

## STABILITY OF HALF-LINEAR NEUTRAL STOCHASTIC DIFFERENTIAL EQUATIONS WITH DELAYS

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### Abstract

In this paper, we study the mean square asymptotic stability of a generalized half-linear neutral stochastic differential equation with variable delays applying fixed point theory. An asymptotic mean square stability theorem with a necessary and sufficient condition is proved, which improves and generalizes some results due to Burton, Zhang and Luo. Two examples are given to illustrate our results.

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### 1. Introduction

It is well known that stochastic delay differential equations, also known as stochastic functional differential equations, are a natural generalization of stochastic ordinary differential equations by allowing the coefficients to depend on values in the past. As a simple example let us mention the differential equation

$$dN(t) = aN(t)(K - N(t - \tau)) dt + \sigma dW(t), \quad t \geq 0,$$

which is frequently used to model the dynamics of a population size taking into account time to maturity  $\tau$  and random fluctuations. Recently, the theory and applications of stochastic delay differential equations have been studied by many authors (see, for example, [5, 8, 10] and the references therein).

On the other hand, Lyapunov's direct method has been successfully used to investigate stability properties of a wide variety of differential equations. However, there are many difficulties encountered in the study of stability by means of Lyapunov's direct method. Recently, Burton [1–4], Luo [9] and Zhang [11, 12] studied stability using fixed point theory which overcame the difficulties encountered in the study of stability by means of Lyapunov's direct method.

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Hitherto, fixed point theory has been used almost exclusively to deal with the stability of deterministic differential equations, not for stochastic differential equations. Very recently, Luo [9] studied the mean square asymptotic stability of a class of linear scalar neutral stochastic differential equations. For more details of stability with regard to stochastic differential equations, we refer to [7, 8] and the references therein.

Motivated by previous work, in this paper we study the mean square asymptotic stability of a half-linear neutral stochastic differential equation with variable delays applying fixed point theory. An asymptotic mean square stability theorem with a necessary and sufficient condition is proved. Two examples are given to illustrate our results. The results presented in this paper improve and generalize the main results in [2, 9, 11, 12].

## 2. Main results

Let  $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, P)$  be a complete filtered probability space and  $W(t)$  denote a one-dimensional standard Brownian motion defined on  $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, P)$  such that  $\{\mathcal{F}_t\}_{t \geq 0}$  is the natural filtration of  $W(t)$ . Let  $a(t), \bar{a}(t), b(t), \bar{b}(t), c(t), e(t), q(t) \in C(R^+, R)$  and  $\tau(t), \delta(t) \in C(R^+, R^+)$  with  $t - \tau(t) \rightarrow \infty$  and  $t - \delta(t) \rightarrow \infty$  as  $t \rightarrow \infty$ . Here  $C(S_1, S_2)$  denotes the set of all continuous function  $\phi : S_1 \rightarrow S_2$  with the supremum norm  $\|\cdot\|$ .

Burton in [2] and Zhang in [12] studied the equation

$$x'(t) = -\bar{b}(t)x(t - \tau(t)) \quad (2.1)$$

and proved the following theorems.

**THEOREM A (Burton [2]).** *Suppose that  $\tau(t) = r$  and there exists a constant  $\alpha < 1$  such that*

$$\int_{t-r}^t |\bar{b}(s+r)| ds + \int_0^t |\bar{b}(s+r)| e^{-\int_s^t \bar{b}(u+r) du} \int_{s-r}^s |\bar{b}(u+r)| du ds \leq \alpha$$

for all  $t \geq 0$  and  $\int_0^\infty \bar{b}(s) ds = \infty$ . Then for every continuous initial function  $\phi : [-r, 0] \rightarrow R$ , the solution  $x(t) = x(t, 0, \phi)$  of (2.1) is bounded and tends to zero as  $t \rightarrow \infty$ .

**THEOREM B (Zhang [12]).** *Suppose that  $\tau$  is differentiable, the inverse function  $g(t)$  of  $t - \tau(t)$  exists, and there exists a constant  $\alpha \in (0, 1)$  such that for  $t \geq 0$ ,  $\liminf_{t \rightarrow \infty} \int_0^t \bar{b}(g(s)) ds > -\infty$  and*

$$\begin{aligned} & \int_{t-\tau(t)}^t |\bar{b}(g(s))| ds + \int_0^t e^{-\int_s^t \bar{b}(g(u)) du} |\bar{b}(s)| |\tau'(s)| ds \\ & + \int_0^t e^{-\int_s^t \bar{b}(g(u)) du} |\bar{b}(g(s))| \int_{s-\tau(s)}^s |\bar{b}(g(v))| dv ds \leq \alpha < 1. \end{aligned} \quad (2.2)$$

Then the zero solution of (2.1) is asymptotically stable if and only if  $\int_0^t \bar{b}(g(s)) ds \rightarrow \infty$ , as  $t \rightarrow \infty$ .

Obviously, Theorem B improves Theorem A. Recently, Zhang [11] studied the half-linear equation

$$x'(t) = -\bar{a}(t)x(t) + b(t)g(x(t - \tau(t))) \quad (2.3)$$

where  $g : R \rightarrow R$  is continuous and obtained the following theorem.

**THEOREM C (Zhang [11]).** Suppose that  $\tau(t) \geq 0$  such that for  $t \geq 0$ ,  $t - \tau(t) \rightarrow \infty$  as  $t \rightarrow \infty$ , and there exists a constant  $L > 0$ , for  $|x|, |y| \leq L$ ,  $|g(x) - g(y)| \leq |x - y|$  and  $q(0) = 0$ . For  $t > 0$ ,  $\liminf_{t \rightarrow \infty} \int_0^t \bar{a}(s) ds > -\infty$  and

$$\sup_{t \geq 0} \int_0^t e^{-\int_s^t \bar{a}(u) du} |b(s)| ds < 1. \quad (2.4)$$

Then the zero solution of (2.3) is asymptotically stable if and only if  $\int_0^t \bar{a}(s) ds \rightarrow \infty$ , as  $t \rightarrow \infty$ .

Very recently, Luo [9] considered the linear neutral stochastic differential equation

$$d[x(t) - q(t)x(t - \tau(t))] = [a(t)x(t) + b(t)x(t - \tau(t))] dt \\ + [c(t)x(t) + e(t)x(t - \delta(t))] dW(t) \quad (2.5)$$

and obtained the following theorem.

**THEOREM D (Luo [9]).** Let  $\tau(t)$  be differentiable. Assume that there exist a constant  $\alpha \in (0, 1)$  and a continuous function  $h(t) : [0, \infty) \rightarrow R$  such that for  $t \geq 0$ ,  $\liminf_{t \rightarrow \infty} \int_0^t h(s) ds > -\infty$  and

$$|q(t)| + \int_{t-\tau(t)}^t |a(s) + h(s)| ds \\ + \int_0^t e^{-\int_s^t h(u) du} |(a(s - \tau(s)) + h(s - \tau(s)))(1 - \tau'(s)) + b(s) - q(s)h(s)| ds \\ + \int_0^t e^{-\int_s^t h(u) du} |h(s)| \int_{s-\tau(s)}^s |a(u) + h(u)| du ds \\ + \left( \int_0^t e^{-2\int_s^t h(u) du} (|c(s)| + |e(s)|)^2 ds \right)^{1/2} \leq \alpha < 1.$$

Then the zero solution of (2.5) is mean square asymptotically stable if and only if  $\int_0^t h(s) ds \rightarrow \infty$ , as  $t \rightarrow \infty$ .

In this paper, we consider the following half-linear neutral stochastic differential equation

$$d[x(t) - q(t)f(x(t - \tau(t)))] = [a(t)x(t) + b(t)f(x(t - \tau(t)))] dt \\ + [c(t)x(t) + e(t)g(x(t - \delta(t)))] dW(t), \quad (2.6)$$

with the initial condition

$$x(s) = \phi(s) \quad \text{for } s \in [m(0), 0],$$

where the functions  $f : R \rightarrow R$ ,  $g : R \rightarrow R$  are continuous,  $\phi \in C([m(0), 0], R)$ ,  $x : [m(0), \infty) \times \Omega \rightarrow R$ , and

$$m(0) = \min \{ \inf\{s - \tau(s), s \geq 0\}, \inf\{s - \delta(s), s \geq 0\} \} \leq 0.$$

Note that (2.6) becomes (2.5) for  $f(x) \equiv g(x) \equiv x$ . Thus we know that (2.6) includes (2.1), (2.3) and (2.5) as special cases. Our aim here is to generalize Theorems B, C and D to apply to (2.6).

For any  $\phi \in C([m(0), 0], R)$ , we define  $\|\phi\| = \sup_{s \in [m(0), 0]} |\phi(s)|$ . For each  $\lambda > 0$ , we define  $C(\lambda) := \{ \phi \in C([m(0), 0], R) : \|\phi\| \leq \lambda \}$ . Denote by  $F$  the Banach space of all  $\mathcal{F}$ -adapted processes  $\psi(t, \omega) : [m(0), \infty) \times \Omega \rightarrow R$  which are almost surely continuous in  $t$  with norm

$$\|\psi\|_F = \left\{ E \left( \sup_{s \geq m(0)} |\psi(s, \omega)|^2 \right) \right\}^{1/2}.$$

Moreover, we define  $F(\lambda) = \{ \psi \in F : \|\psi\|_F \leq \lambda \}$  for each  $\lambda > 0$  and let

$$\|\psi\|_F^{[r,t]} = \left\{ E \left( \sup_{s \in [r,t]} |\psi(s, \omega)|^2 \right) \right\}^{1/2}, \quad \text{for } r < t,$$

and

$$\|\psi\|_F^{[0,\infty)} = \left\{ E \left( \sup_{s \geq 0} |\psi(s, \omega)|^2 \right) \right\}^{1/2}.$$

**THEOREM 2.1.** *Suppose that  $\tau$  is differentiable, and there exist continuous functions  $h(t) : [0, \infty) \rightarrow R$  and constants  $L > 0$ ,  $\alpha \in (0, 1)$ ,  $\beta \in (0, 1]$  such that for  $t \geq 0$ :*

- (i)  $\liminf_{t \rightarrow \infty} \int_0^t h(s) ds > -\infty$ ;
- (ii) 
$$\begin{aligned} & \beta |q(t)| + \int_{t-\tau(t)}^t |a(s) + h(s)| ds \\ & + \int_0^t e^{-\int_s^t h(u) du} |h(s)| \int_{s-\tau(s)}^s |a(u) + h(u)| du ds \\ & + \int_0^t e^{-\int_s^t h(u) du} (|(a(s - \tau(s)) + h(s - \tau(s)))(1 - \tau'(s))| \\ & + \beta |b(s) - q(s)h(s)|) ds \\ & + 2 \left( \int_0^t e^{-2\int_s^t h(u) du} (|c(s)| + \beta |e(s)|)^2 ds \right)^{1/2} \leq \alpha < 1; \end{aligned}$$
- (iii)  $|f(x) - f(y)| \leq \beta |x - y|$  and  $|g(x) - g(y)| \leq \beta |x - y|$  for all  $x, y \in F(L)$  with  $f(0) = g(0) = 0$ .

Then the zero solution of (2.6) is mean square asymptotically stable if and only if

$$\int_0^t h(s) ds \rightarrow \infty, \quad \text{as } t \rightarrow \infty. \tag{2.7}$$

**PROOF.** We suppose that (2.7) holds. Choose  $\delta > 0, \delta < L$  such that  $2\delta K + \alpha L \leq L$ , where  $K = \sup_{t \geq 0} \{e^{-\int_0^t h(s) ds}\}$ . Let  $\phi \in C(\delta)$  and set

$$S = \left\{ x : [m(0), \infty) \times \Omega \rightarrow R \mid x(t, \omega) = \phi(t) \text{ for } t \in [m(0), 0], \right. \\ \left. x(t, \omega) \in F(L) \text{ for } t \geq 0, E|x(t, \omega)|^2 \rightarrow 0 \text{ as } t \rightarrow \infty \right\}.$$

Then it is easy to check that  $S$  is a closed subset of  $F$ . From the definitions of  $\|\cdot\|$ , for any  $x \in S$  and  $t > 0$ ,

$$\|x\|_F = \max\{\|\phi\|, \|x\|_F^{[0, \infty)}\} \leq L. \tag{2.8}$$

Define an operator  $P : S \rightarrow S$  by  $(Px)(t) = \phi(t)$  for  $t \in [m(0), 0]$  and for  $t \geq 0$ ,

$$(Px)(t) = \left( \phi(0) - q(0)f(\phi(-\tau(0))) - \int_{-\tau(0)}^0 (a(s) + h(s))\phi(s) ds \right) e^{-\int_0^t h(s) ds} \\ + q(t)f(x(t - \tau(t))) + \int_{t-\tau(t)}^t (a(s) + h(s))x(s) ds \\ + \int_0^t e^{-\int_s^t h(u) du} ((a(s - \tau(s)) + h(s - \tau(s))) \\ \times (1 - \tau'(s))x(s - \tau(s)) + (b(s) - q(s)h(s))f(x(s - \tau(s)))) ds \\ - \int_0^t e^{-\int_s^t h(u) du} h(s) \left( \int_{s-\tau(s)}^s (a(u) + h(u))x(u) du \right) ds \\ + \int_0^t e^{-\int_s^t h(u) du} (c(s)x(s) + e(s)g(x(s - \delta(s)))) dW(s) \\ := \sum_{i=1}^5 I_i(t). \tag{2.9}$$

We now show the mean square continuity of  $P$  on  $[0, \infty)$ . Let  $x \in S, T_1 > 0$  and  $|r|$  be sufficiently small. Then

$$E|(Px)(T_1 + r) - (Px)(T_1)|^2 \leq 5 \sum_{i=1}^5 E|I_i(T_1 + r) - I_i(T_1)|^2.$$

It is easy to verify that

$$E|I_i(T_1 + r) - I_i(T_1)|^2 \rightarrow 0, \quad \text{as } r \rightarrow 0, \quad i = 1, 2, 3, 4.$$

From the last term  $I_5$  in (2.9), we have

$$\begin{aligned}
 & E|I_5(T_1 + r) - I_5(T_1)|^2 \\
 &= E \left| \int_0^{T_1} e^{-\int_s^{T_1} h(u) du} (e^{-\int_{T_1}^{T_1+r} h(u) du} - 1) \right. \\
 &\quad \times (c(s)x(s) + e(s)g(x(s - \delta(s)))) dW(s) \\
 &\quad \left. + \int_{T_1}^{T_1+r} e^{-\int_s^{T_1+r} h(u) du} (c(s)x(s) + e(s)g(x(s - \delta(s)))) dW(s) \right|^2 \\
 &\leq 2E \int_0^{T_1} e^{-2\int_s^{T_1} h(u) du} |e^{-\int_{T_1}^{T_1+r} h(u) du} - 1|^2 \\
 &\quad \times |c(s)x(s) + e(s)g(x(s - \delta(s)))|^2 ds \\
 &\quad + 2E \int_{T_1}^{T_1+r} e^{-2\int_s^{T_1+r} h(u) du} |c(s)x(s) + e(s)g(x(s - \delta(s)))|^2 ds \\
 &\rightarrow 0 \quad \text{as } r \rightarrow 0.
 \end{aligned}$$

Therefore  $P$  is mean square continuous on  $[0, \infty)$ .

Next, we verify that  $\|Px\|_F \leq L$ . As  $\phi \in C(\delta)$  and  $x \in S$ ,

$$\begin{aligned}
 \|Px\|_F^{[0, \infty)} &= \left\{ E \left( \sup_{s \geq 0} |Px(s)|^2 \right) \right\}^{1/2} = \left\{ E \left( \sup_{s \geq 0} \left| \sum_{i=1}^5 I_i(s) \right|^2 \right) \right\}^{1/2} \\
 &\leq \sum_{i=1}^5 \left\{ E \left( \sup_{s \geq 0} |I_i(s)|^2 \right) \right\}^{1/2}. \tag{2.10}
 \end{aligned}$$

It follows from (2.9), (2.10), condition (ii), (iii) and Doob’s  $L^p$ -inequality (see [6]) that

$$\begin{aligned}
 \|Px\|_F^{[0, \infty)} &\leq \left( |\phi(0)| + |q(0)| \cdot \beta |\phi(-\tau(0))| \right. \\
 &\quad \left. + \int_{-\tau(0)}^0 |a(v) + h(v)| \cdot |\phi(v)| dv \right) \cdot \sup_{s \geq 0} \{ e^{-\int_0^s h(v) dv} \} \\
 &\quad + \left( E \sup_{s \geq 0} \left( |q(s)| \cdot \beta |x(s - \tau(s))| \right. \right. \\
 &\quad \left. \left. + \int_{s-\tau(s)}^s |a(v) + h(v)| \cdot |x(v)| dv \right)^2 \right)^{1/2} \\
 &\quad + \left( E \sup_{s \geq 0} \left( \int_0^s e^{-\int_v^s h(u) du} (|a(v - \tau(v)) \right. \right. \\
 &\quad \left. \left. + h(v - \tau(v))(1 - \tau'(v))| \cdot |x(v - \tau(v))| \right. \right. \\
 &\quad \left. \left. + |b(v) - q(v)h(v)| \cdot \beta |x(v - \tau(v))| \right) dv \right)^2 \right)^{1/2}
 \end{aligned}$$

$$\begin{aligned}
 & + \left( E \sup_{s \geq 0} \left( \int_0^s e^{-\int_v^s h(u) du} |h(v)| \left( \int_{v-\tau(v)}^v |a(u) \right. \right. \right. \\
 & \quad \left. \left. \left. + h(u) \cdot |x(u)| du \right) dv \right)^2 \right)^{1/2} \\
 & + 2 \sup_{s \geq 0} \left( E \int_0^s e^{-2 \int_v^s h(u) du} (|c(v)| \cdot |x(v)| \right. \\
 & \quad \left. + |e(v)| \cdot \beta |x(v - \delta(v))|^2 dv \right)^{1/2} \\
 & \leq \delta K \left( 1 + \beta |q(0)| + \int_{-\tau(0)}^0 |a(v) + h(v)| dv \right) \\
 & + \|x\|_F \cdot \sup_{s \geq 0} \left\{ \beta |q(s)| + \int_{s-\tau(s)}^s |a(v) + h(v)| dv \right. \\
 & \quad + \int_0^s e^{-\int_v^s h(u) du} (|(a(v - \tau(v)) + h(v - \tau(v)))(1 - \tau'(v))| \\
 & \quad + \beta |b(v) - q(v)h(v)|) dv \\
 & \quad + \int_0^s e^{-\int_v^s h(u) du} |h(v)| \left( \int_{v-\tau(v)}^v |a(u) + h(u)| du \right) dv \\
 & \quad \left. + 2 \left( \int_0^s e^{-2 \int_v^s h(u) du} (|c(v)| + \beta |e(v)|)^2 dv \right)^{1/2} \right\} \\
 & \leq 2\delta K + \alpha L \leq L.
 \end{aligned}$$

It follows from (2.8) that

$$\|Px\|_F = \max\{\|\phi\|, \|Px\|_F^{[0, \infty)}\} \leq L.$$

Thirdly, we verify that  $E|(Px)(t)|^2 \rightarrow 0$  as  $t \rightarrow \infty$ . Since  $E|x(t)|^2 \rightarrow 0$ ,  $t - \delta(t) \rightarrow \infty$  as  $t \rightarrow \infty$ , for each  $\epsilon > 0$ , there exists a  $T_1 > 0$  such that  $s \geq T_1$  implies  $E|x(s)|^2 < \epsilon$  and  $E|x(s - \delta(s))|^2 < \epsilon$ . By condition (ii), for  $t \geq T_1$ , the last term  $I_5$  in (2.9) satisfies

$$\begin{aligned}
 E|I_5(t)|^2 & \leq E \int_0^{T_1} e^{-2 \int_s^t h(u) du} (|c(s)| \cdot |x(s)| + |e(s)| \cdot |g(x(s - \delta(s)))|)^2 ds \\
 & \quad + E \int_{T_1}^t e^{-2 \int_s^t h(u) du} (|c(s)| \cdot |x(s)| + |e(s)| \cdot |g(x(s - \delta(s)))|)^2 ds \\
 & \leq (\|x\|_F^{[m(0), T_1]})^2 \int_0^{T_1} e^{-2 \int_s^t h(u) du} (|c(s)| + \beta |e(s)|)^2 ds + \alpha \epsilon \\
 & \leq \|x\|_F^2 \cdot e^{-2 \int_{T_1}^t h(u) du} \int_0^{T_1} e^{-2 \int_s^{T_1} h(u) du} (|c(s)| + \beta |e(s)|)^2 ds + \alpha \epsilon \\
 & \leq L^2 \alpha^2 e^{-2 \int_{T_1}^t h(u) du} + \alpha \epsilon.
 \end{aligned}$$

By (2.7), there exists  $T_2 > T_1$  such that  $L^2\alpha^2e^{-2\int_{T_1}^t h(u) du} < \epsilon$  for  $t \geq T_2$ . Thus for  $t \geq T_2$ ,

$$E|I_5(t)|^2 < \epsilon + \alpha\epsilon.$$

This proves that  $E|I_5(t)|^2 \rightarrow 0$ , as  $t \rightarrow \infty$ . Similarly, we can show that  $E|I_i(t)|^2 \rightarrow 0$ ,  $i = 1, 2, 3, 4$ , as  $t \rightarrow \infty$ . Thus  $E|(Px)(t)|^2 \rightarrow 0$  as  $t \rightarrow \infty$ . Hence  $Px \in S$ .

Now we show that  $P : S \rightarrow S$  is a contraction mapping. For any  $x, y \in S$ ,

$$\begin{aligned} \|Px - Py\|_F &= \left( E \sup_{s \geq m(0)} |(Px)(s) - (Py)(s)|^2 \right)^{1/2} \\ &= \left( E \sup_{s \geq 0} \left| q(s)(f(x(s - \tau(s))) - f(y(s - \tau(s)))) \right. \right. \\ &\quad + \int_{s-\tau(s)}^s (a(v) + h(v))(x(v) - y(v)) dv \\ &\quad + \int_0^s e^{-\int_v^s h(u) du} ((a(v - \tau(v)) + h(v - \tau(v))) \\ &\quad \times (1 - \tau'(v))(x(v - \tau(v)) - y(v - \tau(v))) \\ &\quad + (b(v) - q(v)h(v))(f(x(v - \tau(v))) - f(y(v - \tau(v)))) dv \\ &\quad - \int_0^s e^{-\int_v^s h(u) du} h(v) \left( \int_{v-\tau(v)}^v (a(u) + h(u))(x(u) - y(u)) du \right) dv \\ &\quad + \int_0^s e^{-\int_v^s h(u) du} (c(v)(x(v) - y(v)) + e(v)(g(x(v - \delta(v))) \\ &\quad \left. \left. - g(y(v - \delta(v)))) dW(v) \right|^2 \right)^{1/2} \\ &\leq \|x - y\|_F \cdot \sup_{s \geq 0} \left\{ \beta|q(s)| + \int_{s-\tau(s)}^s |a(v) + h(v)| dv \right. \\ &\quad + \int_0^s e^{-\int_v^s h(u) du} (\beta|b(v) - q(v)h(v)| + |(a(v - \tau(v)) \\ &\quad + h(v - \tau(v)))(1 - \tau'(v))|) dv \\ &\quad + \int_0^s e^{-\int_v^s h(u) du} |h(v)| \int_{v-\tau(v)}^v |a(u) + h(u)| du dv \\ &\quad \left. + 2 \left( \int_0^s e^{-2\int_v^s h(u) du} (|c(v)| + \beta|e(v)|)^2 dv \right)^{1/2} \right\} \\ &\leq \alpha \|x - y\|_F. \end{aligned}$$



Therefore,  $P : S \rightarrow S$  is contraction mapping and so  $P$  has a fixed point  $x \in S$ , which is a solution of (2.6) with  $x(s) = \phi(s)$  on  $[m(0), 0]$  and  $E|x(t)|^2 \rightarrow 0$  as  $t \rightarrow \infty$ .

To obtain the mean square asymptotic stability, we need to show that the zero solution of (2.6) is mean square stable. From (ii) we can choose  $\varepsilon > 0$  such that  $\alpha^2 + \varepsilon < 1$ . Thus we can find a constant  $N > 0$  such that

$$\begin{aligned} & \left(1 + \frac{1}{N}\right) \left( \beta|q(t)| + \int_{t-\tau(t)}^t |a(s) + h(s)| ds \right. \\ & \quad + \int_0^t e^{-\int_s^t h(u) du} (|(a(s - \tau(s)) + h(s - \tau(s)))(1 - \tau'(s))| \\ & \quad \quad \quad + \beta|b(s) - q(s)h(s)|) ds \\ & \quad \left. + \int_0^t e^{-\int_s^t h(u) du} |h(s)| \int_{s-\tau(s)}^s |a(u) + h(u)| du ds \right)^2 \\ & \quad + 4(1 + N) \int_0^t e^{-2\int_s^t h(u) du} (|c(s)| + \beta|e(s)|)^2 ds \leq \alpha^2 + \varepsilon < 1. \end{aligned} \tag{2.11}$$

Let  $\varepsilon > 0$  and  $\epsilon < L$  be given and choose  $\delta_0 > 0$  and  $\delta_0 < \epsilon$  satisfying the condition

$$4(1 + N)\delta_0^2 K^2 + (\alpha^2 + \varepsilon)\epsilon < \epsilon,$$

where  $N$  is defined in (2.11). If  $x(t) = x(t, 0, \phi)$  is a solution of (2.6) with  $\|\phi\| < \delta_0$ , then  $x(t) = (Px)(t)$  defined in (2.9). We claim that  $E|x(t)|^2 < \epsilon$  for all  $t \geq 0$ . Notice that  $E|x(t)|^2 = \|\phi(t)\|^2 < \epsilon$  for  $t \in [m(0), 0]$ . If there exists  $t^* > 0$  such that  $E|x(t^*)|^2 = \epsilon$  and  $E|x(t)|^2 < \epsilon$  for  $t \in [m(0), t^*)$ , then (2.9) and (2.11) imply that

$$\begin{aligned} E|x(t^*)|^2 & \leq (1 + N)\|\phi\|^2 \left(1 + \beta|q(0)| + \int_{-\tau(0)}^0 |a(s) + h(s)| ds\right)^2 e^{-2\int_0^{t^*} h(u) du} \\ & \quad + \epsilon \left(1 + \frac{1}{N}\right) \left( \beta|q(t^*)| + \int_{t^*-\tau(t^*)}^{t^*} |a(s) + h(s)| ds \right. \\ & \quad + \int_0^{t^*} e^{-\int_s^{t^*} h(u) du} \left( \int_{s-\tau(s)}^s |a(u) + h(u)| du \right) |h(s)| ds \\ & \quad + \int_0^{t^*} e^{-\int_s^{t^*} h(u) du} (|(a(s - \tau(s)) + h(s - \tau(s))) \\ & \quad \quad \quad \times (1 - \tau'(s))| + \beta|b(s) - q(s)h(s)|) ds \Big)^2 \\ & \quad + \epsilon \int_0^{t^*} e^{-2\int_s^{t^*} h(u) du} (|c(s)| + \beta|e(s)|)^2 ds \\ & \leq (1 + N)\delta_0^2 \left(1 + \beta|q(0)| + \int_{-\tau(0)}^0 |a(s) + h(s)| ds\right)^2 e^{-2\int_0^{t^*} h(u) du} \\ & \quad + (\alpha^2 + \varepsilon)\epsilon < \epsilon, \end{aligned} \tag{2.12}$$

which contradicts the definition of  $t^*$ . Thus the zero solution of (2.6) is mean square asymptotically stable if (2.7) holds.

Conversely, we suppose that (2.7) fails. From (i) there exists a sequence  $\{t_n\}$  with  $t_n \rightarrow \infty$  as  $n \rightarrow \infty$  such that  $\lim_{n \rightarrow \infty} \int_0^{t_n} h(u) du = \zeta$  for some  $\zeta \in R$ . Then, we can choose a constant  $J > 0$  satisfying  $\int_0^{t_n} h(u) du \in [-J, J]$  for all  $n \geq 1$ . Define

$$\omega(s) := |(a(s - \tau(s)) + h(s - \tau(s)))(1 - \tau'(s))| + \beta|b(s) - q(s)h(s)| + |h(s)| \int_{s-\tau(s)}^s |a(u) + h(u)| du$$

for all  $s \geq 0$ . From (ii) we have

$$\int_0^{t_n} e^{-\int_s^{t_n} h(u) du} \omega(s) ds \leq \alpha,$$

which implies that

$$\int_0^{t_n} e^{\int_0^s h(u) du} \omega(s) ds \leq \alpha e^{\int_0^{t_n} h(u) du} \leq e^J.$$

Therefore, the sequence  $\{\int_0^{t_n} e^{\int_0^s h(u) du} \omega(s) ds\}$  has a convergent subsequence. Without loss of generality, we can assume that

$$\lim_{n \rightarrow \infty} \int_0^{t_n} e^{\int_0^s h(u) du} \omega(s) ds = \gamma$$

for some  $\gamma > 0$ . Let  $k$  be an integer such that

$$\int_{t_k}^{t_n} e^{\int_0^s h(u) du} \omega(s) ds < \frac{\delta_1}{8K} \tag{2.13}$$

for all  $n \geq k$ , where  $0 < \delta_1 < 1$  satisfies  $8\delta_1^2 K^2 e^{2J} + (\alpha^2 + \varepsilon) < 1$ .

We now consider the solution  $x(t) = x(t, t_k, \phi)$  of (2.6) with  $\|\phi(t_k)\| = \delta_1$  and  $\|\phi(t)\| < \delta_1$  for  $t < t_k$ . By the similar method in (2.12), we have  $E|x(t)|^2 < 1$  for  $t \geq t_k$ . We may choose  $\phi$  so that

$$G(t_k) := \phi(t_k) - q(t_k)f(\phi(t_k - \tau(t_k))) - \int_{t_k-\tau(t_k)}^{t_k} (a(s) + h(s))\phi(s) ds \geq \frac{\delta_1}{2}. \tag{2.14}$$

It follows from (2.9), (2.13) and (2.14) with  $x(t) = (Px)(t)$  that for  $n \geq k$ ,

$$\begin{aligned}
 & E \left| x(t_n) - q(t_n)f(x(t_n - \tau(t_n))) - \int_{t_n - \tau(t_n)}^{t_n} (a(s) + h(s))x(s) ds \right|^2 \\
 & \geq G^2(t_k)e^{-2 \int_{t_k}^{t_n} h(u) du} - 2G(t_k)e^{-\int_{t_k}^{t_n} h(u) du} \int_{t_k}^{t_n} e^{-\int_s^{t_n} h(u) du} \omega(s) ds \\
 & \geq G(t_k)e^{-\int_{t_k}^{t_n} h(u) du} \\
 & \quad \times \left( G(t_k)e^{-\int_{t_k}^{t_n} h(u) du} - 2e^{-\int_0^{t_n} h(u) du} \int_{t_k}^{t_n} e^{\int_0^s h(u) du} \omega(s) ds \right) \\
 & \geq G(t_k)e^{-2 \int_{t_k}^{t_n} h(u) du} \left( G(t_k) - 2e^{-\int_0^{t_k} h(u) du} \int_{t_k}^{t_n} e^{\int_0^s h(u) du} \omega(s) ds \right) \\
 & \geq \frac{\delta_1}{2} e^{-2 \int_{t_k}^{t_n} h(u) du} \left( \frac{\delta_1}{2} - 2K \int_{t_k}^{t_n} e^{\int_0^s h(u) du} \omega(s) ds \right) \\
 & \geq \frac{\delta_1^2}{8} e^{-2J} > 0. \tag{2.15}
 \end{aligned}$$

If the zero solution of (2.6) is mean square asymptotically stable, then  $E|x(t)|^2 = E|x(t, t_k, \phi)|^2 \rightarrow 0$  as  $t \rightarrow \infty$ . Since  $t_n - \tau(t_n) \rightarrow \infty$ ,  $t_n - \delta(t_n) \rightarrow \infty$  as  $n \rightarrow \infty$  and conditions (ii) and (iii) hold,

$$\begin{aligned}
 & E \left| x(t_n) - q(t_n)f(x(t_n - \tau(t_n))) - \int_{t_n - \tau(t_n)}^{t_n} (a(s) + h(s))x(s) ds \right|^2 \rightarrow 0, \\
 & \text{as } n \rightarrow \infty,
 \end{aligned}$$

which contradicts (2.15). Thus (2.7) is necessary for Theorem 2.1. This completes the proof. □

**REMARK 2.2.** Theorem 2.1 is still true if condition (ii) is satisfied for  $t \geq t_a$  with some  $t_a \in R^+$ .

**REMARK 2.3.** Theorem 2.1 improves Theorem D under different conditions.

Choosing  $h(t) \equiv -a(t)$  in Theorem 2.1, we have the following corollary.

**COROLLARY 2.4.** Suppose that  $\tau$  is differentiable, and there exist constants  $L > 0$ ,  $\alpha \in (0, 1)$ ,  $\beta \in (0, 1]$  such that for  $t \geq 0$ :

- (i)  $\liminf_{t \rightarrow \infty} \int_0^t -a(s) ds > -\infty$ ;
- (ii)  $\beta|q(t)| + \beta \int_0^t e^{\int_s^t a(u) du} |b(s) + q(s)a(s)| ds + 2(\int_0^t e^{2 \int_s^t a(u) du} (|c(s)| + \beta|e(s)|)^2 ds)^{1/2} \leq \alpha < 1$ ;
- (iii)  $|f(x) - f(y)| \leq \beta|x - y|$  and  $|g(x) - g(y)| \leq \beta|x - y|$  for all  $x, y \in F(L)$  with  $f(0) = g(0) = 0$ .

Then the zero solution of (2.6) is mean square asymptotically stable if and only if  $\int_0^t a(s) ds \rightarrow \infty$  as  $t \rightarrow \infty$ .

Let  $h(t) \equiv -b(p(t))$  in Theorem 2.1. Then we have the following corollary.

**COROLLARY 2.5.** Suppose that  $\tau$  is differentiable, the inverse function  $p(t)$  of  $t - \tau(t)$  exists, and there exist constants  $L > 0$ ,  $\alpha \in (0, 1)$  and  $\beta \in (0, 1]$  such that for  $t \geq 0$ :

- (i)  $\liminf_{t \rightarrow \infty} \int_0^t -b(p(s)) ds > -\infty$ ;
- (ii)

$$\begin{aligned} & \beta|q(t)| + \int_{t-\tau(t)}^t |a(s) - b(p(s))| ds \\ & + \int_0^t e^{\int_s^t b(p(u)) du} |b(p(s))| \int_{s-\tau(s)}^s |a(u) - b(p(u))| du ds \\ & + \int_0^t e^{\int_s^t b(p(u)) du} (|(a(s - \tau(s)) - b(s))(1 - \tau'(s))| \\ & \quad + \beta|b(s) + q(s)b(p(s))|) ds \\ & + 2 \left( \int_0^t e^{2 \int_s^t b(p(u)) du} (|c(s)| + \beta|e(s)|)^2 ds \right)^{1/2} \leq \alpha < 1; \end{aligned}$$

- (iii)  $|f(x) - f(y)| \leq \beta|x - y|$  and  $|g(x) - g(y)| \leq \beta|x - y|$  for all  $x, y \in F(L)$  with  $f(0) = g(0) = 0$ .

Then the zero solution of (2.6) is mean square asymptotically stable if and only if  $\int_0^t b(p(s)) ds \rightarrow \infty$  as  $t \rightarrow \infty$ .

**REMARK 2.6.** When  $q(t) \equiv a(t) \equiv c(t) \equiv e(t) \equiv 0$ ,  $f(x) \equiv g(x) \equiv x$  with  $\beta \equiv 1$ , and  $b(t) \equiv -\bar{b}(t)$ , from the proof process of Theorem 2.1, we know that the conclusion of Corollary 2.5 still holds if condition (ii) is replaced by (2.2). Therefore, Corollary 2.5 is a generalization of Theorem B.

When  $q(t) \equiv c(t) \equiv e(t) \equiv 0$  and  $a(t) \equiv -\bar{a}(t)$  in Theorem 2.1, we obtain the following corollary.

**COROLLARY 2.7.** Suppose that  $\tau$  is differentiable, and there exist continuous functions  $h(t) : [0, \infty) \rightarrow R$  and constants  $L > 0$ ,  $\alpha \in (0, 1)$ ,  $\beta \in (0, 1]$  such that for  $t \geq 0$ :

- (i)  $\liminf_{t \rightarrow \infty} \int_0^t h(s) ds > -\infty$ ;
- (ii)  $\int_{t-\tau(t)}^t |h(s) - \bar{a}(s)| ds + \int_0^t e^{-\int_s^t h(u) du} |h(s)| \int_{s-\tau(s)}^s |h(u) - \bar{a}(u)| du ds + \int_0^t e^{-\int_s^t h(u) du} (|(h(s - \tau(s)) - \bar{a}(s - \tau(s)))(1 - \tau'(s))| + \beta|b(s)|) ds \leq \alpha < 1$ ;
- (iii) if  $|x| \leq L, |y| \leq L$  and  $|g(x) - g(y)| \leq \beta|x - y|$  for all  $x, y \in R$  with  $g(0) = 0$ .

Then the zero solution of (2.3) is asymptotically stable if and only if  $\int_0^t h(s) ds \rightarrow \infty$  as  $t \rightarrow \infty$ .

**REMARK 2.8.** Choosing  $h(t) \equiv \bar{a}(t)$  and  $\beta \equiv 1$ , Corollary 2.7 reduces to Theorem C.

### 3. Two Examples

In this section, we give two examples to illustrate the applications of our main results.

**EXAMPLE 3.1.** Consider the half-linear neutral stochastic delay differential equation

$$d\left(x(t) - \frac{1}{3}x^2\left(t - \frac{t}{4}\right)\right) = \left(-2x(t) + \frac{2}{3}x^2\left(t - \frac{t}{4}\right)\right) dt + \left(\frac{1}{4}x(t) + \frac{3}{8}x^3\left(t - \frac{t}{2}\right)\right) dW(t). \tag{3.1}$$

Then the zero solution of (3.1) is mean square asymptotically stable.

**PROOF.** It is easy to verify that  $t - \tau(t) = t - t/4 \rightarrow \infty$  and  $t - \delta(t) = t - t/2 \rightarrow \infty$  as  $t \rightarrow \infty$ . Since  $|x^2| \leq |x|$  and  $|x^3| \leq |x|$  when  $|x| \leq 1$  for  $x \in \mathbb{R}$ , we can choose  $L = 1/2$  and  $\beta = 1$  such that condition (iii) of Theorem 2.1 holds. Choosing  $h(t) = 2$  in Theorem 2.1, we have  $|q(t)| = 1/3$ ,

$$\begin{aligned} \int_{t-\tau(t)}^t |a(s) + h(s)| ds &= \int_0^t e^{-\int_s^t h(u) du} |h(s)| \int_{s-\tau(s)}^s |a(u) + h(u)| du ds = 0, \\ \int_0^t e^{-\int_s^t h(u) du} (|a(s - \tau(s)) + h(s - \tau(s))|(1 - \tau'(s))| &+ |b(s) - q(s)h(s)|) ds = 0, \end{aligned}$$

and

$$\begin{aligned} 2\left(\int_0^t e^{-2\int_s^t h(u) du} (|c(s)| + |e(s)|)^2 ds\right)^{1/2} &= \frac{5}{4}\left(\int_0^t e^{-4(t-s)} ds\right)^{1/2} \\ &= \frac{5}{8}(1 - e^{-4t})^{1/2} \leq \frac{5}{8}. \end{aligned}$$

It is easy to check that  $\int_0^t h(s) ds \rightarrow \infty$  as  $t \rightarrow \infty$ . Let  $\alpha = 1/3 + 5/8$ . Then  $\alpha = 23/24 < 1$  and the zero solution of (3.1) is mean square asymptotically stable by Theorem 2.1. □

**EXAMPLE 3.2.** Consider the delay differential equation

$$x'(t) = -\frac{19}{100}x(t) + \frac{1}{5} \sin\left(\frac{1}{10}x(t - e^{-t})\right). \tag{3.2}$$

Then the zero solution of (3.2) is asymptotically stable.

**PROOF.** It is easy to verify that  $t - \tau(t) = t - e^{-t} \rightarrow \infty$  as  $t \rightarrow \infty$ . Because  $|\sin \frac{1}{10}x| \leq \frac{1}{10}|x|$  for  $x \in R$ , we can choose  $\beta = \frac{1}{10}$  and  $L$  for any positive constant. Then condition (iii) of Corollary 2.7 is satisfied. Choosing  $h(t) \equiv 0.29$  in Corollary 2.7, we have

$$\begin{aligned} \int_{t-\tau(t)}^t |h(s) - \bar{a}(s)| ds &= \int_{t-e^{-t}}^t (0.29 - 0.19) ds \rightarrow 0.1e^{-t} \leq 0.1, \\ \int_0^t e^{-\int_s^t h(u) du} |h(s)| \int_{s-\tau(s)}^s |h(u) - \bar{a}(u)| du ds \\ &\leq \int_0^t e^{-0.29(t-s)} (0.29 \times 0.1) ds \leq 0.1 \end{aligned}$$

and

$$\begin{aligned} \int_0^t e^{-\int_s^t h(u) du} (|(h(s - \tau(s)) - \bar{a}(s - \tau(s)))(1 - \tau'(s))| + \beta|b(s)|) ds \\ = \int_0^t e^{-0.29(t-s)} \left[ (0.29 - 0.19)(1 + e^{-s}) + \frac{1}{10} \times \frac{1}{5} \right] ds \leq 0.7587. \end{aligned}$$

It is easy to see that all the conditions of Corollary 2.7 hold for  $\alpha = 0.1 + 0.1 + 0.7587 = 0.9587 < 1$ . Thus Corollary 2.7 implies that the zero solution of (3.2) is asymptotically stable.  $\square$

However, Theorem C cannot be used to verify that the zero solution of (3.2) is asymptotically stable. In fact, noticing that  $|\sin \frac{1}{10}x - \sin \frac{1}{10}y| \leq |x - y|$  for all  $x, y \in R$ ,  $b(t) \equiv 0.2$ ,  $\bar{a}(t) \equiv 0.19$  and

$$\int_0^t e^{-\int_s^t \bar{a}(u) du} |b(s)| ds = 0.2 \int_0^t e^{-0.19(t-s)} ds < 1.0527,$$

we can see that the condition (2.4) of Theorem C does not hold with  $\alpha = 1.05327 > 1$ .

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