# DELAY DIFFERENTIAL EQUATIONS OF ODD ORDER SATISFYING PROPERTY $P_{k}$ 

RAYMOND D. TERRY

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#### Abstract

The property $P_{k}(k=0,1, \cdots, n)$ is formulated. For $k=0, n$ this property reduces to conditions $A$ and $B$ defined by Kiguradze (1962) for a class of ordinary differential equations. Sufficient conditions are then given which guarantee that a class of delay differential equations of odd order possesses property $P_{k}$. The property $P_{k}$ is also seen to be useful in reducing the number of types of positive solutions of a related nonhomogeneous delay differential equation.


The equation

$$
\begin{equation*}
D^{m} y(t)+F[t, y(t)]=0, m \geqq 2 \tag{1}
\end{equation*}
$$

has been considered by various authors subject to additional sign and monotone properties on $F(t, u)$. Briefly, a solution of (1) or of (2) below is called oscillatory on $[a, \infty)$ if for each $\alpha>a$ there is a $\beta>\alpha$ such that $y(\beta)=0$. It is called nonoscillatory otherwise. Paralleling the development by Kiguradze (1962) we adopt the following terminology.

Definition 1. For $m=2 n+1$, a positive solution y of (1) is of type $A_{k}$ $(k=0, \cdots, n)$ if for $t$ sufficiently large $D^{j} y(t)>0$ for $j=0, \cdots, 2 k$ and $(-1)^{j} D^{j} y(t)>0$ for $j=2 k+1, \cdots, 2 n$.

Definition 2. For $m=2 n$, a positive solution $y$ of (1) is of type $A_{k}$ $(k=0, \cdots, n-1)$ if for $t$ sufficiently large $D^{j} y(t)>0$ for $j=0, \cdots, 2 k+1$ and $(-1)^{j+1} D^{j} y(t)>0$ for $j=2 k+2, \cdots, 2 n-1$.

Definition 3. Equation (1) is said to satisfy condition $A$ if (1) has an oscillatory solution and every nonoscillatory solution tends to zero monotonically as $t \rightarrow \infty$.

DEFINITION 4. Equation (1) satisfies condition $B$ if a solution $y$ is either oscillatory or $\lim _{t \rightarrow \infty} D^{m-1} y(t)=0$.

It has been shown in Kiguradze (1962) that a positive solution of (1) is necessarily of type $A_{k}$ for some admissible $k$. For $m=2 n$, (1) fulfills condition $A$ if, and only if, all solutions are oscillatory. For $m=2 n+1$, (1) satisfies condition $A$ if, and only if, there are no solutions of type $A_{r}(r=1, \cdots, n)$ and every solution of type $A_{0}$ tends to zero monotonically as $t \rightarrow \infty$.

In section one we consider a homogeneous delay differential equation of odd order and formulate a property $P_{k}$ which includes both conditions $A$ and $B$ as special cases. Section two is devoted to providing sufficient conditions for the equation to possess property $\boldsymbol{P}_{k}$. In section three an a priori classification according to types $C_{k}^{R}$ is introduced for the positive solutions of a nonhomogeneous delay differential equation of odd order. The property $P_{k}$ is seen to be useful in reducing the kinds of positive solutions admissible.

## 1

In this section and the next we shall consider the homogeneous delay differential equation

$$
\begin{equation*}
D^{2 n+1-i}\left[r(t) D^{i} y(t)\right]+y_{\tau}(t) f\left[t, y_{\tau}(t)\right]=0 \tag{2}
\end{equation*}
$$

where $0<m \leqq r(t) \leqq M<\infty, 0 \leqq \tau(t) \leqq T<\infty, y_{\tau}(t)=y[t-\tau(t)]$ and $f(t, u)$ satisfies the following properties:
(F1) $\quad f(t, u)$ is a continuous real-valued function on $[0, \infty) \times R$;
(F2) for each fixed $t \in[0, \infty), f(t, u)<f(t, v)$ for $0<u<v$; and
(F3) for each fixed $t \in[0, \infty), f(t, u)>0$ and $f(t,-u)=f(t, u)$ for $u \neq 0$.
We first let

$$
y_{j}(t)= \begin{cases}D^{j} y(t), & j=0, \cdots, i-1 \\ D^{j-i}\left[r(t) D^{i} y(t)\right], & j=i, \cdots, 2 n\end{cases}
$$

Analogous to Definition 1 we shall classify the positive solutions of (2).
DEfinition 5. A positive solution y of (2) is of type $C_{k}$ on $\left[T_{0}, \infty\right)$ if for $t \geqq T_{0} y_{j}(t)>0(j=0, \cdots, 2 k)$ and $(-1)^{j} y_{j}(t)>0(j=2 k+1, \cdots, 2 n)$.

As in Terry $(1973,1974)$, it is evident that a positive solution of (2) is necessarily of type $C_{k}$ for some $k=0, \cdots, n$. Moreover, the following two lemmas may be established.

Lemma 1. Let y be a solution of (2) of type $C_{k}, k \geqq 1$. Then there exist numbers $N_{j}^{k}>0(j=0, \cdots, 2 k)$ such that

$$
\begin{aligned}
&\left(t-T_{1}\right) y_{i}(t) \leqq N_{i}^{k} y_{j-1}(t), t \geqq T_{1} \\
&=T_{0}+T \text { and } \\
& t y_{j}(t) \leqq 2 N_{j}^{k} y_{j-1}(t), \quad t \geqq 2 T_{1} .
\end{aligned}
$$

Lemma 2. Let $y$ be a solution of (2) of type $C_{k}, k \geqq 1$. Then there exist numbers $k_{i}>0$ and $t_{j} \geqq T_{1}(j=0, \cdots, 2 k-1)$ such that

$$
y_{i r}(t)=y_{j}(t-\tau(t)) \geqq k_{j} y_{j}(t), \quad t \geqq t_{j} .
$$

While it is of interest to obtain specific estimates for the numbers $N_{j}^{k}$, this is unnecessary for the subsequent development of this paper. As in Terry (1973), these two lemmas and the later results may be extended to the case where $\tau(t)$ satisfies either of the two conditions

$$
\begin{align*}
& 0 \leqq \tau(t) \leqq \mu t, \quad 0 \leqq \mu<m /(m+M), \text { or }  \tag{T1}\\
& 0 \leqq \tau(t) \leqq \mu t^{\beta}, \quad 0 \leqq \mu<\infty \text { and } 0 \leqq \beta<1
\end{align*}
$$

provided $T_{1}$ is reinterpreted as $\min \left\{t>T_{0}: t-\tau(t) \geqq T_{0}\right.$ for $\left.t \geqq T_{1}\right\}$.
Definition 6. Equation (2) fulfills property $P_{k}$ if, and only if, (2) has no solutions of types $C_{r}(r=k+1, \cdots, n)$ and for any solution $y(t)$ of type $C_{k}$ the intermediate function $y_{2 k}(t)$ tends to zero monotonically as $t \rightarrow \infty$.

When $r \equiv 1$ and $\tau \equiv 0$, the classification of solutions of (2) according to types $C_{k}$ coincides with that of Kiguradze (1962). Moreover, property $P_{0}$ is the natural analogue of condition $A$; property $P_{n}$ corresponds to condition $B$.

We now seek to prescribe conditions which ensure that equation (2) fulfills the property $P_{k}$.

Theorem 1. Let y be a positive solution of (2) of type $C_{k}$. Then $y_{2 k}(t)$ tends to zero monotonically as $t \rightarrow \infty$ if for all positive constants $C$

$$
\begin{equation*}
\int^{\infty} t^{2 n} f\left(t, C t^{2 k}\right) d t=+\infty \tag{3}
\end{equation*}
$$

Proof. Let $y$ be a solution of (2) of type $C_{k}$ on $\left[T_{0}, \infty\right)$. Then for $t \geqq T_{1}$, $y_{\tau}(t)>0, y_{j}(t)>0(j=0, \cdots, 2 k)$ and $(-1)^{j} y_{j}(t)>0(j=2 k+1, \cdots, 2 n)$. Multiplying (2) by $t^{2 n-2 k}$ and integrating from $T_{1}$ to $t \geqq T_{1}$

$$
\int_{T_{1}}^{t} s^{2 n-2 k} D y_{2 n}(s) d s+\int_{T_{1}}^{t} s^{2 n-2 k} y_{\tau}(s) f\left[s, y_{\tau}(s)\right] d s=0 .
$$

Integrating the first term by parts

$$
\begin{aligned}
I & \equiv \int_{T_{1}}^{t} s^{2 n-2 k} D y_{2 n}(s) d s=\left[s^{2 n-2 k} y_{2 n}(s)\right]_{T_{i}}^{t} \\
& -(2 n-2 k) \int_{T_{1}}^{t} s^{2 n-2 k-1} y_{2 n}(s) d s
\end{aligned}
$$

An easy induction yields

$$
I=\left[\sum_{j=0}^{i}(-1)^{j}(2 n-2 k)_{j} s^{2 n-2 k-i} y_{2 n-j}(s)\right]{ }_{T_{i}}
$$

$$
\begin{equation*}
+(-1)^{t+1}(2 n-2 k)_{t+1} \int_{T_{1}}^{t} s^{2 n-2 k-t-1} y_{2 n-l}(s) d s \tag{4}
\end{equation*}
$$

where $0 \leqq j \leqq l \leqq 2 n-i,(n)_{0}=1$ and $(n)_{k}=n \cdots(n-k+1)$ for $k \geqq 1$. If $2 k \geqq i, 2 n-2 k \leqq 2 n-i$ and we may let $l=2 n-2 k-1$ in (4) to obtain

$$
\left.I=\left[\sum_{j=0}^{2 n-2 k-1}(-1)^{i}(2 n-2 k)_{j} s^{2 n-2 k-j} y_{2 n-j}(s)\right]\right]_{T_{1}}
$$

$$
\begin{equation*}
+(-1)^{2 n-2 k}(2 n-2 k)_{2 n-2 k} \int_{T_{1}}^{t} y_{2 k+1}(s) d s \tag{5}
\end{equation*}
$$

On the other hand, if $1<2 k<i$, then $2 n-2 k>2 n-i$. We let $l=2 n-i$ in (4) and observe that

$$
\begin{aligned}
(-1)^{I+1} y_{2 n-1}(s) & =(-1)^{2 n-i+1} y_{i}(s)=(-1)^{i+1} y_{i}(s) \\
& =(-1)^{i+1} r(s) D^{i} y(s) \\
& \geqq(-1)^{i+1} M D^{i} y(s)
\end{aligned}
$$

Then (4) becomes

$$
I \geqq\left[\sum_{j=0}^{2 n-i}(-1)^{i}(2 n-2 k)_{j} s^{2 n-2 k-j} y_{2 n-j}(s)\right]{ }_{T},
$$

$$
\begin{equation*}
+(-1)^{2 n-i+1} M(2 n-2 k)_{2 n-i+1} \int_{\pi}^{t} s^{i-2 k-1} D y_{i-1}(s) d s \tag{6}
\end{equation*}
$$

We now examine the latter integral. An integration by parts results in

$$
\begin{aligned}
J \equiv \int_{T_{1}}^{t} s^{i-2 k-1} D y_{i-1}(s) d s & =\left[s^{i-2 k-1} y_{i-1}(s)\right]_{T_{1}}^{t} \\
& -(i-2 k-1) \int_{T_{1}}^{t} s^{i-2 k-2} y_{i-1}(s) d s .
\end{aligned}
$$

This serves as the anchor for another inductive argument based on further integration by parts. It follows that

$$
\begin{aligned}
J & =\left[\sum_{j=1}^{L}(-1)^{j+1}(i-2 k-1)_{j-i} s^{i-2 k-j} y_{i-j}(s)\right] \frac{t_{1}}{T_{1}} \\
& +(-1)^{L}(i-2 k-1)_{L} \int_{T_{1}}^{1} s^{i-2 k-j-1} y_{i-L}(s) d s
\end{aligned}
$$

where $1 \leqq j \leqq L \leqq i-2 k-1$. Combining (6) and (7), we obtain

$$
\begin{aligned}
& I \geqq\left[\sum_{j=0}^{2 n-i}(-1)^{j}(2 n-2 k)_{j} s^{2 n-2 k-j} y_{2 n-j}(s)\right. \\
&\left.+N_{1} \sum_{j=1}^{L}(-1)^{j+1}(i-2 k-1)_{j} s^{i-2 k-j} y_{i-j}(s)\right] T_{i} \\
&+N_{1} N_{2} \int_{T_{i}}^{t} y_{i-L}(s) d s
\end{aligned}
$$

where $N_{1}=(-1)^{i+1} M(2 n-2 k)_{2 n-i+1}$ and $N_{2}=(-1)^{L}(i-2 k-1)_{L}$. We may let $L=i-2 k-1$ in this and observe that

$$
\operatorname{sgn} N_{1} N_{2}=(-1)^{i+1}(-1)^{L}=(-1)^{i+1}(-1)^{i-2 k-1}=+1
$$

It follows that
(8a)

$$
\begin{aligned}
{\left[F_{2 k}(s)\right]_{T_{1}}^{t} } & +(2 n-2 k)!\int_{T_{1}}^{t} y_{2 k+1}(s) d s \\
& +\int_{T_{1}}^{1} s^{2 n-2 k} y_{\tau}(s) f\left[s, y_{\tau}(s)\right] d s=0
\end{aligned}
$$

for $i \leqq 2 k$ and

$$
\left[\bar{F}_{2 k}(s)\right]_{T_{1}}^{t}+N_{1} N_{2} \int_{T_{1}}^{t} y_{2 k+1}(s) d s
$$

(8b)

$$
+\int_{T_{1}}^{t} s^{2 n-2 k} y_{\tau}(s) f\left[s, y_{\tau}(s)\right] d s \leqq 0
$$

for $i>2 k$, where

$$
\begin{aligned}
F_{2 k}(s)= & \sum_{i=0}^{2 n-2 k-1}(-1)^{j}(2 n-2 k)_{j} s^{2 n-2 k-j} y_{2 n-j}(s) \text { and } \\
\bar{F}_{2 k}(s)= & \sum_{j=0}^{2 n-i}(-1)^{i}(2 n-2 k)_{j} s^{2 n-2 k-j} y_{2 n-j}(s) \\
& +N_{1} \sum_{j=1}^{i-2 k-1}(-1)^{j}(i-2 k-1)_{j} s^{i-2 k-j} y_{i-i}(s)
\end{aligned}
$$

We note that each term of $F_{2 k}(s)$ is positive on $\left[T_{1}, \infty\right)$ since

$$
(-1)^{i} y_{2 n-j}(s)=(-1)^{2 n-i}(s)=(-1)^{p} y_{p}(s)
$$

and $p=2 n-j \geqq 2 k+1$ since $0 \leqq j \leqq 2 n-2 k-1$. Similarly, each term of $\bar{F}_{2 k}(s)$ is positive since

$$
(-1)^{i+1}(-1)^{i+1} y_{i-j}(s)=(-1)^{i-j} y_{i-j}(s)=(-1)^{q} y_{q}(s)
$$

and $q=i-j \geqq 2 k+1$ since $j \leqq i-2 k-1$. Moreover,

$$
\begin{aligned}
\int_{T_{t}}^{t} y_{2 k+1}(s) d s & =y_{2 k}(t)-y_{2 k}\left(T_{1}\right) \quad \text { if } \quad 2 k+1 \neq i \\
& =\int_{T_{1}}^{t} r(s) D^{i} y(s) \quad \text { if } \quad 2 k+1=i \\
& \geqq M \int_{T_{2}}^{t} D^{i} y(s)=M\left[\dot{y}_{2 k}(t)-y_{2 k}\left(T_{1}\right)\right] .
\end{aligned}
$$

Let us assume that $\lim _{t \rightarrow \infty} y_{2 k}(t)=\gamma>0$. Since $y_{2 k+1}(t)<0$ on $\left[T_{1}, \infty\right), y_{2 k}(t)$ is a decreasing function of $t$ on $\left[T_{1}, \infty\right)$ and $y_{2 k}(t) \geqq \gamma, t \geqq T_{1}$. By Lemma 1

$$
y(s) \geqq N s^{2 k} y_{2 k}(s) \geqq N \gamma s^{2 k}, \text { where } N^{-1}=N_{1}^{k} N_{2}^{k} \cdots N_{2 k}^{k} .
$$

Hence,

$$
y_{\tau}(s) \geqq N \gamma[s-\tau(s)]^{2 k} \geqq N \gamma(1-\mu)^{2 k} s^{2 k}
$$

if $\tau$ satisfies (T1). On the other hand, if $\tau$ satisfies (T2), there is a $T_{2} \geqq T_{1}$ such that $s-\tau(s) \geqq s / 2$ for $s \geqq T_{2}$, which implies that $y_{\tau}(s) \geqq N \gamma 2^{-2 k} s^{2 k}$ for $s \geqq T_{2}$. As we may replace $T_{1}$ by $T_{2}$ in the above considerations, we may assume, without loss of generality, that $T_{2}=T_{1}$. Thus, in either case $y_{\tau}(s) \geqq C s^{2 k}$ on the appropriate interval so that

$$
\begin{aligned}
s^{2 n-2 k} y_{\tau}(s) f\left[s, y_{\tau}(s)\right] & \geqq s^{2 n-2 k} C s^{2 k} f\left[s, C s^{2 k}\right] \\
& =C s^{2 n} f\left(s, C s^{2 k}\right)
\end{aligned}
$$

For $i \leqq 2 k$ we substitute in (8a)

$$
\left[F_{2 k}(s)\right]_{T_{1}}^{l_{1}}+(2 n-2 k)!\left[y_{2 k}(s)\right]_{T_{1}}^{t_{1}} s^{2 n} f\left(s, C s^{2 k}\right) d s \leqq 0
$$

Transposing,

$$
\int_{T_{1}}^{t} s^{2 n} f\left(s, C s^{2 k}\right) d s \leqq C^{-1}\left[F_{2 k}\left(T_{1}\right)+(2 n-2 k)!y_{2 k}(t)\right]
$$

This contradicts (3) in the case $\tau$ satisfies ( $T 1$ ); if $\tau$ satisfies ( $T 2$ ), we replace $T_{1}$ by $T_{2}$ and obtain the same contradiction. For $i>2 k$, we substitute in ( 8 b ) instead.

Theorem 2. Let $\phi$ be a function satisfying $\phi(y)>0, \phi^{\prime}(y) \geqq 0$ and

$$
\begin{equation*}
\int^{\infty} \frac{d y}{y \phi(y)}<\infty \tag{9a}
\end{equation*}
$$

then (2) fulfills property $P_{k}$ if for all positive constants $C$

$$
\begin{equation*}
\int^{\infty} t^{2 n} f\left(t, C t^{2 k}\right) \phi^{-1}(t) d t=+\infty \tag{9b}
\end{equation*}
$$

Proof. Suppose that $y$ is a solution of (2) of type $C_{k}$ on $\left[T_{0}, \infty\right)$, where $k \geqq 1$. Then multiplying equation (2) by $t^{2 n}[\phi(t) y(t)]^{-1}$ and integrating from $T_{1}$ to $t>T_{1}$

$$
\begin{equation*}
\int_{T_{1}}^{t} s^{2 n} D y_{2 n}(s)[\phi(s) y(s)]^{-1} d s+\int_{T_{1}}^{t} s^{2 n} \frac{f\left[s, y_{\tau}(s)\right.}{\phi(s) y(s)} d s=0 . \tag{10}
\end{equation*}
$$

We denote the first integral by $I_{1}$. An integration by parts yields

$$
\begin{equation*}
I_{1}=\left[\gamma(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \gamma(s) D\left((\phi(s) y(s))^{-1}\right) d s, \tag{11}
\end{equation*}
$$

where $\gamma(s)=D^{-1}\left(s^{2 n} D y_{2 n}(s)\right)$. Specifically, one integration by parts gives

$$
\gamma(s)=s^{2 n} y_{2 n}(s)-2 n D^{-1}\left(s^{2 n-1} y_{2 n}(s)\right) .
$$

We may establish by induction that

$$
\begin{align*}
\gamma(s) & =\sum_{j=0}^{p}(-1)^{j}(2 n)_{j} s^{2 n-j} y_{2 n-j}(s) \\
& +\left(-1^{p+1}(2 n)_{p+1} D^{-1}\left[s^{2 n-p-1} y_{2 n-p}(s)\right]\right. \tag{12}
\end{align*}
$$

for $0 \leqq j \leqq p \leqq 2 n-i$. If $2 k \leqq i, 2 n-2 k \leqq 2 n-i$ and we may let $p=2 n-2 k$ in (12) to obtain

$$
\gamma(s)=\sum_{j=0}^{2 n-2 k}(-1)^{i}(2 n)_{j} s^{2 n-i} y_{2 n-j}(s)+N_{0} D^{-1}\left[s^{2 k-1} y_{2 k}(s)\right],
$$

where $N_{0}=(-1)^{2 n-2 k+1}(2 n)_{2 n-2 k+1}$. We define $\gamma_{0}(s)$ by

$$
\gamma(s)=\gamma_{0}(s)+N_{0} D^{-1}\left[s^{2 k-1} y_{2 k}(s)\right] .
$$

Then, a substitution in (11) produces

$$
\begin{aligned}
& I_{1}= {\left[\left(\gamma_{0}(s)+N_{0} D^{-1}\left(s^{2 k-1} y_{2 k}(s)\right)\right)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t} } \\
&-\int_{T_{1}}^{t}\left(\gamma_{0}(s)+N_{0} D^{-1}\left(s^{2 k-1} y_{2 k}(s)\right) D\left((\phi(s) y(s))^{-1}\right) d s\right. \\
&=\left[\gamma_{0}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \gamma_{0}(s) D\left((\phi(s) y(s))^{-1}\right) d s \\
&+N_{0}\left[D^{-1}\left(s^{2 k-1} y_{2 k}(s)\right) / \phi(s) y(s)\right]_{T_{1}}^{t} \\
&-N_{0} \int_{T_{1}}^{1} D^{-1}\left(s^{2 k-1} y_{2 k}(s)\right) D\left((\phi(s) y(s))^{-1}\right) d s .
\end{aligned}
$$

Applying the integration-by-parts formula in reverse, we recombine the last two terms to obtain

$$
\begin{aligned}
I_{1}=\left[\gamma_{0}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t} & -\int_{T_{1}}^{t} \gamma_{0}(s) D\left((\phi(s) y(s))^{-1}\right) d s \\
& +N_{0} \int_{T_{1}}^{1} \frac{s^{2 k-1} y_{2 k}(s)}{\phi(s) y(s)} d s
\end{aligned}
$$

By Lemma 1 there is a number $N_{2 k}=N_{1}^{k} \cdots N_{2 k}^{k}>0$ such that

$$
t^{2 k} y_{2 k}(t) \leqq N_{2 k} y(t) \text { for } t \geqq 2 T_{1}
$$

Thus

$$
\frac{s^{2 k-1} y_{2 k}(s)}{\phi(s) y(s)}=\frac{s^{2 k} y_{2 k}(s)}{s \phi(s) y(s)} \leqq \frac{N_{2 k}}{s \phi(s)} .
$$

Since $N_{0}=-\left|N_{0}\right|<0$,

$$
I_{1} \geqq\left[\gamma_{0}(s)(\phi(s) y(s))^{-1} l_{T_{1}}^{t}-\int_{T_{1}}^{t} \gamma_{0}(s) D\left((\phi(s) y(s))^{-1}\right) d s\right.
$$

$$
\begin{equation*}
-\left|N_{0}\right| N_{2 k} \int_{2 T_{1}}^{t} \frac{d s}{s \phi(s)} \tag{13}
\end{equation*}
$$

Otherwise, if $2 k<i$, we continue the inductive procedure defined by (12) until $p=2 n-i$. Then (12) becomes

$$
\gamma(s)=\sum_{i=0}^{2 n-i}(-1)^{i}(2 n)_{i} s^{2 n-j} y_{2 n-j}(s)+N_{1} D^{-1}\left[s^{i-i} y_{i}(s)\right],
$$

where $N_{1}=(-1)^{2 n-i+1}(2 n)_{2 n-i+1}$. Letting

$$
\gamma(s)=\gamma_{1}(s)+N_{1} D^{-1}\left[s^{i-1} y_{i}(s)\right] ;
$$

it follows as before upon substitution in (11) that

$$
\begin{aligned}
I_{1}=\left[\gamma_{1}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{\prime} & -\int_{T_{1}}^{1} \gamma_{1}(s) D\left((\phi(s) y(s))^{-1}\right) d s \\
& +N_{1} \int_{T_{1}}^{1} \frac{s^{i-1} y_{i}(s)}{\phi(s) y(s)} d s .
\end{aligned}
$$

We observe that

$$
\begin{aligned}
N_{1} y_{i}(s) & =\left|N_{1}\right|(-1)^{2 n-i+1} y_{i}(s)=\left|N_{1}\right|(-1)^{i+1} y_{i}(s) \\
& =\left|N_{1}\right|(-1)^{i+1} r(s) D y_{i-1}(s) \\
& \geqq\left|N_{1}\right|(-1)^{i+1} M D y_{i-1}(s)=M N_{1} D y_{i-1}(s)
\end{aligned}
$$

Thus,

$$
I_{1} \geqq\left[\gamma_{1}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t_{1}}-\int_{r_{i}}^{1} \dot{\gamma_{1}}(s) D\left((\phi(s) y(s))^{-1}\right) d s
$$

$$
\begin{equation*}
+N_{1} M \int_{T_{1}}^{1} \frac{s^{i-1} D y_{i-1}(s)}{\phi(s) y(s)} d s \tag{14}
\end{equation*}
$$

Analogous to (11) we have

$$
\begin{aligned}
I_{2}=\int_{T_{1}}^{1} \frac{s^{i-1} D y_{i-1}(s)}{\phi(s) y(s)} d s & =\left[\gamma_{2}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t} \\
& -\int_{T_{1}}^{1} \gamma_{2}(s) D\left((\phi(s) y(s))^{-1}\right) d s
\end{aligned}
$$

where $\gamma_{2}(s)=D^{-1}\left[s^{i-1} D y_{i-1}(s)\right]$. We find upon one integration that

$$
\gamma_{2}(s)=s^{i-1} y_{i-1}(s)-(i-1) D^{-1}\left[s^{i-2} y_{i-1}(s)\right] .
$$

An inductive argument yields

$$
\begin{aligned}
\gamma_{2}(s)= & \sum_{j=1}^{p}(-1)^{i+1}(i-1)_{j-1} s^{i-j} y_{i-i}(s) \\
& +(-1)^{p}(i-1)_{p} D^{-1}\left[s^{i-p-1} y_{i-p}(s)\right]
\end{aligned}
$$

for $i \leqq j \leqq p \leqq i-2 k$. Letting $p=i-2 k$ results in

$$
\begin{aligned}
\gamma_{2}(s)= & \sum_{j=1}^{i-2 k}(-1)^{i+1}(i-1)_{j-1} s^{i-j} y_{i-j}(s) \\
& +(-1)^{i-2 k}(i-1)_{i-2 k} D^{-1}\left[s^{2 k-1} y_{2 k}(s)\right] \\
= & \gamma_{3}(s)+N_{2} D^{-1}\left[s^{2 k-1} y_{2 k}(s)\right]
\end{aligned}
$$

where

$$
\begin{aligned}
\gamma_{3}(s) & =\sum_{j=1}^{i-2 k}(-1)^{j+1}(i-1)_{j-1} s^{i-j} y_{i-j}(s) \\
N_{2} & =(-1)^{i-2 k}(i-1)_{i-2 k} .
\end{aligned}
$$

and
To simplify the expressions involved, let

$$
\begin{aligned}
\Gamma(s) & =\gamma_{1}(s)+M N_{1} \gamma_{2}(s) \\
& =\gamma_{1}(s)+M N_{1}\left[\gamma_{3}(s)+N_{2} D^{-1}\left(s^{2 k-1} y_{2 k}(s)\right)\right] \\
& =\gamma_{1}(s)+M N_{1} \gamma_{3}(s)+M N_{1} N_{2} D^{-1}\left[s^{2 k-1} y_{2 k}(s)\right] \\
& =\Gamma_{0}(s)+M N_{1} N_{2} D^{-1}\left[s^{2 k-1} y_{2 k}(s)\right] \\
& =\Gamma_{0}(s)-M\left|N_{1} N_{2}\right| D^{-1}\left[s^{2 k-1} y_{2 k}(s)\right] .
\end{aligned}
$$

We note here that $\operatorname{sgn} N_{1} N_{2}=(-1)^{2 n-i+1}(-1)^{i-2 k}=(-1)^{1}=-1$. Substituting in (14),

$$
\begin{aligned}
I_{1} \geqq & {\left[\gamma_{1}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \gamma_{1}(s) D\left((\phi(s) y(s))^{-1}\right) d s } \\
& +M N_{1}\left[\left(\gamma_{3}(s)+N_{2} D^{-1}\left(s^{2 k-1} y_{2 k}(s)\right)\right) / \phi(s) y(s)\right]_{T_{1}}^{\prime} \\
& -M N_{1} \int_{T_{1}}^{1}\left(\gamma_{3}(s)+N_{2} D^{-1}\left(s^{2 k-1} y_{2 k}(s)\right)\right) D\left((\phi(s) y(s))^{-1}\right) d s
\end{aligned}
$$

$$
\begin{aligned}
= & {\left[\Gamma_{0}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \Gamma_{0}(s) D\left((\phi(s) y(s))^{-1}\right) d s } \\
& +M N_{1} N_{2} \int_{T_{1}}^{t} \frac{s^{2 k-1} y_{2 k}(s)}{\phi(s) y(s)} d s .
\end{aligned}
$$

As in the discussion preceding (13) we conclude that

$$
\begin{align*}
I_{1} \tau\left[\Gamma_{0}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t} & -\int_{T_{1}}^{t} \Gamma_{0}(s) D\left((\phi(s) y(s))^{-1}\right) d s \\
& -M\left|N_{1} N_{2}\right| \int_{2 T_{1}}^{t} \frac{d s}{s \phi(s)} \tag{15}
\end{align*}
$$

We next consider the second integral in (10). By Lemma 2 there is a $k_{0}>0$ and a $t_{0}>T_{1}$ such that $y_{\tau}(s) \geqq k_{0} y(s)$ for $s \geqq t_{0}$. Since $y_{2 k}(s)>0, y_{2 k-1}(s)$ is increasing on $\left[T_{0}, \infty\right)$ and there is a $C_{0}>0$ such that $y_{2 k-1}(s) \geqq C_{0}$ for $s \geqq T_{1}$. Moreover, by Lemma 1 there is an $N_{2 k-1}=N_{1}^{k} \cdots N_{2 k-1}^{k}$ such that $s^{2 k-1} y_{2 k-1}(s) \leqq N_{2 k-1} y(s)$ for $s \geqq 2 T_{1}$. Thus,

$$
y_{\tau}(s) \geqq k_{0} y(s) \geqq k_{0} N_{2 k-1}^{-1} s^{2 k-1} y_{2 k-1}(s) \geqq k_{0} N_{2 k-1}^{-1} C_{0} s^{2 k-1} .
$$

By (iii)

$$
s^{2 n} f\left[s, y_{\tau}(s)\right] y_{\tau}(s) y^{-1}(s) \phi^{-1}(s) \geqq k_{0} s^{2 n} f\left(s, C_{1} s^{2 k-1}\right) \phi^{-1}(s),
$$

where $C_{1}=k_{0} N_{2 k-1}^{-1} C_{0}$ and $s \geqq T_{*}=\max \left\{t_{0}, 2 T_{1}\right\}$. As a result,

$$
\begin{aligned}
\int_{T_{1}}^{t} \frac{s^{2 n} f\left[s, y_{\tau}(s)\right] y_{\tau}(s) d s}{\phi(s) y(s)} & \geqq \int_{T .}^{t} \frac{s^{2 n} f\left[s, y_{\tau}(s)\right] y_{\tau}(s) d s}{\phi(s) y(s)} \\
& \geqq k_{0} \int_{T .}^{1} s^{2 n} f\left(s, C_{1} s^{2 k-1}\right) d s / \phi(s)
\end{aligned}
$$

Substituting (16) together with (13) or (15) in (10), we obtain
$\left[\gamma_{0}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \gamma_{0}(s) D\left((\phi(s) y(s))^{-1}\right) d s$
(17a)

$$
-\left|N_{0}\right| N_{2 k} \int_{2 T_{1}}^{t} \frac{d s}{s \phi(s)}+k_{0} \int_{T .}^{t} s^{2 n} f\left(s, C_{1} s^{2 k-1}\right) d s / \phi(s) \leqq 0 \quad \text { for } 2 k \geqq i
$$

or
$\left[\Gamma_{0}(s)(\phi(s) y(s))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \Gamma_{0}(s) D\left((\phi(s) y(s))^{-1}\right) d s$
$(17 \mathrm{~b})$
$-M\left|N_{1} N_{2}\right| N_{2 k} \int_{2 T_{1}}^{1} \frac{d s}{s \phi(s)}+k_{0} \int_{T .}^{1} s^{2 n} f\left(s, C_{1} s^{2 k-1}\right) d s / \phi(s) \leqq 0 \quad$ for $2 k<i$.

We note that each term of $\gamma_{0}(s)$ or of $\Gamma_{0}(s)$ is positive on $\left[T_{1}, \infty\right)$. Since $k \geqq 1, y^{\prime}(s) \geqq 0$ and

$$
-D\left((\phi(s) y(s))^{-1}\right)=\frac{D(\phi(s) y(s))}{[\phi(s) y(s)]^{2}}=\frac{\phi(s) y^{\prime}(s)+\phi^{\prime}(s) y(s)}{[\phi(s) y(s)]^{2}}>0 .
$$

Consequently,

$$
\int_{T}^{t} s^{2 n} f\left(s, C_{1} s^{2 k-1}\right) \phi^{-1}(s) d s \leqq\left\{\begin{array}{l}
k_{0}^{-1}\left[\gamma_{0}(\phi y)\left(T_{1}\right)+\left|N_{0}\right| N_{2 k} \int_{2 T_{1}}^{t} \frac{d s}{s \phi(s)}\right] \\
k_{0}^{-1}\left[\Gamma_{0}(\phi y)\left(T_{1}\right)+M\left|N_{1} N_{2}\right| N_{2 k} \int_{2 T_{1}}^{t} \frac{d s}{s \phi(s)}\right]
\end{array}\right.
$$

Thus the condition

$$
\int^{x} t^{2 n} f\left(t, C t^{2 k-1}\right) \phi^{-1}(t) d t=\infty, \quad k \geqq 1
$$

will imply that (2) has no $C_{r}$-solutions $(r=k, \cdots, n)$, that is the condition

$$
\int^{\infty} t^{2 n} f\left(t, C t^{2 k+1}\right) \phi^{-1}(t) d t=\infty, \quad k \geqq 0
$$

will imply that (2) has no $C_{r}$ - solution $r=k+1, \cdots, n$ ). A fortiori, (9b) implies that (2) has no $C_{r}$-solutions ( $r=k+1, \cdots, n$ ), where $k \geqq 0$. In addition, the conditions $\phi>0$ and $\phi^{\prime} \geqq 0$ show that there is a $k>0$ such that $\phi(t) \geqq k$ so that

$$
\begin{aligned}
\int^{\infty} t^{2 n} f\left(t, C t^{2 k}\right) d t & =k\left[\frac{1}{k} \int^{\infty} t^{2 n} f\left(t, C t^{2 k}\right) d t\right] \\
& \geqq k \int^{\infty} t^{2 n} f\left(t, C t^{2 k}\right) \phi^{-1}(t) d t
\end{aligned}
$$

Thus, the integral condition of (9b) implies that of (3). By Theorem 1, any $C_{k}$ - solution $y$ of (2) will satisfy $\lim _{t \rightarrow \infty} y_{2 k}(t)=0$. It follows that (2) possesses property $P_{k}$.

By modifying the conditions on $f$ and $\phi$, we may obtain a simpler criterion for the presence of property $P_{k}$.

Definition 7. The function $f$ is nonlinear with strength coefficient $2 n+1-j$ $(j=0, \cdots, 2 n+1)$ if, and only if, there is a function $\phi$ satisfying $\phi(u)>0$, $\phi^{\prime}(u) \geq 0$,

$$
\int^{\infty} \frac{d u}{u \phi(u)}<\infty
$$

and $f(t, u) \geqq \phi(u) f\left(t, C t^{j}\right)$.

When $j=0$, the strength coefficient is maximal and $f(t, u)$ is called strongly nonlinear.

In the presence of some degree of nonlinearity, the hypotheses of Theorem 2 may be proportionately weakened. Suppose that $f$ is nonlinear with strength coefficient $2 n+1-2 j$ and $\phi^{\prime \prime}(u)<0$. Then, multiplying (2) by $t^{2 n}[\phi(y) y]^{-1}$, we obtain as in the proof of Theorem 2

$$
\begin{aligned}
& {\left[\gamma_{0}(s)(y(s) \phi(y(s)))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \gamma_{0}(s) D\left((y(s) \phi(y(s)))^{-1}\right) d s} \\
& \quad-\int_{T_{1}}^{t} \frac{s^{2 k-1} y_{2 k}(s)}{y(s) \phi(y(s))} d s+\int_{T_{1}}^{t} s^{2 n} y_{\tau}(s) f\left[s, y_{\tau}(s)\right] d s / \phi(y(s)) y(s)=0
\end{aligned}
$$

or

$$
\begin{aligned}
0 \geqq & {\left[\Gamma_{0}(s)(y(s) \phi(y(s)))^{-1}\right]_{T_{1}}^{t}-\int_{T_{1}}^{t} \Gamma_{0}(s) D\left((y(s) \phi(y(s)))^{-1}\right) d s } \\
& -M\left|N_{1} N_{2}\right| \int_{T_{1}}^{t} \frac{s^{2 k-1} y_{2 k}(s)}{y(s) \phi(y(s))} d s \\
& +\int_{T_{1}}^{t} s^{2 n} y_{\tau}(s) f\left[s, y_{\tau}(s)\right] d s / y(s) \phi(y(s))
\end{aligned}
$$

Since $\phi>0, \phi^{\prime} \geqq 0$ and $\phi^{\prime \prime} \leqq 0, \phi^{\prime}$ is a positive decreasing function on $\left[T_{0}, \infty\right)$ so that

$$
\phi(t)-\phi\left(T_{1}\right)=\int_{T_{1}}^{t} \phi^{\prime}(s) d s \geqq\left(t-T_{1}\right) \phi^{\prime}(t)
$$

that is.

$$
\left(t-T_{1}\right) \phi^{\prime}(t) \leqq \phi(t)-\phi\left(T_{1}\right)<\phi(t)
$$

for $t \geqq T_{1}$. Thus, $t \phi^{\prime}(t) \leqq \phi(t)$ for $t \geqq 2 T_{1}$. Either of these inequalities implies that $\lim _{t \rightarrow \infty} \phi^{\prime}(t) / \phi(t)=0$. We consider

$$
\left|\frac{\phi\left(y_{\tau}(t)\right)}{\phi(y(t))}-1\right|=\frac{\phi(y(t))-\phi\left(y_{\tau}(t)\right)}{\phi(y(t))}=\frac{\tau(t) \phi^{\prime}(\mu)}{\phi(y)}
$$

for some $\mu$, where $y_{\tau}(t)<\mu<y(t)$. Since $\phi$ is an increasing function, $\phi\left(y_{\tau}(t)\right)<\phi(\mu)<\phi(y(t))$, which implies that $1 / \phi(y(t))<1 / \phi\left(y_{\tau}(t)\right)$. Similarly, $\phi^{\prime}$ is a decreasing function so that $\phi^{\prime}(\mu)<\phi^{\prime}\left(y_{\tau}(t)\right)$. Thus, $\phi^{\prime}(\mu) / \phi(y(t))<\phi^{\prime}\left(y_{\tau}(t)\right) / \phi\left(y_{\tau}(t)\right)$. Moreover, because $k \geqq 1, \lim _{t \rightarrow \infty} y_{\tau}(t)=\infty$, which shows that

$$
\lim _{t \rightarrow \infty} \frac{\phi\left(y_{\tau}(t)\right)}{\phi(y(t))}=1
$$

Thus, for any $\varepsilon$ with $0<\varepsilon<1$, there is a $t_{\varepsilon} \geqq T_{1}$ such that

$$
\phi\left(y_{\tau}(t)\right) \geqq(1-\varepsilon) \phi(y(t)), \quad t \geqq t_{f}
$$

By Lemma 2, there is a $k_{0}>0$ and a $t_{0} \geqq T_{1}$ such that $y_{\tau}(t) \geqq k_{0} y(t)$ for $t \geqq t_{0}$. Thus, for $s \geqq T=\max \left\{t_{0}, t_{e}, 2 T_{1}\right\}$

$$
\begin{aligned}
s^{2 n} \frac{y \tau(s)}{y(s)} \frac{f\left[s, y_{\tau}(s)\right]}{\phi(y(s))} & \geqq k_{0}(1-\varepsilon) s^{2 n} \frac{f\left[s, y_{\tau}(s)\right]}{\phi(y(s))} \\
& \geqq k_{0}(1-\varepsilon) s^{2 n} f\left(s, C s^{i}\right)
\end{aligned}
$$

By Lemma 1 and a change of variables

$$
\begin{aligned}
& \int_{T_{1}}^{l} \frac{s^{2 k-1} y_{2 k}(s)}{y(s) \phi(y(s))} d s \geqq N_{2 k} \int_{T_{1}}^{l} \frac{y^{\prime}(s) d s}{y(s) \phi(y(s))} \\
& N_{2 k} \int_{y\left(T_{1}\right)}^{y(t)} \frac{d u}{u \phi(u)}
\end{aligned}
$$

We may now duplicate the rest of the arguments of the proof of Theorem 2 to obtain the following result.

Corollary 1. Let $f$ be nonlinear with strength coefficient $2 n+1-j$. Let the associated function $\phi$ satisfy $\phi^{\prime \prime}(u)<0$. Then (2) fulfills property $P_{0}$ if for all positive constants $C$

$$
\int^{\infty} t^{2 n} f\left(t, C t^{j}\right) d t=\infty
$$

Remark 1. If $\tau \equiv 0$, the ratio $y_{\tau}(t) / y(t)$ does not occur and the condition $\phi^{\prime \prime}(u)<0$ may be omitted.

Remark 2. When $r \equiv 1, \tau \equiv 0$ and $k \equiv 0$, Theorem 1 reduces to the sufficiency of Theorem 1 of Kiguradze (1962). Under the same conditions the conclusion of Theorem 2 is that (2) satisfies property $P_{0}$, that is, condition $A$; Theorem 2 then coincides with Theorem 3 of Kiguradze (1962). In view of Remark 1 , when $r \equiv 1, \tau \equiv 0$ and $j=0$, Theorem 3 reduces to the sufficiency of Theorem 5 of Kiguradze (1962).

Remark 3. When $r \equiv 1, \tau \equiv 0, k=n$, the conclusion of Theorem 2 is that any $C_{n}$-solution $y(t)$ of (2) must satisfy $\lim _{t \rightarrow x} y_{2 n}(t)=0$. This is not quite condition B since we have not shown that any positive solution of (2) has this property. If $r(t) \equiv 1$, property $P_{n}$ reduces to condition $B$. For suppose that $y(t)$ is any solution of (2) of type $C_{k}$, where $k<n$, then $D^{2 n-1} y(t)=y_{2 n-1}(t)<0$. We now invoke a lemma most recently stated in generalized form by Ladas (1971) which we adapt here as follows.

Lemma 3. Let $y$ be a positive solution of (2) on $\left[t_{0}, \infty\right)$ with $r \equiv 1$. Then

$$
\lim _{t \rightarrow \infty} D^{2 n} y(t)=\lim _{t \rightarrow \infty}(j-1)!\left(t-t_{0}\right)^{t-j} D^{2 n+1-j} y(t)
$$

where $j=1, \cdots, 2 n+1$.

Letting $j=2$, we note that $D^{2 n} y(t)>0$ so that $\lim _{t \rightarrow x} D^{2 n} y(t) \geqq 0$. On the other hand, $D^{2 n-1} y(t)<0$, which implies that the limit on the right-hand side is nonpositive and $\lim _{t \rightarrow \infty} D^{2 n} y(t)=0$.

When $r(t) \not \equiv 1$, the statement of this lemma is more complicated. We may, however, state a weak analogue.

Lemma $3^{\prime}$. Let $y(t)$ be a positive solution of (2) on $\left[t_{0}, \infty\right)$ with $j \geqq$ $2 n+1-i$. Then

$$
\lim _{t \rightarrow \infty} y_{2 n}(t)=\lim _{t \rightarrow \infty}(j-1)!\left(t-t_{0}\right)^{1-j} y_{2 n+1-j}(t)
$$

where $j=1, \cdots, 2 n+1-i$.
Now let $y$ be a $C_{k}$-solution of (2) on [ $T_{0}, \infty$ ) for $k=0, \cdots, n-1$. Then $y_{2 n-1}(t)<0$ for $t \geqq T_{0}$. We see then that if $i \leqq 2 n-1,2 n-i \geqq 1$ and $2 n-i+1 \geqq 2$. Thus, we may let $j=2$ in the statement of Lemma $3^{\prime}$ to obtain as before that $\lim _{t \rightarrow \infty} y_{2 n}(t)=0$. It follows that if $i \leqq 2 n-1$, the conclusion of Theorem 2 may be restated as: (2) fulfills condition B. Specifically, property $P_{n}$ and condition $B$ coincide for the equation

$$
D^{n+1}\left[r(t) D^{n} y(t)\right]+y_{\tau}(t) f\left[t, y_{\tau}(t)\right]=0, \quad n \geqq 1
$$

since $i=n \leqq 2 n-1$ if $n \geqq 1$. The same remark holds for

$$
D^{n}\left[r(t) D^{n+1} y(t)\right]+y_{\tau}(t) f\left[t, y_{\tau}(t)\right]=0, \quad n \geqq 2
$$

since $i=n+1 \leqq 2 n-1$ if $n \geqq 2$.
Remark 4. Use of the preliminary transformation $Y(t)=-y(t)$ will enable us to formulate criteria for the nonexistence of negative solutions $y$ of (2) for which $-y$ is of type $C_{k}(k=0, \cdots, n)$. Moreover, if (2) has property $P_{k}$, then there are no negative solutions $y$ such that $-y$ is of type $C_{r}$ ( $r=k+1, \cdots, n$ ) and any negative solution $y$ for which $-y$ is of type $C_{k}$ will satisfy $\lim _{t \rightarrow \infty} y_{2 k}(t)=0$.

## 3

In this section we consider the nonhomogeneous delay differential equation

$$
\begin{equation*}
D^{2 n+1-i}\left[r(t) D^{i} y(t)\right]+y_{\tau}(t) f\left[t, y_{\tau}(t)\right]=Q(t) \tag{18}
\end{equation*}
$$

Following the procedure introduced and used most effectively by Kartsatos and Manougian (to appear), we shall assume that $R$ is a solution of the ordinary differential equation

$$
\begin{equation*}
D^{2 n+1-i}\left[r(t) D^{i} R(t)\right]=Q(t) \tag{19}
\end{equation*}
$$

This permits the transformation of (18) to a homogeneous delay equation of order $2 n+1$ for which the methods of the previous sections may be applied. Let us assume that $y$ is a positive solution of (18) and let $u(t)=y(t)-R(t)$. Then

$$
\begin{aligned}
D^{2 n+1-i}\left[r(t) D^{i} u(t)\right] & =D^{2 n+1-i}\left[r(t) D^{i} y(t)\right]-D^{2 n+1-i}\left[r(t) D^{i} R(t)\right] \\
& =-y_{\tau}(t) f\left[t, y_{\tau}(t)\right]=-(u+R)_{\tau}(t) f\left[t,(u+R)_{\tau}(t)\right],
\end{aligned}
$$

so that $u$ is a solution of the homogeneous equation

$$
\begin{equation*}
D^{2 n+1-i}\left[r(t) D^{i} u(t)\right]+(u+R)_{\tau}(t) f\left[t,(u+R)_{\tau}(t)\right]=0 . \tag{20}
\end{equation*}
$$

Since $y(t)>0$ for $t \geqq T_{0},(u+R)_{\tau}(t)>0$ for $t \geqq T_{1}$ and $D^{2 n+1-i}\left[r(t) D^{i} u(t)\right]<0$ for $t \geqq T_{1}$, which implies that $u(t)$ is a nonoscillatory solution of (20). If $u(t)<0$, then we further transform the equation by letting $v(t)=-u(t)$. It follows that $v$ is a positive solution of

$$
\begin{equation*}
D^{2 n+1-i}\left[r(t) D^{i} v(t)\right]-(R-v)_{\tau}(t) f\left[t,(R-v)_{\tau}(t)\right]=0 \tag{21}
\end{equation*}
$$

DEFINITION 8. A positive solution $y$ of (18) is of type $C_{k}^{R}$ on $\left[T_{0}, \infty\right)$ for $k=0, \cdots, n$ if $u=y-R$ is a positive solution of (20) of type $C_{k}$ on $\left[T_{0}, \infty\right)$.

Definition 9. A positive solution y of (18) is of type $\hat{C}_{k}^{R}$ on $\left[T_{0}, \infty\right)$ for $k=0, \cdots, n-1$ if $v=R-y$ is a positive solution of (21) which for $t \geqq T_{0}$ satisfies

$$
v_{i}(t)>0, i=0, \cdots, 2 k+1 \text { and }(-1)^{i+1} v_{i}(t)>0, i=2 k+2, \cdots, 2 n
$$

It is of type $\hat{C}_{n}^{R}$ if $v_{i}(t)>0$ for $i=0, \cdots, 2 n$.
Definition 10. Equation (18) has property $P_{k}^{R}$ if, and only if, (20) has property $P_{k}$.

A positive solution of (18) is evidently of type $C_{k}^{R}(k=0, \cdots, n)$ or of type $\hat{C}_{k}^{R}(k=0, \cdots, n)$ for some $k$. We now formulate criteria under which (18) possesses property $P_{k}^{R}$.

Theorem 3. Let $R$ be a solution of (19). Any solution y of type $C_{k}^{R}$ will satisfy

$$
\begin{equation*}
\lim _{t \rightarrow \times}[y(t)-R(t)]_{2 k}=0 \tag{22}
\end{equation*}
$$

if for all positive constants $C$

$$
\begin{equation*}
\int^{\infty} t^{2 n-2 k}\left(R_{\tau}(t)+C t^{2 k}\right) f\left[t, R_{\tau}(t)+C t^{2 k}\right] d t=\infty \tag{23}
\end{equation*}
$$

Proof. Let $y$ be a solution of (18) of type $C_{k}^{R}$ on [ $\left.T_{0}, \infty\right)$. As in Theorem 1, we obtain

$$
\int^{t} s^{2 n-2 k} D y_{2 n}(s) d s+\int^{1} s^{2 n-2 k}(u+R)_{\tau}(s) f\left[s,(u+R)_{\tau}(s)\right] d s=0 .
$$

The first integral is handled as in Theorem 1. It remains to estimate the second integral. Since $u$ is of type $C_{k}$ on $\left[T_{0}, x\right)$, there are numbers $k_{11}>0, N_{2 k}>0$, $C>0$ such that

$$
u_{\tau}(t) \geqq k_{0} u(t) \geqq k_{0} N_{2 k}^{-1} t^{2 k} u_{2 k}(t) \geqq k_{0} N_{2 k}^{-1} C t^{2 k}
$$

provided we assume that $\lim _{t \rightarrow \times} u_{2 k}(t)=C>0$. The above inequalities will lead to the same contradiction as in the proof of Theorem 1.

Theorem 4. Suppose that $R$ is as in the hypothesis of Theorem 3 and that $\phi$ is a function satisfying $\phi(y)>0, \phi^{\prime}(y) \geqq 0$ and (9a). Equation (18) possesses property $P_{k}^{R}$ if in addition to (23) for all positive constants $C$

$$
\begin{equation*}
\int^{\infty} t^{2 n} f\left(t, R_{r}(t)+C t^{2 k}\right) s t / \phi(t)=x \tag{24}
\end{equation*}
$$

Proof. As in the proof of Theorem 2, we first show that

$$
\int^{\infty} t^{2 n} f\left(t, R_{r}(t)+C t^{2 k-1}\right) d t / \phi(t)=\infty, \quad k \geqq 1
$$

is sufficient to exclude solutions of type $C^{R}(s=k, \cdots, n)$. Then

$$
\int^{\infty} t^{2 n} f\left(t, R_{\tau}(t)+C t^{2 k+1}\right) d t / \phi(t)=x, \quad k \geqq 0
$$

and hence (24) will exclude solutions of (18) of type $C_{s}^{R}(s=k+1, \cdots, n)$. The details are left to the reader.

Remark 5. If $R(t)>0$, the condition of Theorem 3 may be replaced by

$$
\begin{equation*}
\int^{\infty} t^{2 n} f\left(t, C t^{2 k}\right) d t=\infty \tag{25}
\end{equation*}
$$

The same replacement in Theorem 4 may be made. Thus (25) will ensure that (18) has property $P_{k}^{R}$.

REmark 6. If $R$ is oscillatory or negative, there can be no solutions of (18) of type $\hat{C}_{k}^{R}$. The conclusion of Theorem 4 is thereby strengthened.

Remark 7. Use of the transformation $w_{k}(t)=y_{2 n}(t) y_{2 k-1}^{-1}(t)$ results in a stronger criterion for the nonexistence of $C_{k}^{R}$-solutions of (18) independent of the existence of an auxiliary function $\phi(t)$ satisfying the hypotheses of Theorem 4. Specifically, we may obtain:

Theorem 5. Let $R$ be a solution of (19) with $R(t)=0\left(t^{2 k-1-f}\right)$ for some $\varepsilon$ such that $0<\varepsilon<2 k-1$; (18) has no positive solutions of type $C_{s}^{R}$ ( $s=$ $k, \cdots, n)$ if for all positive constants $C$

$$
\int^{\infty} t^{2 k-1} f\left(t, R_{\tau}(t)+C t^{2 k-1}\right) d t=\infty
$$

Remark 8. As in Remark 4, the preliminary transformation $Y(t)=-y(t)$ will enable us to formulate analogous criteria for the nonexistence of certain negative solutions $y$ of (18) for which $-y$ is a positive $C_{k}^{-R}$-solution of the transformed non-homogeneous delay differential equation.

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California Polytechnic State University
San Luis Obispo
California 93407
U.S.A.

