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A review on gait generation of the biped robot on various terrains – CORRIGENDUM

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DOI: <https://doi.org/10.1017/S0263574723000097>, Published online by Cambridge University Press: 15 February 2023

Keywords: biped robot; gait generation; DBM; controllers; soft computing techniques; ZMP; review

The authors regret the inclusion of an error in the above article. On page 2, Table 1 contains a mistake in the ZMP equations.

The correct version of the ZMP equation in Table 1 is provided below.

$$x_{ZMP} = \sum_{i=1}^n \left[\frac{-I_i \dot{\omega}_i + m_i x_i (\ddot{z}_i - g) + m_i \ddot{x}_i z_i}{m_i (\ddot{z}_i - g)} \right]$$

$$y_{ZMP} = \sum_{i=1}^n \left[\frac{-I_i \dot{\omega}_i + m_i y_i (\ddot{z}_i - g) + m_i \ddot{y}_i z_i}{m_i (\ddot{z}_i - g)} \right]$$

Reference

- [1] Khan, M. and Mandava, R. (2023). A review on gait generation of the biped robot on various terrains. *Robotica*, 41(6), 1888–1930. doi: [10.1017/S0263574723000097](https://doi.org/10.1017/S0263574723000097)

Cite this article: M. S. Khan and R. K. Mandava (2023). “A review on gait generation of the biped robot on various terrains – CORRIGENDUM”, *Robotica* 41, 3233. <https://doi.org/10.1017/S0263574723000802>