# ON THE RANK NUMBERS OF AN ARC 

## J. TURGEON

0. Introduction. The $k$ th rank number, $\operatorname{rank}_{k} B$, of a differentiable arc $B$ in real projective $n$-space is the least upper bound of the number of osculating $k$-spaces of $B$ which meet an ( $n-k-1$ )-flat, $k=0,1, \ldots, n-1$. The number $\operatorname{rank}_{0} B$ is called the order of $B ;$ cf. 1.1-1.3. It has been conjectured by Peter Scherk that

$$
\begin{equation*}
\operatorname{rank}_{k} B \geqq(k+1)(n-k), \tag{0.1}
\end{equation*}
$$

equality holding if and only if $B$ has the order $n$; cf. [2, p. 396]. In this paper we prove the following results.

Theorem 1. If $B$ is a differentiable elementary arc, then (0.1) holds for $k=0,1, \ldots, n-1$.

Theorem 2. If $B$ is a differentiable elementary arc and order $B>n$, then $\operatorname{rank}_{k} B>(k+1)(n-k)$ for $k=1, \ldots, n-2$.

By a theorem of Park [3, p. 38], every differentiable arc contains a subarc of order $n$. This eliminates the assumption that $B$ is elementary from Theorem 1. We do not know whether it can be dropped from Theorem 2.

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1. Prerequisites. We first list some definitions and known results which will be used throughout the paper. Unless otherwise stated, they are quoted from [4].
1.1. We consider arcs in real projective $n$-space $R_{n}$. An $\operatorname{arc} B$ is the continuous image of an open interval. Thus the points of $B$ depend continuously on a real parameter $s$. The point corresponding to the parameter $s$ will also be denoted by $s$.

The image of a neighbourhood of the parameter $s$ on the parameter interval is a neighbourhood of the point $s$ on $B$. If a sequence of parameter values converges to the parameter $s$, we say that the corresponding sequence of points on $B$ also converges to the point $s$.

[^0]1.2. The order of $B$ is the least upper bound of the number of points that $B$ can have in common with any hyperplane in $R_{n}$. Clearly, the order of $B$ is not less than $n$. An arc of order $n$ has end points.

An arc is elementary if it is the finite union of arcs of order $n$ and of their end points.

The order of a point $s$ on $B$ is defined to be the order of a sufficiently small neighbourhood of $s$ on $B$. A point $s$ is called regular if it has order $n$. An elementary arc has only finitely many singular, i.e., non-regular, points. An arc is regular if all its points are regular.
1.3. We call a point $s$ of $B$ differentiable if all the linear osculating spaces $L_{k}{ }^{n}(s)$ exist, $k=-1,0,1, \ldots, n$. We construct them inductively. Define $L_{-1}{ }^{n}(s)=\emptyset$. Suppose that we have defined the osculating $k$-space $L_{k}{ }^{n}(s)$ and postulated its existence. Then we postulate that:
(i) if $t \neq s$ is a point of $B$ sufficiently close to $s$, then $t L_{k}{ }^{n}(s)$ is a $(k+1)$-space (here, $t L_{k}{ }^{n}(s)$ denotes the linear subspace spanned by $t$ and $L_{k}{ }^{n}(s)$; a similar notation will be used throughout).
(ii) this $(k+1)$-space converges as $t \rightarrow s$. Then we define

$$
L_{k+1}{ }^{n}(s)=\lim _{t \rightarrow s} t L_{k}^{n}(s) .
$$

Thus $L_{0}{ }^{n}(s)$ is the point $s$ itself. We call $L_{n-1}{ }^{n}(s)$ the osculating hyperplane of $B$ at $s$. If a hyperplane contains $L_{k}{ }^{n}(s)$ but not $L_{k+1}{ }^{n}(s)$, we say that it contains $L_{k}{ }^{n}(s)$ exactly, $-1 \leqq k \leqq n-2$.

We say that $B$ is differentiable if each of its points is differentiable.
1.4. Let $\varphi$ denote the projection of $R_{n}$ from a point $P$.
(a) If $B$ is differentiable in $R_{n}$, then $\varphi B$ is differentiable in $R_{n-1}$.
(b) If $B$ has order $n$ and $P \in B$, then $\varphi B$ has order $n-1$.
(c) If $B$ has order $n$ and $P$ is an arbitrary point in space, then $\varphi B$ is an arc of order $n$ or $n-1$. By a theorem of Haupt, every differentiable arc of order $n$ in $R_{n-1}$ is elementary; cf. [2, p. 249]. Hence, the projection of an elementary arc is also elementary.
(d) If $B$ is regular and $P$ does not lie on any osculating hyperplane of $B$, then $\varphi B$ is regular.

From now on, "arc" means "differentiable elementary arc".
1.5. A duality maps the family of the osculating $k$-spaces of an $\operatorname{arc} B$ into a family of $(n-k-1)$-spaces $M_{n-k-1}^{n}(s)$ in the dual $n$-space. In particular, the osculating hyperplanes of $B$ are mapped onto a family $C$ of points. This family $C$ is an arc and $M_{n-k-1}^{n}(s)$ is the osculating ( $n-k-1$ )-space of $C$ at $s, k=0,1, \ldots, n-1$.
1.6. Let $B$ be an arc of order $n ; s \in B$. If a hyperplane contains $L_{k}{ }^{n}(s)$ exactly, count $s$ with the multiplicity $k+1$ as a point of contact of $B$ with this hyperplane. Then the sum of the multiplicities of the points of contact of $B$ with a hyperplane is at most $n$.

Dually, if a point $P$ lies on $L_{n-k}{ }^{n}(s)$ but not on $L_{n-k-1}^{n}(s)$, count $L_{n-1}{ }^{n}(s)$ as passing through $P$ with the multiplicity $k$. Then the sum of the multiplicities with which the osculating hyperplanes pass through $P$ is at most $n$.

These statements remain valid if one but not both end points are added to $B$.
1.7. The class of any $\operatorname{arc} B$ is the least upper bound of the number of osculating hyperplanes of $B$ passing through a point $P$ in $R_{n}$. The statements of 1.6 imply that $B$ has order $n$ if and only if it has class $n$.
1.8. If $k+1$ points of an $\operatorname{arc} B$ of order $n$ converge to a point $s$ of $B$, then the $k$-space spanned by them converges to $L_{k}{ }^{n}(s)$ and, by duality, the intersection of their osculating hyperplanes is an ( $n-k-1$ )-space which converges to $L_{n-k-1}^{n}(s)$ (strong differentiability and strong dual differentiability).

These statements also hold if we take into account the multiplicities described in 1.6. For instance, if $s_{1}$ and $s_{2}$ converge to $s$ and $0 \leqq j \leqq k-1$, $s_{1} \neq s_{2}$, then the $k$-space $L_{j}{ }^{n}\left(s_{1}\right) L_{k-j-1}^{n}\left(s_{2}\right)$ converges to $L_{k}{ }^{n}(s)$.

In particular, if all the $k+1$ points are identified, i.e. if one point is counted with the multiplicity $k+1$, we obtain the statement that the osculating spaces $L_{k}{ }^{n}(s)$ of an arc of order $n$ vary continuously with $s$. Clearly, this last property extends to all our elementary arcs.
1.9. Dualizing the projection of the dual of $B$, we obtain the dual projection $\varphi^{*}$ of $B$. Then $\varphi^{*} B$ is an arc in $E=R_{n-1}$ whose points are given by

$$
\varphi^{*}(s)= \begin{cases}s & \text { if } L_{1}{ }^{n}(s) \subset E \\ E \cap L_{1}{ }^{n}(s) & \text { otherwise }\end{cases}
$$

This dual projection has the following properties; cf. 1.4.
(a) If $B$ has order $n$ and $E$ is an osculating hyperplane of $B$, then $\varphi^{*} B$ has order $n-1$.
(b) If $B$ has order $n$ and $E$ is an arbitrary hyperplane, then $\varphi^{*} B$ is an arc of order $n$ or $n-1$.
(c) If $B$ is regular and $E$ does not meet $B$, then $\varphi^{*} B$ is regular.

## 2. Lower bounds for the rank numbers.

2.1. Lemma. Let $B$ be a regular arc in $R_{n}, s_{0} \in B$. Let $l$ be a straight line which is not contained in any osculating hyperplane of $B$. Consider the mapping

$$
\tau(s)=l \cap L_{n-1}^{n}(s)
$$

of $B$ into $l$. If $\tau(s)$ changes its direction at $s_{0}$, then

$$
\tau\left(s_{0}\right)=l \cap L_{n-2}^{n}\left(s_{0}\right)
$$

Proof. Since $B$ is elementary and regular, every point of $B$ is strongly differentiable and strongly dually differentiable.

The arc $\tau(B)$ on $l$ may be considered as the result of repeated dual projections. Hence $\tau(B)$ is elementary and $\tau(s)$ changes its direction only finitely many times.

Since $\tau(s)$ changes its direction at $s_{0}$, there are sequences $s_{i}$ and $s_{i}{ }^{\prime}$, both converging monotonically to $s_{0}$, such that $s_{0}$ lies between $s_{i}$ and $s_{i}{ }^{\prime}$ on $B$, for every $i$, and

$$
\tau\left(s_{i}\right)=\tau\left(s_{i}^{\prime}\right)=\tau_{i},
$$

say. Thus

$$
\tau_{i} \in L_{n-1}^{n}\left(s_{i}\right) \cap L_{n-1}^{n}\left(s_{i}^{\prime}\right) \cap l
$$

Let $i \rightarrow \infty$. Then

$$
L_{n-1}{ }^{n}\left(s_{i}\right) \cap L_{n-1}{ }^{n}\left(s_{i}{ }^{\prime}\right) \rightarrow L_{n-2}{ }^{n}\left(s_{0}\right),
$$

by the strong dual differentiability of $s_{0}$. Hence

$$
\tau_{i} \rightarrow \tau\left(s_{0}\right)=L_{n-2}^{n}\left(s_{0}\right) \cap l
$$

2.2. The following lemma is a slight generalization of a result due to Derry [1, p. 161].

Lemma. Let $B$ be a regular arc in $R_{n}$. Let $P$ be a point of $R_{n}$ lying on $k$ osculating hyperplanes of $B$, say

$$
P \in L_{n-1}^{n}\left(s_{1}\right) \cap \ldots \cap L_{n-1}^{n}\left(s_{k}\right),
$$

where $s_{1}<s_{2}<\ldots<s_{k}$. If $Q$ is a point of $R_{n}$ which does not lie on any osculating hyperplane of $B$, and $\varphi$ is the projection of $R_{n}$ from $Q$, then $\varphi P$ lies on at least $k-1$ osculating hyperplanes of $\varphi B$, say

$$
\varphi P \in L_{n-2}^{n-1}\left(t_{1}\right) \cap \ldots \cap L_{n-2}^{n-1}\left(t_{k-1}\right)
$$

where

$$
s_{1}<t_{1}<s_{2}<\ldots<t_{k-1}<s_{k}
$$

Proof. Since $Q$ does not lie on any osculating hyperplane of $B$, the intersection

$$
\tau(s)=P Q \cap L_{n-1}{ }^{n}(s)
$$

is uniquely defined for all $s \in B$. Since

$$
\tau\left(s_{i}\right)=\tau\left(s_{i+1}\right)=P
$$

for $i=1, \ldots, k-1$ and $\tau(s)$ is always distinct from $Q$, there exists at least one point $t_{i}$ on $B$ with $s_{i}<t_{i}<s_{i+1}$, where $\tau(s)$ changes its direction. By 2.1,

$$
P Q \cap L_{n-2}{ }^{n}\left(t_{i}\right) \neq \emptyset .
$$

The statement follows.
2.3. Lemma. For a fixed value of $k, 0 \leqq k \leqq n-2$, let $B_{1}, \ldots, B_{n-k}$ be regular arcs in $R_{n}$ and let $P_{1}, \ldots, P_{n-k}$ be points of $R_{n}$ such that
(i) $P_{1}, \ldots, P_{n-k}$ are independent, i.e.,

$$
\operatorname{dim}\left(P_{1} \ldots P_{n-k}\right)=n-k-1
$$

(ii) $P_{i}$ lies on $n$ osculating hyperplanes of $B_{i}$,
(iii) for all $h$ with $1 \leqq h \leqq n-k-1$ and every $t_{j} \in B_{j}$,

$$
\operatorname{dim}\left(L_{n-h}^{n}\left(t_{j_{0}}\right) P_{j_{1}} \ldots P_{j_{h}}\right)=n
$$

for every choice of the $(h+1)$-tuple $j_{0}, \ldots, j_{n}$ from $1, \ldots, n-k$. Then $P_{1} \ldots P_{n-k}$ meets the osculating $k$-spaces of $k+1$ points of each of $B_{1}, \ldots, B_{n-k}$.

Proof. For $i=1, \ldots, n-k$, let $\varphi_{i}$ be the projection of $R_{n}$ from $P_{i}$. Then, by property (iii) and 1.4 (d), $\varphi_{h} \varphi_{h-1} \ldots \varphi_{3} \varphi_{2} B_{1}$ is a regular arc in $R_{n-(h-1)}$ and $\varphi_{h} \ldots \varphi_{2} P_{h+1}$ does not lie on any osculating hyperplane of $\varphi_{h} \ldots \varphi_{2} B_{1}$, $1 \leqq h \leqq n-k-2$ (for $h=1$, the $\varphi$ s do not appear). Hence by $2.2, \varphi_{2} P_{1}$ lies on $n-1$ osculating hyperplanes of $\varphi_{2} B_{1}, \varphi_{3} \varphi_{2} P_{1}$ lies on $n-2$ osculating hyperplanes of $\varphi_{3} \varphi_{2} B_{1}$, and, in general, $\varphi_{h+1} \ldots \varphi_{2} P_{1}$ lies on $n-h$ osculating hyperplanes of $\varphi_{h+1} \ldots \varphi_{2} B_{1}, h=1, \ldots, n-k-1$. Thus $\varphi_{n-k} \ldots \varphi_{2} P_{1}$ lies on $k+1$ osculating hyperplanes of $\varphi_{n-k} \ldots \varphi_{2} B_{1}$. But this means that $P_{1} \ldots P_{n-k}$ meets $k+1$ osculating $k$-spaces of $B_{1}$. Symmetrically, it meets $k+1$ osculating $k$-spaces of each of $B_{2}, \ldots, B_{n-k}$.
2.4. Lemma. Let $0 \leqq k \leqq n-2$. Suppose that $s_{1}, \ldots, s_{n-k}$ are regular points of $B$ with the following properties:

$$
\begin{equation*}
s_{1}, \ldots, s_{n-k} \text { are independent } \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{dim}\left(L_{n-h}^{n}\left(s_{j_{0}}\right) s_{j_{1}} \ldots s_{j_{h}}\right)=n \quad(h=1, \ldots, n-k-1) \tag{2.2}
\end{equation*}
$$

for every choice of the $(h+1)$-tuple $j_{0}, \ldots, j_{n}$ from $1, \ldots, n-k$. Then for $i=1, \ldots, n-k$, there exists a closed neighbourhood $N_{i}$ of $s_{i}$ in $R_{n}$ containing $s_{i}$ in its interior and such that, if $P_{i}$ is any point of $N_{i}$ and $t_{i}$ is any point of a neighbourhood $B_{i}$ of $s_{i}$ on $B, B_{i} \subset N_{i}$, then

$$
\begin{equation*}
P_{1}, \ldots, P_{n-k} \text { are independent } \tag{2.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{dim}\left(L_{n-n}^{n}\left(t_{j_{0}}\right) P_{j_{1}} \ldots P_{j_{h}}\right)=n \quad(h=1, \ldots, n-k-1) \tag{2.4}
\end{equation*}
$$

for every choice of the $(h+1)$-tuple $j_{0}, \ldots, j_{n}$ from $1, \ldots, n-k$.
Proof. Suppose (2.4) were false. Then there would exist an $(h+1)$-tuple of indices $j_{0}, \ldots, j_{h}$ from $1, \ldots, n-k$ and a sequence of $(h+1)$-tuples

$$
t_{j_{0}}{ }^{\lambda}, P_{j_{1}}{ }^{\lambda}, \ldots, P_{j h}^{\lambda}, \quad \lambda=1,2, \ldots,
$$

such that

$$
\begin{equation*}
\lim t_{j_{0}}^{\lambda}=s_{j_{0}}, \lim P_{j_{1}}^{\lambda}=s_{j_{1}}, \ldots, \lim P_{j_{h}}^{\lambda}=s_{j_{h}} \tag{2.5}
\end{equation*}
$$

and that

$$
L_{n-h}{ }^{n}\left(t_{j 0}{ }^{\lambda}\right), P_{j_{1}}{ }^{\lambda}, \ldots, P_{j h}^{\lambda}
$$

lie in a hyperplane $E^{\lambda}$. We may assume that the $E^{\lambda}$ converge to a hyperplane $E$. Since $L_{n-h}{ }^{n}(s)$ is continuous, (2.5) implies that

$$
L_{n-h^{n}}\left(s_{j_{0}}\right), s_{j_{1}}, \ldots, s_{j_{h}}
$$

lie in $E$, contradicting (2.2).

The proof of (2.3) is even simpler.
2.5. Proof of Theorem 1. Without loss of generality, we may assume that $n \geqq 3,1 \leqq k \leqq n-2$, and that $B$ has order $n$.

Let $s_{1}, \ldots, s_{n-k}$ be any $n-k$ points of $B$. By 1.6 , they satisfy conditions (2.1) and (2.2). Hence there exist closed neighbourhoods $N_{1}, \ldots, N_{n-k}$ with the properties (2.3) and (2.4).

Let $P_{i}$ be a point of $N_{i}$ lying on $n$ osculating hyperplanes of a neighbourhood $B_{i}$ of $s_{i}$ on $B, B_{i} \subset N_{i}, i=1, \ldots, n-k$. Such points always exist by the strong dual differentiability of $B$; cf. 1.8. Then the points $P_{i}$ and the subarcs $B_{i}$ satisfy the assumptions of 2.3 . Therefore the $(n-k-1)$-flat $P_{1} \ldots P_{n-k}$ meets the osculating $k$-spaces of at least $k+1$ points of each of $B_{1}, \ldots, B_{n-k}$, i.e., altogether it meets at least $(k+1)(n-k)$ osculating $k$-spaces of $B$.

## 3. Two lemmas.

3.1. Lemma. Let $B$ be an arc of order greater than $n$ in $R_{n}$. Let $\Sigma^{n}$ be any finite set of points of $B$ containing all the singular points of $B$. Then there exist a hyperplane $E$ and $n+1$ points $s_{1}, \ldots, s_{n+1}$ of $B$ such that
$(1)_{n}$ :

$$
E \cap \Sigma^{n}=\emptyset
$$

$(2)_{n}:$
E contains $s_{1}, \ldots, s_{n+1}$ exactly,
(3) ${ }_{n}$ :

$$
s_{1}, \ldots, s_{n} \text { span } E \text {, }
$$

(4) ${ }_{n}$ :

$$
s_{1}, \ldots, s_{n-1}, s_{n+1} \text { span } E
$$

(5) $)_{n}: \quad \operatorname{dim}\left(L_{n-h}^{n}\left(s_{j_{0}}\right) s_{j_{1}} \ldots s_{j_{h}}\right)=n \quad(h=1, \ldots, n-3)$,
for every choice of the $(h+1)$-tuple $j_{0}, \ldots, j_{n}$ from $1, \ldots, n-2$.
Note that the parameters $s_{n}$ and $s_{n+1}$ are distinct, but that the corresponding points in $R_{n}$ may coincide.

Proof. We note that $(5)_{n}$ is void for $n \leqq 3$.
The case $n=1$ is trivial. Suppose that the statement is true up to $n-1$.
Some hyperplane meets $B$ in more than $n$ points. We may assume that these points span the hyperplane. Hence at least one of them, say $s_{0}$, has the property that the projection $\varphi_{0} B$ of $B$ from $s_{0}$ has order $>n-1$. With $B, \varphi_{0} B$ is an elementary arc ; cf. 1.4(c).

Let $\Sigma_{0}{ }^{n}$ be the union of $\Sigma^{n}$ with $s_{0}$ and all the points of $B$ which coincide with $s_{0}$.

Let $\Sigma_{0}{ }^{n-1}$ be the set consisting of $\varphi_{0} \Sigma_{0}{ }^{n}$, the points of $\varphi_{0} B$ coinciding with points of $\varphi_{0} \Sigma_{0}{ }^{n}$, and the singular points of $\varphi_{0} B$.

By our induction hypothesis, there exists a hyperplane $E_{0}$ through $s_{0}$ and through $n$ points $s_{01}, \ldots, s_{0 n}$ of $B$ such that
(1) $n_{n-1}: \quad \varphi_{0} E_{0} \cap \Sigma_{0}{ }^{n-1}=\emptyset$, and thus $\left\{s_{01}, \ldots, s_{0 n}\right\} \cap \Sigma_{0}{ }^{n}=\emptyset$,
$(3)_{n-1}: \quad \varphi_{0} S_{01}, \ldots, \varphi_{0} S_{0, n-1} \quad \operatorname{span} \varphi_{0} E_{0}$,
$(4)_{n-1}: \quad \varphi_{0} S_{01}, \ldots, \varphi_{0} s_{0, n-2}, \varphi_{0} S_{0 n} \quad$ span $\varphi_{0} E_{0}$.
Hence, except possibly for the pair $s_{0, n-1}, s_{0 n}$, no two of the points $s_{01}, \ldots, s_{0, n-1}, s_{0 n}$ can coincide.

If $n=2$ and $s_{01}$ and $s_{02}$ coincide, put $s_{2}=s_{01}$ and $s_{3}=s_{02}$. Each of the conditions
(i) $s_{1} \notin L_{1}{ }^{2}\left(s_{2}\right) \cup L_{1}{ }^{2}\left(s_{3}\right)$,
(ii) $s_{2} \notin L_{1}{ }^{2}\left(s_{1}\right)$,
(iii) $s_{1} s_{2} \cap \Sigma^{2}=\emptyset$
excludes only a finite number of points. Hence there is a point $s_{1}$ satisfying all three of them. Then $s_{1}, s_{2}$, and $s_{3}$ satisfy our requirements.

If $n=2$ and $s_{01}$ and $s_{02}$ do not coincide or if $n>2$, then we put $s_{1}=s_{01}$. Then $s_{1}$ does not coincide with any of $s_{02}, \ldots, s_{0 n}$, so that $s_{1}$ has the following properties:
(a) $1_{1}: s_{1} \notin \Sigma^{n}$,
(b) 1 : if $\varphi_{1}$ is the projection from $s_{1}$, then order $\varphi_{1} B>n-1$, since $E_{0}$ meets $B$ in $s_{0}, s_{1}, s_{02}, \ldots, s_{0 n}$.

Define

$$
\Sigma_{1}{ }^{n}=\Sigma^{n} \cup\left\{s \in B \mid s \in L_{n-1}{ }^{n}\left(s_{1}\right)\right\} \cup\left\{s \in B \mid s_{1} \in L_{n-1}{ }^{n}(s)\right\} .
$$

Let $\Sigma^{n-1}$ consist of $\varphi_{1} \Sigma_{1}{ }^{n}$ and all the points of $\varphi_{1} B$ coinciding with any point of $\varphi_{1} \Sigma_{1}{ }^{n}$. Then $\varphi_{1} s_{1} \in \Sigma^{n-1}$ since $s_{1} \in L_{n-1}{ }^{n}\left(s_{1}\right)$.

By the induction assumption, there exists a hyperplane $E_{1}$ through $s_{1}$ and through $n$ points $s_{12}, \ldots, s_{1, n+1}$ on $B$ such that
(1) $n_{n-1}: \varphi_{1} E_{1} \cap \Sigma^{n-1}=\emptyset$, and thus $\left\{s_{12}, \ldots, s_{1, n+1}\right\} \cap \Sigma_{1}{ }^{n}=\emptyset$,
(3) $)_{n-1}$ :
$\varphi_{1} s_{12}, \ldots, \varphi_{1} s_{1 n} \operatorname{span} \varphi_{1} E_{1}$,
(4) $)_{n-1}: \quad \varphi_{1} s_{12}, \ldots, \varphi_{1} s_{1, n-1}, \varphi_{1} s_{1, n+1} \operatorname{span} \varphi_{1} E_{1}$.

If $n=2$, then by the definition of $\Sigma^{n-1}, E=s_{1} s_{12} s_{13}$ has the required properties. From now on we may assume that $n \geqq 3$.

Except perhaps for the pair $s_{1 n}, s_{1, n+1}$, no two of the points $s_{1}, s_{12}, \ldots, s_{1, n+1}$ coincide. Put $s_{2}=s_{12}$. Then the points $s_{1}, s_{2}$ have the following properties:
(a) ${ }_{2}$ :
$s_{1} s_{2} \cap \Sigma^{n}=\emptyset$,
(b) 2 :
if $\varphi_{i}$ is the projection from $s_{i}$,
$i=1,2$, then order $\varphi_{i} B>n-1$ and order $\varphi_{2} \varphi_{1} B>n-2$,
(c) ${ }_{2}$ :

$$
\operatorname{dim}\left(s_{1} s_{2}\right)=1
$$

(d) $)_{2}: \quad \operatorname{dim}\left(L_{n-1}{ }^{n}\left(s_{j_{0}}\right) s_{j_{1}}\right)=n$ for any permutation $j_{0}, j_{1}$ of $1,2$.

Now suppose that we have $k$ points $s_{1}, \ldots, s_{k}$ for some fixed $k$, $2 \leqq k \leqq n-3$, such that
$(\mathrm{a})_{k}: \quad s_{1} \ldots s_{k} \cap \Sigma^{n}=\emptyset$,
(b) ${ }_{k}: \quad$ if $\varphi_{i}$ is the projection from $s_{i}(i=1, \ldots, k)$, then order $\varphi_{j_{h}} \ldots \varphi_{j_{1}} B>n-h \quad(h=1, \ldots, k)$, where $j_{1}, \ldots, j_{h}$ is any $h$-tuple from $1, \ldots, k$,
(c) ${ }_{k}$ :

$$
\operatorname{dim}\left(s_{1} \ldots s_{k}\right)=k-1
$$

(d) $)_{k}: \operatorname{dim}\left(L_{n-h}{ }^{n}\left(s_{j_{0}}\right) s_{j_{1}} \ldots s_{j_{h}}\right)=n$ for any $(h+1)$-tuple $j_{0}, \ldots, j_{h}$ from $1, \ldots, k(h=1, \ldots, k-1)$.
Define

$$
\begin{aligned}
& \Sigma_{k}{ }^{n}=\Sigma^{n} \cup\left\{s \in B \mid \operatorname{dim}\left(s s_{1} \ldots s_{k}\right)<k\right\} \\
& \cup\left\{s \in B \mid \operatorname{dim}\left(L_{n-h}{ }^{n}\left(s_{j_{0}}\right) s_{j_{1}} \ldots s_{j_{h}}\right)<n\right. \\
& \quad \text { for some } h, 1 \leqq h \leqq k, \text { and some }(h+1) \text {-tuple }
\end{aligned}
$$

$$
\left.s_{j_{0}}, \ldots, s_{j h} \text { from } s, s_{1}, \ldots, s_{k}\right\} .
$$

Put $\Psi_{k}=\varphi_{k} \ldots \varphi_{1}$. Let $\Sigma^{n-k}$ consist of $\Psi_{k} \Sigma_{k}{ }^{n}$ and all the points of $\Psi_{k} B$ coinciding with any point of $\Psi_{k} \Sigma_{k}{ }^{n}$. Then $\Psi_{k} s_{i} \in \Sigma^{n-k}$ since $s_{i} \in L_{n-k-1}^{n}\left(s_{i}\right)$, $i=1, \ldots, k$.

Again by our induction hypothesis, there exists a hyperplane $E_{k}$ through $s_{1}, \ldots, s_{k}$ and through $n-k+1$ points $s_{k, k+1}, \ldots, s_{k, n+1}$ on $B$ such that
(1) $)_{n-k}: \quad \Psi_{k} E_{k} \cap \Sigma^{n-k}=\emptyset$, and thus $\left\{s_{k, k+1}, \ldots, s_{k, n+1}\right\} \cap \Sigma_{k}{ }^{n}=\emptyset$,
(3) $)_{n-k}: \quad \Psi_{k} s_{k, k+1}, \ldots, \Psi_{k} s_{k n} \quad \operatorname{span} \Psi_{k} E_{k}$,
(4) $)_{n-k}: \quad \Psi_{k} s_{k, k+1}, \ldots, \Psi_{k} s_{k, n-1}, \Psi_{k} s_{k, n+1} \quad \operatorname{span} \Psi_{k} E_{k}$.

In particular, no two of the points $s_{k, k+1}, \ldots, s_{k, n+1}$ coincide, except possibly for the pair $s_{k, n}, s_{k, n+1}$. Put $s_{k+1}=s_{k, k+1}$. Then the points $s_{1}, \ldots, s_{k+1}$ have the properties $(\mathrm{a})_{k+1},(\mathrm{~b})_{k+1},(\mathrm{c})_{k+1}$, and $(\mathrm{d})_{k+1}$. We have thus proved by induction the existence of $n-2$ points $s_{1}, \ldots, s_{n-2}$ with the corresponding properties (a) $)_{n-2}, \ldots,(\mathrm{~d})_{n-2}$.

We now define

$$
\begin{aligned}
\Sigma_{n-2}{ }^{n}=\Sigma^{n} & \cup\left\{s \in B \mid \operatorname{dim}\left(s s_{1} \ldots s_{n-2}\right)<n-2\right\} \\
& \cup\left\{s \in B \mid \operatorname{dim}\left(L_{1}{ }^{n}(s) s_{1} \ldots s_{i-1} L_{1}{ }^{n}\left(s_{i}\right) s_{i+1} \ldots s_{n-2}\right)<n\right.
\end{aligned}
$$

for some $i, 1 \leqq i \leqq n-2\}$.
Put $\Psi=\varphi_{n-2} \ldots \varphi_{1}$. Let $\Sigma^{2}$ consist of $\Psi \Sigma_{n-2}{ }^{n}$ and all the points of $\Psi B$ coinciding with some point of $\Psi \Sigma_{n-2}{ }^{n}$. Then $\Psi s_{i} \in \Sigma^{2}$ since $s_{i} \in L_{1}{ }^{n}\left(s_{i}\right)$, $i=1, \ldots, n-2$.

Since $\Psi B$ has order $>2$ (by property (b) $)_{n-2}$ ), there is a hyperplane $E$ through $s_{1}, \ldots, s_{n-2}$ and through three points $s_{n-1}, s_{n}, s_{n+1}$ of $B$ such that
$(1)_{2}: \quad \Psi E \cap \Sigma^{2}=\emptyset$, and thus $\left\{s_{n-1}, s_{n}, s_{n+1}\right\} \cap \Sigma_{n-2}{ }^{n}=\emptyset$,
$(2)_{2}: \quad \Psi E$ contains $\Psi s_{n-1}, \Psi s_{n}, \Psi s_{n+1}$ exactly,
$(3)_{2}: \quad \Psi s_{n-1}, \Psi s_{n}$ span $\Psi E$,
$(4)_{2}$ :
$\Psi s_{n-1}, \Psi s_{n+1}$ span $\Psi E$.
We can now verify that $s_{1}, \ldots, s_{n+1}$ possess the properties $(1)_{n}, \ldots,(5)_{n}$.
Verification of $(1)_{n}$. If $s$ lies on $s_{1} \ldots s_{n-2}$, then $s \notin \Sigma^{n}$, by (a) $)_{n-2}$. Hence, if $s \in E \cap \Sigma^{n}$, then $s \notin s_{1} \ldots s_{n-2}$ and

$$
\Psi s \in \Psi\left(E \cap \Sigma^{n}\right) \subset \Psi E \cap \Sigma^{2}=\emptyset
$$

a contradiction.
To verify $(2)_{n}$, first let $1 \leqq i \leqq n-2$. Since $\Psi s_{i} \in \Sigma^{2}$, we have $\Psi s_{i} \notin \Psi E$, by (1) $)_{2}$. Hence $L_{1}{ }^{n}\left(s_{i}\right) \not \subset E$ and $E$ contains $s_{i}$ exactly.

If $n-1 \leqq i \leqq n+1$, then $\Psi s_{i} \in \Psi E$. Thus $\Psi s_{i} \notin \Sigma^{2}$, by ( 1$)_{2}$, and $s_{i} \notin s_{1} \ldots s_{n-2}$. By $(2)_{2}, L_{1}{ }^{2}\left(\Psi s_{i}\right) \not \subset \Psi E$. By the definition of $\Sigma_{n-2}{ }^{n}$,

$$
\operatorname{dim}\left(L_{1}{ }^{n}\left(s_{i}\right) s_{1} \ldots s_{n-2}\right)=n-1
$$

Hence $L_{1}{ }^{n}\left(s_{i}\right) \not \subset E$.
Verification of $\quad(3)_{n} . \quad$ By $\quad(\mathrm{c})_{n-2}, \quad \operatorname{dim}\left(s_{1} \ldots s_{n-2}\right)=n-3 . \quad$ Hence $\operatorname{dim} \Psi E=1$. Let $s_{1}, \ldots, s_{n}$ span the subspace $F$ of $E$. Since

$$
s_{n-1}, s_{n}, s_{n+1} \notin s_{1} \ldots s_{n-2}
$$

and $\Psi s_{n-1}, \Psi s_{n}$ span $\Psi E$, we have $\Psi F=\Psi E$. Hence $\operatorname{dim} \Psi F=1$, $\operatorname{dim}$ $F=n-1$ and $F=E$.

As for $(4)_{n}$, clearly, we can replace $s_{n}$ by $s_{n+1}$ and (3) $)_{2}$ by (4) $)_{2}$ in the verification of (3) $)_{n}$ to obtain (4) $n$.

Finally, the property $(\mathrm{d})_{n-2}$ of $s_{1}, \ldots, s_{n-2}$ yields $(5)_{n}$.
This completes the proof of 3.1.
3.2. Lemma. Let $B$ be an arc of order $n$ in $R_{n}$. Let $s_{0} \in B$ and

$$
P_{0} \in L_{n-1}{ }^{n}\left(s_{0}\right) \backslash L_{n-2}{ }^{n}\left(s_{0}\right) .
$$

Then there exist an open neighbourhood $O$ of $P_{0}{ }^{\text {r }}$ in $R_{n}$ and a closed neighbourhood $B_{0}$ of $s_{0}$ on $B$ such that, if $P$ is any point in $O$, then

$$
\begin{equation*}
P \in L_{n-1}{ }^{n}(s) \backslash L_{n-2}^{n}(s) \tag{3.1}
\end{equation*}
$$

for some $s \in B_{0}$.

Proof. Since $P_{0}$ lies on at most $n$ osculating hyperplanes of $B$, we can find a closed neighbourhood $B_{0}$ of $s_{0}$ on $B$, with endpoints, say, $s_{1}$ and $s_{2}$, such that $P_{0} \notin L_{n-1}{ }^{n}(s)$ for all $s \in B_{0}, s \neq s_{0}$. Let

$$
\Sigma=L_{n-1}^{n}\left(s_{1}\right) \cup L_{n-1}^{n}\left(s_{2}\right) \cup \bigcup_{s \in B_{0}} L_{n-2}^{n}(s) .
$$

Suppose that there is no neighbourhood of $P_{0}$ with the desired property. Then there exists a sequence $P_{1}, P_{2}, \ldots$ of points converging to $P_{0}$ for which (3.1) does not hold. Since $\Sigma$ is closed and $P_{0} \notin \Sigma$, we may assume that no point of the sequence $P_{1}, P_{2}, \ldots$ is in $\Sigma$. Thus

$$
\begin{equation*}
P_{i} \notin L_{n-1}^{n}(s) \quad \text { for all } s \in B_{0}, \quad i=1,2, \ldots \tag{3.2}
\end{equation*}
$$

Let $l_{i}=P_{0} P_{i}$ and

$$
\begin{equation*}
\tau_{i}(s)=l_{i} \cap L_{n-1}^{n}(s), \quad s \in B_{0} \tag{3.3}
\end{equation*}
$$

Since $R_{n}$ is compact and $\tau_{i}(s)$ is continuous, $\tau_{i}\left(B_{0}\right)$ is a closed segment on $l_{i}$ containing $P_{0}$. By 2.1, the end points of $\tau_{i}\left(B_{0}\right)$ are points of $\Sigma$. Since $P_{0} \in \tau_{i}\left(B_{0}\right) \backslash \Sigma, P_{0}$ is an interior point of $\tau_{i}\left(B_{0}\right)$.

By (3.2) and (3.3), $P_{i} \notin \tau_{i}\left(B_{0}\right)$ and, for all $i, P_{i}$ and $P_{0}$ are separated on $l_{i}$ by two points of $\Sigma$. Since $\Sigma$ is closed, no sequence of points of $\Sigma$ can converge to $P_{0}$. Thus the sequence $P_{i}$ does not converge to $P_{0}$ either, a contradiction.
4. Proof of Theorem 2. For $n \geqq 3$, let $B$ be an arc of order greater than $n$ in $R_{n}$. Let $E$ and $s_{1}, \ldots, s_{n+1}$ be chosen according to 3.1 , with $\Sigma^{n}$ consisting of the singular points of $B$.

Given $k, 1 \leqq k \leqq n-2$, let $\Psi$ denote the projection of $R_{n}$ from $F=s_{1} \ldots s_{n-k-1}$. By 3.1, (3) $)_{n}$, and (4),$F$ does not contain any of $s_{n-k}, \ldots, s_{n+1}$. Hence $\Psi B$ is an arc of order greater than $k+1$ in $\Psi R_{n}=R_{k+1}$. Hence also

$$
\text { class } \Psi B>k+1
$$

Let $\Sigma^{k+1}$ be the finite set of points of $\Psi B$ consisting of $s_{1}, \ldots, s_{n-k-1}, \Sigma^{n}$, and the singular points of $\Psi B$. Then applying duality to 3.1 , we obtain $k+2$ points $q_{1}, \ldots, q_{k+2}$ on $\Psi B$ and a point $Q$ in $\Psi R_{n}$ such that

$$
\begin{array}{lc}
(1)_{k+1}{ }^{*}: & Q \notin L_{k}^{k+1}(s) \\
(2)_{k+1}^{*}: & \text { if } s \in \Sigma^{k+1}, \\
& Q \in L_{k}^{k+1}\left(q_{j}\right) \backslash L_{k-1}^{k+1}\left(q_{j}\right), \\
j=1, \ldots, k+2 .
\end{array}
$$

Thus $q_{j} \notin \Sigma^{k+1}$.
By 3.2, there exists an open neighbourhood of $Q$ in $\Psi R_{n}$, all of whose points have the above properties. Projection being continuous, the inverse image of that neighbourhood is an open set $O$ in $R_{n}$. Thus, if $T$ is any point in $O$, there are values $t_{j}$ near $q_{j}$ on $B$ such that

$$
\Psi T \notin L_{k}^{k+1}(s) \quad \text { if } s \in \Sigma^{k+1}
$$

and

$$
\Psi T \in L_{k}^{k+1}\left(t_{j}\right) \backslash L_{k-1}^{k+1}\left(t_{j}\right) .
$$

Hence

$$
\begin{equation*}
T \notin F L_{k}^{n}(s) \quad \text { if } \Psi s \in \Sigma^{k+1} \tag{4.1}
\end{equation*}
$$

and

$$
\begin{equation*}
T \in F L_{k}^{n}\left(t_{j}\right) \backslash F L_{k-1}^{n}\left(t_{j}\right) \tag{4.2}
\end{equation*}
$$

By (5) ${ }_{n}$, the flats

$$
L_{n-h-1}{ }^{n}\left(s_{i_{0}}\right) s_{i_{1}} \ldots s_{i_{h}} \quad(h=1, \ldots, n-k-2)
$$

are hyperplanes in $R_{n}$; here $i_{0}, \ldots, i_{h}$ is any $(h+1)$-tuple from

$$
1, \ldots, n-k-1
$$

Being open, $O$ is not contained in any of these hyperplanes nor in any of the osculating hyperplanes $L_{n-1}{ }^{n}\left(s_{i}\right), i=1, \ldots, n-k-1$. Moreover, we may choose $O$ so small that none of these hyperplanes meets $O$, i.e., that if $T$ is any point of $O$, then

$$
\begin{equation*}
T \notin L_{n-1}^{n}\left(s_{i}\right) \quad(i=1, \ldots, n-k-1) \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
T \notin L_{n-h-1}^{n}\left(s_{i_{0}}\right) s_{i_{1}} \ldots s_{i_{h}} \quad(h=1, \ldots, n-k-2), \tag{4.4}
\end{equation*}
$$

where $i_{0}, \ldots, i_{h}$ is any $(h+1)$-tuple from $1, \ldots, n-k-1$.
Let $T \in O$ and let $t_{j} \in B$ be fixed satisfying (4.2), $j=1, \ldots, k+2$. Let $l$ be any line through $T$ such that

$$
l \not \subset F L_{k}^{n}\left(t_{j}\right), \quad j=1, \ldots, k+2 .
$$

Consider the mapping

$$
\tau(F, t)=\left(F L_{k}^{n}(t)\right) \cap l
$$

defined for all $t$ on $B$ for which

$$
\begin{equation*}
\operatorname{dim}\left(F L_{k}{ }^{n}(t)\right)=n-1 \tag{4.5}
\end{equation*}
$$

and

$$
\begin{equation*}
l \not \subset F L_{k}{ }^{n}(t) . \tag{4.6}
\end{equation*}
$$

Since, by (4.1) and the definition of $\Sigma^{k+1}$, (4.5) holds for each $t_{j}$, (4.5) will be satisfied for all $t$ sufficiently close to any $t_{j}$. For these values of $t$, the hyperplane $F L_{k}{ }^{n}(t)$ will depend continuously on $t$, and hence (4.6) will be satisfied for all $t$ close to $t_{j}$. Thus $\tau(F, t)$ will be defined and continuous in some neighbourhood of $t_{j}, j=1, \ldots, k+2$.

Similarly, since by (4.2),

$$
\begin{equation*}
\tau(F, t) \notin F L_{k-1}^{n}(t) \tag{4.7}
\end{equation*}
$$

for $t=t_{j}$, this relation will still hold in some smaller neighbourhood of $t_{j}$. Thus altogether, $\tau(F, t)$ will be defined, continuous, and, by 2.1 , monotonic in that smaller neighbourhood of $t_{j}$. Let $\sigma_{j}$ denote, for each $j$, the image of that neighbourhood on $l$. Thus $T \in \sigma_{j}$ and there is a closed neighbourhood $\sigma$ of $T$ on $l$ containing $T$ in its interior and contained in all the $\sigma_{j}$ and in $O$.

Let $Q_{1}$ and $Q_{2}$ denote the endpoints of $\sigma$. Then there are points $t_{1 j}$ and $t_{2 j}$ near $t_{j}$ such that

$$
\begin{equation*}
\tau\left(F, t_{1 j}\right)=Q_{1}, \quad \tau\left(F, t_{2 j}\right)=Q_{2}, \quad j=1, \ldots, k+2 . \tag{4.8}
\end{equation*}
$$

As $t$ moves from $t_{1 j}$ to $t_{2 j}, \tau(F, t)$ moves monotonically through $\sigma$ from $Q_{1}$ to $Q_{2}$. Let $\bar{B}_{j}$ denote the closed neighbourhood of $t_{j}$ on $B$ bounded by $t_{1 j}$ and $t_{2 j}$.

By properties (3) $)_{n}$ and $(5)_{n}$ of $s_{1}, \ldots, s_{n+1}$, we may apply 2.4 to the points $s_{1}, \ldots, s_{n-k-1}$ of $B$. Thus for $i=1, \ldots, n-k-1$, there exists a closed neighbourhood $N_{i}$ of $s_{i}$ containing $s_{i}$ in its interior such that if $P_{i} \in N_{i}$ and $s_{i}{ }^{\prime}$ is any point of a neighbourhood $B_{i}$ of $s_{i}$ on $B, B_{i} \subset N_{i}$, then

$$
\begin{equation*}
\operatorname{dim}\left(P_{1} \ldots P_{n-k-1}\right)=n-k-2 \tag{4.9}
\end{equation*}
$$

and
(4.10) $\operatorname{dim}\left(L_{n-h-1}{ }^{n}\left(s_{i_{0}}{ }^{\prime}\right) P_{i_{1}} \ldots P_{i_{h}}\right)=n-1 \quad(h=1, \ldots, n-k-2)$
for every choice of the $(h+1)$-tuple $i_{0}, \ldots, i_{h}$ from $1, \ldots, n-k-1$.
Since $\sigma \subset O$, (4.1) and the definition of $\Sigma^{k+1}$ imply that $\sigma \cap F=\emptyset$. Also by (4.3),

$$
\sigma \cap L_{n-1}^{n}\left(s_{i}\right)=\emptyset, \quad i=1, \ldots, n-k-1
$$

Finally, (4.4) implies

$$
\sigma \cap\left(L_{n-h-1}^{n}\left(s_{i_{0}}\right) s_{i_{1}} \ldots s_{i_{h}}\right)=\emptyset \quad(h=1, \ldots, n-k-2)
$$

for every $(h+1)$-tuple $i_{0}, \ldots, i_{h}$ from $1, \ldots, n-k-1$. On the other hand, the flats

$$
\widetilde{F}=P_{1} \ldots P_{n-k-1}
$$

and the hyperplanes

$$
L_{n-h-1}{ }^{n}\left(s_{i}^{\prime}\right) \quad \text { and } \quad L_{n-h-1}^{n}\left(s_{i_{0}}^{\prime}\right) P_{i_{1}} \ldots P_{i h}
$$

depend continuously on the points $s_{i}{ }^{\prime}$ and $P_{i}$; cf. (4.10). Hence, $\sigma$ being closed, we may assume that the neighbourhoods $N_{1}, \ldots, N_{n-k-1}$ were taken so small that

$$
\begin{gather*}
\sigma \cap \widetilde{F}=\emptyset,  \tag{4.11}\\
\sigma \cap L_{n-1}^{n}\left(s_{i}^{\prime}\right)=\emptyset, \tag{4.12}
\end{gather*}
$$

and

$$
\begin{equation*}
\sigma \cap\left(L_{n-h-1}^{n}\left(s_{i_{0}}^{\prime}\right) P_{i_{1}} \ldots P_{i_{h}}\right)=\emptyset \tag{4.13}
\end{equation*}
$$

for all choices of $P_{i}$ in $N_{i}$ and $s_{i}{ }^{\prime}$ in a neighbourhood $B_{i}$ of $s_{i}$ on $B, B_{i} \subset N_{i}$, $i=1, \ldots, n-k-1$. For the same reason, we may choose the $N_{i}$ so small that the subarcs $B_{i}$ are regular and that (4.5), (4.6), and (4.7) also hold for $\widetilde{F}$, i.e., that

$$
\operatorname{dim} \widetilde{F} L_{k}{ }^{n}(t)=n-1, \quad l \not \subset \widetilde{F} L_{k}{ }^{n}(t)
$$

and that

$$
\boldsymbol{\tau}(\widetilde{F}, t)=\left(\widetilde{F} L_{k}^{n}(t)\right) \cap l \not \subset \widetilde{F} L_{k-1}^{n}(t)
$$

for all $\widetilde{F}=P_{1} \ldots P_{n-k-1}$ and all $t \in \bigcup_{j=1}^{k+2} \bar{B}_{j}$. Thus $\tau(\widetilde{F}, t)$ is defined on each $\bar{B}_{j}$ and maps it continuously and monotonically into $l$.

Let $\sigma^{\prime}$ be a closed segment on $l$ containing $T$ in its interior and contained in the interior of $\sigma$. Then

$$
\tau\left(F, t_{j}\right)=T \in \sigma^{\prime}
$$

and, by (4.8),

$$
\tau\left(F, t_{\alpha j}\right)=Q_{\alpha} \notin \sigma^{\prime}, \quad \alpha=1,2 .
$$

Hence there are closed neighbourhoods $M_{i}$ of $s_{i}$ contained in $N_{i}$ and such that $s_{i}$ lies in the interior of $M_{i}, \tau\left(\widetilde{F}, t_{j}\right) \in \sigma^{\prime}$, and

$$
\tau\left(\widetilde{F}, t_{\alpha j}\right) \notin \sigma^{\prime} \quad \text { for all } P_{i} \in M_{i}, \quad i=1, \ldots, n-k-1, \quad \alpha=1,2 .
$$

Choose $P_{1}, \ldots, P_{n-k-1}$ arbitrarily but fixed in $M_{1}, \ldots, M_{n-k-1}$, respectively. Then, $\widetilde{F}$ is fixed and, as $t$ moves on $\bar{B}_{j}$ from $t_{1 j}$ through $t_{j}$ to $t_{2 j}, \tau(\widetilde{F}, t)$ moves continuously and monotonically from $\tau\left(\widetilde{F}, t_{1 j}\right) \notin \sigma^{\prime}$ through $\tau\left(\widetilde{F}, t_{j}\right) \in \sigma^{\prime}$ to $\tau\left(\widetilde{F}, t_{2 j}\right) \notin \sigma^{\prime}$. Hence $\sigma^{\prime} \subset \tau\left(\widetilde{F}, \bar{B}_{j}\right)$ and for each $Q \in \sigma^{\prime}$, there exists a $t_{j} \in \bar{B}_{j}$ such that

$$
Q=\tau\left(\widetilde{F}, t_{j}\right), \quad j=1, \ldots, k+2
$$

Thus the $(n-k-1)$-flat $\widetilde{F} Q$ meets the osculating $k$-space of one point of each of $\bar{B}_{1}, \ldots, \bar{B}_{k+2}$; cf. (4.11).

Let $B_{i}$ be a neighbourhood of $s_{i}$ on $B, B_{i} \subset M_{i}$. Let $\varphi$ denote the projection of $R_{n}$ from a point $Q$ of $\sigma^{\prime}$. Let $P_{i}$ be a point of $M_{i}$ which lies on the osculating hyperplanes of $n$ distinct points of $B_{i}$; cf. 1.8.

We next verify that the $\operatorname{arcs} \varphi B_{i}$ and the points $\varphi P_{i}$ in $\varphi R_{n}$ satisfy all the assumptions of 2.3 . By (4.12), the arcs $\varphi B_{i}$ are regular. By (4.9) and (4.11), $\operatorname{dim} \varphi \widetilde{F}=n-k-2$ and thus the points $\varphi P_{1}, \ldots, \varphi P_{n-k-1}$ are independent. By (4.12) and 2.2, the points $\varphi P_{i}$ lie on $n-1$ osculating hyperplanes of $\varphi B_{i}$. Finally, by (4.10) and (4.13),

$$
\operatorname{dim} \varphi\left(L_{n-h-1}{ }^{n}\left(s_{i_{0}}{ }^{\prime}\right) P_{i_{1}} \ldots P_{i_{h}}\right)=n-1
$$

for every choice of the $(h+1)$-tuple $i_{0}, \ldots, i_{h}$ from $1, \ldots, n-k-1$, $h=1, \ldots, n-k-2$. Therefore by 2.3 , the $(n-k-2)$-flat $\varphi P_{1} \ldots \varphi P_{n-k-1}$ meets the osculating $k$-spaces of $k+1$ points of each of $\varphi B_{1}, \ldots, \varphi B_{n-k-1}$. Hence the $(n-k-1)$-flat $\widetilde{F} Q$ meets the osculating $k$-spaces of $k+1$ points
of each of $B_{1}, \ldots, B_{n-k-1}$ and of one point of each of $\bar{B}_{1}, \ldots, \bar{B}_{k+2}$, altogether at least

$$
(n-k-1)(k+1)+(k+2)>(n-k)(k+1)
$$

osculating $k$-spaces of $B$. This completes our proof.

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University of Toronto, Toronto, Ontario;
Université de Montréal, Montréal, Québec


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