients $a_{i j}(x), i, j=1, \cdots, n$, are $N$-square matrices with entries in $C^{\infty}(\bar{\Omega})$. Let $\boldsymbol{b}_{j}(x), j=1, \cdots, N$, be the given $N$-vectors with components in $C^{\infty}(\Gamma)$ which are linearly independent at each $x \in \Gamma$. By $V\left(S_{1}, S_{2}\right)$ we denote the closed subspace of $H_{1}(\Omega)^{N}$ which is defined by (1.9). Then, in order that the $Q[u, u]$ be coercive over $V\left(S_{1}, S_{2}\right)$, it is necessary and sufficient that

$$
\left(\begin{array}{l}
\text { for every } P \text { on } \bar{\Gamma}_{\alpha}(\alpha=1,2) \text {, there exists a constant } c>0 \text { such } \\
\text { that the inequality }
\end{array}\right.
$$

$$
\begin{align*}
& \langle B(P, \dot{\xi}) a, a\rangle \geqq c|\dot{\xi}|\langle a, a\rangle, \quad a \in L^{P}\left(S_{\alpha}\right)  \tag{4.3}\\
& r y \dot{\xi} \in T_{P}, B(P, \dot{\xi}) \text { being defined by (4.2). }
\end{align*}
$$

Proof. The proof easily follows from Proposition 1.3, Theorem 2 and its Corollary 2, where we should note that

$$
V_{R}^{P}= \begin{cases}V_{0}\left(S_{\alpha}, S_{\alpha}\right) \cap \mathscr{E}_{R}^{\prime} \text { with } \boldsymbol{b}_{j}=\boldsymbol{b}_{j}(P), & \text { if } P \in \Gamma_{\alpha} \\ V_{0}\left(S_{1}, S_{2}\right) \cap \mathscr{E}_{R}^{\prime} \text { with } \boldsymbol{b}_{j}=\boldsymbol{b}_{j}(P), & \text { if } P \in \gamma=\bar{\Gamma}_{1} \cap \bar{\Gamma}_{2}\end{cases}
$$

Q.E.D.

Corresponding to Corollary 1 of Theorem 2, we can replace (4.3) with

$$
\text { for every } P \text { on } \bar{\Gamma}_{\alpha}(\alpha=1,2) \text { and every } \dot{\xi} \in T_{P} \text {, any function } F(t)
$$ $\in H_{1}\left(\boldsymbol{R}_{+}\right)$satisfying

$$
\begin{cases}A^{0}\left(P, \dot{\xi}+\nu(P) D_{t}\right) F(t)=0 & \text { in } t>0,  \tag{4.4}\\ \left\langle\boldsymbol{b}_{j}(P), F(t)\right\rangle=0 \text { on } t=0 & \text { for } j \in S_{\alpha}\end{cases}
$$

vanishes in $t>0$ if

$$
\left\langle\quad Q_{\xi}^{P}[F, F]=\int_{0}^{\infty}\left\langle\sum_{i, j=1}^{n} a_{i j}(P)\left(\dot{\xi}_{i}+\nu_{i} D_{t}\right) F,\left(\dot{\xi}_{j}+\nu_{j} D_{t}\right) F\right\rangle d t \leqq 0 .\right.
$$

## §5. Formally positive quadratic forms and Korn's inequality

Let $\Omega, \Gamma, \Gamma_{\alpha}, S_{\alpha}(\alpha=1,2)$ and $V\left(S_{1}, S_{2}\right)$ be the same as in Section 1 and let $A_{j}(x), j=1, \cdots, n$, be $M \times N$-matrices ( $M \geqq N$ ) with entries in $C^{\infty}(\bar{\Omega})$. For $u=\left(u_{1}(x), \cdots, u_{N}(x)\right)$, we write as

$$
\begin{equation*}
L(x, D) u=\sum_{j=1}^{n} A_{j}(x) D_{j} u \tag{5.1}
\end{equation*}
$$

and introduce a formally positive quadratic form

$$
\begin{equation*}
Q[u, u]=\int_{\Omega}\langle L(x, D) u, L(x, D) u\rangle d x \tag{5.2}
\end{equation*}
$$

which is nothing but the form (1.1) with $a_{i j}(x)=A_{j}(x) * A_{i}(x)$. The condition (1.3) leads to

$$
\begin{equation*}
\operatorname{rank} L(x, \xi)=N \tag{5.3}
\end{equation*}
$$

for every $x \in \bar{\Omega}$ and every $\xi \in \boldsymbol{R}^{n}, \xi \neq 0$. On the other hand, it is obvious that the condition (1.2) is automatically satisfied. Then we shall study the coerciveness of the form (5.2) over $V\left(S_{1}, S_{2}\right)$. To this purpose, we are going to characterize (4.4), where $A^{0}$ and $Q_{\xi}^{P}$ are given by

$$
\left\{\begin{array}{l}
A^{0}\left(P, \dot{\xi}+\nu D_{t}\right)=L\left(P, \dot{\xi}+\nu D_{t}\right)^{*} L\left(P, \dot{\xi}+\nu D_{t}\right),  \tag{5.4}\\
Q_{\dot{\xi}}^{P}[F, F]=\int_{0}^{\infty}\left\langle L\left(P, \dot{\xi}+\nu D_{t}\right) F, L\left(P, \dot{\xi}+\nu D_{t}\right) F\right\rangle d t
\end{array}\right.
$$

with $\nu=\nu(P)$ and

$$
L(x, D)^{*} u=\sum_{j=1}^{n} D_{j}\left(A_{j}(x)^{*} u\right) .
$$

That is, we would like to get the algebraic conditions under which any function $F(t) \in H_{1}\left(\boldsymbol{R}_{+}\right)$satisfying, for any $P \in \bar{\Gamma}_{\alpha}(\alpha=1,2)$ and any $\dot{\xi} \in T_{P}$,

$$
\begin{cases}L\left(P, \dot{\xi}+\nu D_{t}\right) F(t)=0 & \text { in } t>0  \tag{5.5}\\ \left\langle\boldsymbol{b}_{j}(P), F(t)\right\rangle=0 & \text { on } t=0, \text { for } j \in S_{\alpha}\end{cases}
$$

identically vanishes in $t>0$.
Let $P$ be fixed in $\bar{\Gamma}_{\alpha}(\alpha=1,2)$ and let $\dot{\xi}$ be fixed in $T_{P}$. Since we have

$$
L\left(P, \dot{\xi}+\nu D_{t}\right)=L(P, \nu) D_{t}+L(P, \dot{\xi})
$$

and rank $L(P, \nu)=N$ by (5.3), it follows that the space $\mathscr{N}(P, \dot{\xi})$ of vectorvalued functions which satisfy the equation

$$
L\left(P, \dot{\xi}+\nu D_{t}\right) F(t)=0 \quad \text { in } t>0
$$

and belong to $H_{1}\left(\boldsymbol{R}_{+}\right)^{N}$ is isomorphic as a vector space to the space of initial values:

$$
\mathscr{N}_{0}(P, \dot{\xi})=\left\{F(0) \in C^{N} ; F(t) \in \mathscr{N}(P, \dot{\xi})\right\}
$$

Let $\mathscr{N}_{0}^{\perp}(P, \dot{\xi})$ be the orthogonal complement of the space $\mathscr{N}_{0}(P, \dot{\xi})$ with respect to $C^{N}$ and put

$$
\boldsymbol{r}(P, \xi)=\operatorname{dim} \mathscr{N}_{0}(P, \dot{\xi})
$$

Then we can show
THEOREM 4. The formally positive quadratic form $Q[u, u]$ of the form (5.2) satisfying (5.3) is coercive over $V\left(S_{1}, S_{2}\right)$ if and only if
$\left\{\begin{array}{l}\text { for every } P \text { on } \bar{\Gamma}_{\alpha}(\alpha=1,2) \text { and every } \dot{\xi} \in T_{P}, \text { there exist } \mathrm{r}(P, \dot{\xi}) \\ \text { vectors among }\left\{\boldsymbol{b}_{j}(P) ; j \in S_{\alpha}\right\} \text { which are linearly independent } \\ \bmod \mathscr{N}_{0}^{\perp}(P, \dot{\xi}) .\end{array}\right.$

Proof. We have only to show that any function $F \in H_{1}\left(\boldsymbol{R}_{+}\right)^{N}$ satisfying (5.5) identically vanishes in $t>0$ if and only if (5.6) is valid, that is, to show that every $a \in \mathscr{N}_{0}(P, \dot{\xi})$ satisfying $\left\langle b_{j}(P), a\right\rangle=0$ for all $j \in S_{\alpha}$ vanishes if and only if (5.6) is valid. But this fact is immediately established.
Q.E.D.

Noting that $V\left(S_{1}, S_{2}\right)=H_{1}(\Omega)^{N}$ if $S_{1}=S_{2}=\phi$, we can prove
Corollary. The quadratic form $Q[u, u]$ in Theorem 4 is coercive over $H_{1}(\Omega)^{N}$ if and only if


Proof. It easily follows from (4.4) that the quadratic form $Q[u, u]$ is coercive over $H_{1}(\Omega)^{N}$ if and only if $\mathcal{N}(P, \dot{\xi})=\{0\}$ or $r(P, \dot{\xi})=0$ for every $P \in \Gamma$ and every $\dot{\xi} \in T_{P}$.

Suppose that (5.7) does not hold for some $P \in \Gamma, \dot{\xi} \in T_{P}$ and $\tau$ such
that $\operatorname{Im} \tau>0$. Then we can find a vector $a \neq 0$ in $C^{N}$ such that $L(P, \dot{\xi}+\tau \nu)=0$. Clearly we have $e^{i \tau t} a \in \mathscr{N}(P, \dot{\xi})$, and hence $\mathscr{N}(P, \dot{\xi}) \neq\{0\}$.

Now we assume that (5.7) holds. It is well-known that any solution $F(t)$ in $H_{1}\left(\boldsymbol{R}_{+}\right)$of the equation $L\left(P, \dot{\xi}+\nu D_{t}\right) F(t)=0$ can be written as a sum of

$$
\phi_{j_{k}}(t)=\frac{1}{k!}(i t)^{k} e^{i t \tau_{j}} a_{j k} \quad(j=1, \cdots, r ; k=0, \cdots, s)
$$

where $\tau_{j}$ are the distinct complex numbers such that $\operatorname{Im} \tau_{j}>0$ and $a_{j k}$ are some $N$-vectors. Since

$$
L\left(D_{t}\right) \phi_{j k}(t)=\left\{\frac{(i t)^{k}}{k!} L\left(\tau_{j}\right) a_{j k}+\frac{(i t)^{k-1}}{(k-1)!} L^{\prime}\left(\tau_{j}\right) a_{j k}\right\} e^{i t_{j}}
$$

and $L\left(D_{t}\right) F(t)=0$, we have, for $j=1, \cdots, r$,

$$
\left\{\begin{array}{l}
L\left(\tau_{j}\right) a_{j s}=0 \\
L\left(\tau_{j}\right) a_{j_{s-1}}+L^{\prime}\left(\tau_{j}\right) a_{j s}=0 \\
\quad \vdots \\
L\left(\tau_{j}\right) a_{j 0}+L^{\prime}\left(\tau_{j}\right) a_{j 1}=0
\end{array}\right.
$$

where we put, for brevity, $L\left(D_{t}\right)=L\left(P, \dot{\xi}+\nu D_{t}\right), L(\tau)=L(P, \dot{\xi}+\tau \nu)$, and $L^{\prime}(\tau)=d L(\tau) / d \tau$. It then follows from (5.7) that $a_{j s}=a_{j s-1}=\cdots$ $=a_{j 0}=0$ for all $j$. Accordingly we have $F(t)=0$ in $t>0$. Q.E.D.

By applying this corollary, we can finally give the simple proof of what is called the second Korn inequality :

$$
\begin{equation*}
\int_{\Omega} \sum_{i, j=1}^{n}\left|D_{j} u_{i}+D_{i} u_{j}\right|^{2} d x \geqq c\|u\|_{1}^{2}-\int_{\Omega}|u|^{2} d x \tag{5.8}
\end{equation*}
$$

for any $u=\left(u_{1}, \cdots, u_{n}\right) \in H_{1}(\Omega)^{n}$ with a constant $c>0$. The proof is anything but trivial. In fact, various proofs have been published by Friedrichs [3] and others (see [2] and Bibliography of Lecture 12 of [1]).

For $n$ functions $u=\left(u_{1}, \cdots, u_{n}\right)$ defined in $\Omega$, we define a system of $n^{2}$ differential equations:

$$
L_{i j}(D) u=D_{j} u_{i}+D_{i} u_{j}, \quad i, j=1, \cdots,, n
$$

and

$$
L(D) u={ }^{t}\left(L_{11}(D) u, \cdots, L_{1 n}(D) u, \cdots, L_{n 1}(D) u, \cdots, L_{n n}(D) u\right),
$$

which is one of operators of the type (5.1) with ( $n^{2} \times n$ )-matrices $A_{j}(x)$. Then it is obvious that the quadratic form (5.2) with $L(x, D)=L(D)$ becomes the left hand side of (5.8). Therefore, the inequality (5.8) means that the quadratic form (5.2) with $L(x, D)=L(D)$ is coercive over $H_{1}(\Omega)^{n}$, Consequently it is sufficient to verify (5.3) and (5.7), in order to show that the inequality (5.8) is valid for all $u \in H_{1}(\Omega)^{n}$.

To do so, let $a \in \boldsymbol{C}^{n}$ and $\zeta \in \boldsymbol{C}^{n}, \zeta \neq 0$, and assume that $L(\zeta) a=0$, i.e.,

$$
L_{i j}(\zeta) a=\zeta_{j} a_{i}+\zeta_{i} a_{j}=0
$$

for all $i, j=1, \cdots, n$. For $i$ such that $\zeta_{i} \neq 0$, we have $a_{i}=0$, for $L_{i i}(\zeta) a$ $=2 \zeta_{i} a_{i}=0$. Now let $\zeta_{i}=0$, for some $i$. There then exists an integer $j(\neq i)$ such that $\zeta_{j} \neq 0$. For such $i, j$, we have $L_{i j}(\zeta) a=\zeta_{j} a_{i}=0$, which implies $a_{i}=0$. Thus we get $a=0$. This means $\operatorname{rank} L(\zeta)=n$ for all $\zeta \in \boldsymbol{C}^{n}, \zeta \neq 0$. In particular, we have $\operatorname{rank} L(\xi)=n$ for $\xi \in \boldsymbol{R}^{n}, \xi \neq 0$.

Let $P$ be an arbitrary point on $\Gamma$. For every $\dot{\xi} \in T_{P}$ and every $\tau$ such that $\operatorname{Im} \tau>0$, it is easily proved that $\dot{\xi}+\tau \nu \in C^{n}(\nu=\nu(P))$ and $\dot{\xi}+\tau \nu \neq 0$. Accordingly $\operatorname{rank} L(\dot{\xi}+\tau \nu)=n$. Hence it follows from Corollary of Theorem 4 that Korn's inequality (5.8) is valid for all $u \in H_{1}(\Omega)^{n}$.

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