

## POSITIVE SOLUTIONS TO $p(x)$ -LAPLACIAN–DIRICHLET PROBLEMS WITH SIGN-CHANGING NON-LINEARITIES

XIANLING FAN

Department of Mathematics, Lanzhou City University, Lanzhou 730070, PR China  
Department of Mathematics, Lanzhou University, Lanzhou 730000, PR China  
e-mail: fanxl@lzu.edu.cn

(Received 8 March 2009; revised 14 January 2010; accepted 21 February 2010)

**Abstract.** Consider the  $p(x)$ -Laplacian–Dirichlet problem with sign-changing non-linearity of the form

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p(x)-2} \nabla u) + m(x) |u|^{p(x)-2} u = \lambda a(x) f(u) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where  $\Omega \subset \mathbb{R}^N$  is a bounded domain,  $p \in C^0(\overline{\Omega})$  and  $\inf_{x \in \overline{\Omega}} p(x) > 1$ ,  $m \in L^\infty(\Omega)$  is non-negative,  $f: \mathbb{R} \rightarrow \mathbb{R}$  is continuous and  $f(0) > 0$ , the coefficient  $a \in L^\infty(\Omega)$  is sign-changing in  $\Omega$ . We give some sufficient conditions to assure the existence of a positive solution to the problem for sufficiently small  $\lambda > 0$ . Our results extend the corresponding results established in the  $p$ -Laplacian case to the  $p(x)$ -Laplacian case.

2010 *Mathematics Subject Classification.* 35J70.

**1. Introduction.** In this paper, we consider the existence of positive solutions for the following  $p(x)$ -Laplacian–Dirichlet problem of the form

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p(x)-2} \nabla u) + m(x) |u|^{p(x)-2} u = \lambda a(x) f(u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.1)$$

where  $\Omega$  is a bounded smooth domain in  $\mathbb{R}^N$ ,  $\lambda > 0$ , the function  $a(x)$  is allowed to change sign,  $p$ ,  $m$  and  $f$  satisfy the following conditions, respectively:

(P)  $p \in C^0(\overline{\Omega})$  and  $1 < p_- := \inf_{x \in \overline{\Omega}} p(x) \leq p_+ := \sup_{x \in \overline{\Omega}} p(x) < +\infty$ .

(M)  $m \in L^\infty(\Omega)$  and  $m(x) \geq 0$  for  $x \in \Omega$ .

(F)  $f: \mathbb{R} \rightarrow \mathbb{R}$  is continuous and  $f(0) > 0$ .

Problem (1.1) involves the variable exponent  $p(\cdot)$ . The study of various mathematical problems with variable exponent has received considerable attention in recent years. For a survey of this area see [4, 7, 20, 28], and for the application background see [21, 27]. The existence and multiplicity of solutions to the  $p(x)$ -Laplacian equations under various hypotheses were studied by many authors (see e.g. [3, 8, 10–12, 16, 23–26, 29, 30]). In this paper, we study the existence of a positive solution to problem (1.1) for sufficiently small  $\lambda > 0$ .

The existence of positive solutions to problem (1.1) when  $p(x) \equiv p$  (a constant) was obtained in [2, 5, 6, 17, 18]. In [2, 5, 6, 17] the case that  $p = 2$  and  $m = 0$  was investigated, where in [5] the radially symmetric case was investigated. Hai and Xu [18] investigated the case that  $p \in (1, \infty)$  and  $m \geq 0$ . In [2, 5, 6, 17, 18] the authors gave

some sufficient conditions on  $a(x)$  to assure the existence of a positive solution for small values of  $\lambda$ . We denote by  $S_p(a)$  the unique solution of the problem

$$\begin{cases} -\operatorname{div}(|\nabla z|^{p-2} \nabla z) + m|z|^{p-2} z = a(x) & \text{in } \Omega, \\ z = 0 & \text{on } \partial\Omega, \end{cases} \tag{1.2}$$

for  $a \in L^\infty(\Omega)$ . Then the condition given in [6, 17] is

$(A_\varepsilon^\geq)$  there exists  $\varepsilon > 0$  such that  $S_2(a^+ - (1 + \varepsilon)a^-) \geq 0$  in  $\Omega$ , where  $a^+(x) = \max\{0, a(x)\}$  and  $a^-(x) = a^+(x) - a(x)$ .

The condition given in [2, 18] is

$(A_*)$   $S_p(a) > 0$  in  $\Omega$  and  $\frac{\partial S_p(a)}{\partial \nu} < 0$  on  $\partial\Omega$ , where  $\nu$  denotes the unit outward normal vector.

The  $p(x)$ -Laplacian is an extension of the  $p$ -Laplacian. An essential difference between them is that the  $p$ -Laplacian operator is  $(p - 1)$ homogeneous, that is,  $\Delta_p(\lambda u) = \lambda^{p-1} \Delta_p u$  for every  $\lambda > 0$ , but the  $p(x)$ -Laplacian operator, when  $p(x)$  is not a constant, is not homogeneous. Our purpose is to extend the corresponding results established in [2, 5, 6, 17, 18] on the  $p$ -Laplacian problems to the  $p(x)$ -Laplacian case; however, in this respect we face an essential difficulty due to the inhomogeneity of the  $p(x)$ -Laplacian operator. It is well known that, in the case that  $p(x) \equiv p$  (a constant), if  $z$  is a positive solution of (1.2), then, by the  $(p - 1)$ homogeneity of the  $p$ -Laplacian operator, for any  $\lambda > 0$ ,  $\lambda^{\frac{1}{p-1}} z$  is exactly a positive solution of the problem

$$\begin{cases} -\operatorname{div}(|\nabla z|^{p-2} \nabla z) + m|z|^{p-2} z = \lambda a(x) & \text{in } \Omega, \\ z = 0 & \text{on } \partial\Omega. \end{cases} \tag{1.3}$$

This fact plays an important role in [2, 5, 6, 17, 18]. It is a pity that, in the  $p(x)$ -Laplacian case, such fact does not hold. To see this, in Section 2 we give an example which shows that there are  $p(x)$  and  $a(x)$  such that the corresponding problem (1.2) with  $p = p(x)$  has a positive solution, but for sufficiently small  $\lambda > 0$ , the corresponding problem (1.3) with  $p = p(x)$  has no positive solution. Such an example shows that the condition of the same form as  $(A_\varepsilon^\geq)$  or  $(A_*)$  is not suitable for the variable exponent problems considered in the present paper. In order to achieve our goal we must find some new conditions which are different from  $(A_\varepsilon^\geq)$  and  $(A_*)$  in form, but include  $(A_\varepsilon^\geq)$  and  $(A_*)$  as a special case when  $p$  is a constant.

In Section 2, we give some preliminaries about the  $p(x)$ -Laplacian and also give an example as mentioned above. In Section 3, we give some sufficient conditions for the existence of a positive solution to problem (1.1) for sufficiently small  $\lambda > 0$ . Our results are a generalization of the corresponding results established in [2, 5, 6, 17, 18] for the  $p$ -Laplacian case to the  $p(x)$ -Laplacian case.

**2. Preliminaries and example.** In this paper, if there is no other explanation, it will always be assumed that  $\Omega$  is a bounded smooth domain in  $\mathbb{R}^N$  and  $p$  and  $m$  satisfy (P) and (M).

The variable exponent Lebesgue space  $L^{p(\cdot)}(\Omega)$  is defined by

$$L^{p(\cdot)}(\Omega) = \left\{ u \mid u : \Omega \rightarrow \mathbb{R} \text{ is measurable, } \int_\Omega |u|^{p(x)} dx < \infty \right\}$$

with the norm

$$|u|_{L^{p(\cdot)}(\Omega)} = |u|_{p(\cdot)} = \inf \left\{ \sigma > 0 \mid \int_{\Omega} \left| \frac{u}{\sigma} \right|^{p(x)} dx \leq 1 \right\}.$$

The variable exponent Sobolev space  $W^{1,p(\cdot)}(\Omega)$  is defined by

$$W^{1,p(\cdot)}(\Omega) = \{u \in L^{p(\cdot)}(\Omega) \mid |\nabla u| \in L^{p(\cdot)}(\Omega)\}$$

with the norm

$$\|u\|_{W^{1,p(\cdot)}(\Omega)} = \|u\|_{1,p(\cdot)} = |u|_{p(\cdot)} + |\nabla u|_{p(\cdot)}.$$

Denote by  $W_0^{1,p(\cdot)}(\Omega)$  the closure of  $C_0^\infty(\Omega)$  in  $W^{1,p(\cdot)}(\Omega)$ .  $|\nabla u|_{p(\cdot)}$  is an equivalent norm on  $W_0^{1,p(\cdot)}(\Omega)$ . We refer to [4, 7, 14, 19, 22, 28] for the elementary properties of the space  $W^{1,p(x)}(\Omega)$ .

$u \in W_0^{1,p(\cdot)}(\Omega)$  is said to be a (weak) solution of (1.1) if

$$\int_{\Omega} (|\nabla u|^{p(x)-2} \nabla u \nabla v + m(x) |u|^{p(x)-2} uv) dx = \lambda \int_{\Omega} a(x) f(u) v dx, \forall v \in W_0^{1,p(\cdot)}(\Omega).$$

Define  $T = T_{p(\cdot)} : W_0^{1,p(\cdot)}(\Omega) \rightarrow (W_0^{1,p(\cdot)}(\Omega))^*$  by

$$T(u)v = \int_{\Omega} (|\nabla u|^{p(x)-2} \nabla u \nabla v + m(x) |u|^{p(x)-2} uv) dx, \forall u, v \in W_0^{1,p(\cdot)}(\Omega).$$

**PROPOSITION 2.1.** ([12]) *The mapping  $T : W_0^{1,p(\cdot)}(\Omega) \rightarrow (W_0^{1,p(\cdot)}(\Omega))^*$  is a strictly monotone homeomorphism, and is of type  $(S_+)$ , namely for any sequence  $\{u_n\} \subset W_0^{1,p(\cdot)}(\Omega)$  for which  $u_n \rightharpoonup u$  in  $W_0^{1,p(\cdot)}(\Omega)$  and  $\overline{\lim}_{n \rightarrow \infty} T(u_n)(u_n - u) \leq 0$ ,  $u_n$  must converge strongly to  $u$  in  $W_0^{1,p(\cdot)}(\Omega)$ , where ‘ $\rightharpoonup$ ’ denotes the weak convergence in  $W_0^{1,p(\cdot)}(\Omega)$ .*

Denote by  $S = S_{p(\cdot)}$  the inverse mapping of  $T$ . Then the mapping  $S = T^{-1} : (W_0^{1,p(\cdot)}(\Omega))^* \rightarrow W_0^{1,p(\cdot)}(\Omega)$  is a strictly monotone homeomorphism. We often view  $S$  as the solution operator for the problem

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p(x)-2} \nabla u) + m(x) |u|^{p(x)-2} u = h(x) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \tag{2.1}$$

namely, we denote by  $S(h)$  the (unique) solution of (2.1), and according to the different ranges of  $h$  and  $S(h)$ , we may have the different understandings of the mapping  $S$ .

**PROPOSITION 2.2.** (1) *For every  $h \in L^\infty(\Omega)$ , (2.1) has a unique solution  $S(h)$  and  $S(h) \in L^\infty(\Omega)$ .*

(2) (Comparison principle) The mapping  $S : L^\infty(\Omega) \rightarrow L^\infty(\Omega)$  is increasing, that is,  $S(h) \leq S(g)$  in  $\Omega$  if  $h \leq g$  in  $\Omega$ .

(3) The mapping  $S : L^\infty(\Omega) \rightarrow L^\infty(\Omega)$  is bounded, and there is a positive constant  $C_*$ , dependent on  $p_+, p_-, N$  and  $|\Omega|$ , such that

$$|S(h)|_{L^\infty(\Omega)} \leq C_* \max \left\{ |h|_{L^\infty(\Omega)}^{\frac{1}{p_+-1}}, |h|_{L^\infty(\Omega)}^{\frac{1}{p_--1}} \right\} \text{ for all } h \in L^\infty(\Omega).$$

*Proof.* For statement (1) see [13], and for statement (2) see [10]. Here we only prove statement (3). First, let us consider the case that  $h(x) \equiv M$  (a constant). By [10, Lemma 2.1], there exists a positive constant  $C_*$ , dependent on  $p_+, p_-, N$  and  $|\Omega|$ , such that

$$|S(M)|_{L^\infty(\Omega)} \leq C_* \max \left\{ |M|^{\frac{1}{p_+-1}}, |M|^{\frac{1}{p_--1}} \right\} \text{ for all } M \in \mathbb{R}.$$

(Note that Lemma 2.1 in [10] was proved for the case that  $m = 0$ , in fact, the proof of the same result in the case when  $m \neq 0$  is similar and the constant  $C_*$  is independent of  $m$ ). Then, for any  $h \in L^\infty(\Omega)$ , statement (3) follows from the above inequality for the constant function  $M$  and the comparison principle (2).  $\square$

$p$  is said to be Hölder continuous on  $\bar{\Omega}$  if there exist constants  $\alpha \in (0, 1)$  and  $L > 0$  such that  $|p(x) - p(y)| \leq L|x - y|^\alpha$  for all  $x, y \in \bar{\Omega}$ .  $p$  is said to be Log-Hölder continuous on  $\bar{\Omega}$  if there exists a positive constant  $L$  such that

$$|p(x) - p(y)| \leq \frac{L}{-\ln|x - y|} \text{ for all } x, y \in \bar{\Omega} \text{ with } |x - y| \leq \frac{1}{2}.$$

It is obvious that Lipschitz continuity  $\implies$  Hölder continuity  $\implies$  Log-Hölder continuity.

**PROPOSITION 2.3.** (1) ([1, 10, 13]) When  $p$  is Log-Hölder continuous on  $\bar{\Omega}$ , for every  $h \in L^\infty(\Omega)$ ,  $S(h)$  is Hölder continuous on  $\bar{\Omega}$ , and therefore, the mapping  $S : L^\infty(\Omega) \rightarrow C^0(\bar{\Omega})$  is completely continuous.

(2) ([1, 9, 10]) When  $p$  is Hölder continuous on  $\bar{\Omega}$ , for every  $h \in L^\infty(\Omega)$ ,  $S(h) \in C^{1,\alpha}(\bar{\Omega})$ , and therefore, the mapping  $S : L^\infty(\Omega) \rightarrow C^1(\bar{\Omega})$  is completely continuous.

**PROPOSITION 2.4.** ([15]) (A strong maximum principle) Suppose that  $p$  is Lipschitz continuous on  $\bar{\Omega}$ ,  $h \in L^\infty(\Omega)$ ,  $h(x) \geq 0$  for  $x \in \Omega$  and  $h(x) \not\equiv 0$  in  $\Omega$ . Then  $S(h) \in C^{1,\alpha}(\bar{\Omega})$ ,  $S(h)(x) > 0$  for  $x \in \Omega$  and  $\frac{\partial S(h)}{\partial \nu} < 0$  on  $\partial\Omega$ .

Propositions 2.1–2.4 are an extension of the corresponding results established in the case that  $p$  is a constant.

An essential difference between the  $p(x)$ -Laplacian and the  $p$ -Laplacian is that the  $p$ -Laplacian is homogeneous but the  $p(x)$ -Laplacian is inhomogeneous. As mentioned in Section 1, in the case that  $p$  is a constant, if for a fixed  $h \in L^\infty(\Omega)$  there holds  $S_p(h)(x) \geq 0$  (resp.  $S_p(h)(x) > 0$ ) for  $x \in \Omega$ , then for every  $\lambda > 0$ , there holds also  $S_p(\lambda h)(x) \geq 0$  (resp.  $S_p(\lambda h)(x) > 0$ ) for  $x \in \Omega$ . However, this is not the case when  $p(\cdot)$  is not a constant. To see this, we give an example as follows.

EXAMPLE. Let  $N = 1$ ,  $\Omega = (-1, 1)$ ,  $m = 0$ ,

$$p(r) = \begin{cases} 4, & \text{if } |r| \leq \frac{1}{4}, \\ -8\left(|r| - \frac{1}{2}\right) + 2, & \text{if } \frac{1}{4} \leq |r| \leq \frac{1}{2}, \\ 2, & \text{if } \frac{1}{2} \leq |r| \leq 1, \end{cases}$$

$$h_\varepsilon(r) = \begin{cases} -\varepsilon, & \text{if } |r| \leq \frac{1}{2}, \\ 1 & \text{if } \frac{1}{2} < |r| \leq 1. \end{cases}$$

where  $\varepsilon$  is a small positive number.

For this example we have the following

PROPOSITION 2.5. *In the above example, there exists  $\varepsilon > 0$  sufficiently small such that  $S_{p(\cdot)}(h_\varepsilon) > 0$  in  $\Omega$  and*

$$\inf_{r \in (-1, 1)} S_{p(\cdot)}(\lambda h_\varepsilon)(r) < 0 \quad \text{for sufficiently small } \lambda > 0. \tag{2.2}$$

*Proof.* By the definition of  $p(r)$ ,  $p$  is Lipschitz continuous on  $\overline{\Omega}$ . Noting that when  $\varepsilon = 0$ ,  $h_0 \geq 0$  and  $h_0 \not\equiv 0$  in  $\Omega$ , by Proposition 2.4,  $S(h_0) \in C^1(\overline{\Omega})$ ,  $S(h_0)(x) > 0$  for  $x \in \Omega$  and  $\frac{\partial S(h_0)}{\partial \nu} < 0$  on  $\partial\Omega$ . By 2) of Proposition 2.3, for sufficiently small  $\varepsilon > 0$ , we have  $S(h_\varepsilon) \in C^1(\overline{\Omega})$ ,  $S(h_\varepsilon)(x) > 0$  for  $x \in \Omega$  and  $\frac{\partial S(h_\varepsilon)}{\partial \nu} < 0$  on  $\partial\Omega$ . Now let  $\varepsilon \in (0, 1)$  be small enough. For any  $\lambda > 0$ , denote  $u_\lambda = S(\lambda h_\varepsilon)$ . Then, since  $p(\cdot)$  and  $h_\varepsilon(\cdot)$  are radially symmetric,  $u_\lambda$  is radially symmetric and it is the unique solution of the following problem:

$$\begin{cases} -(|u'_\lambda(r)|^{p(r)-2}u'_\lambda(r))' = \lambda h_\varepsilon(r) & \text{in } (0, 1) \\ u_\lambda(1) = 0, \quad u'_\lambda(0) = 0. \end{cases} \tag{2.3}$$

Indeed, problem (2.3) has a unique solution  $u_\lambda(r)$  for  $r \in [0, 1]$ , which is expressed by formula (2.4). Setting  $u_\lambda(r) = u_\lambda(-r)$  for  $r \in [-1, 0]$ , then the function  $u_\lambda(r)$ ,  $r \in [-1, 1]$ , is radially symmetric and  $u_\lambda = S(\lambda h_\varepsilon)$ .

Denote  $\Phi(r, \xi) = |\xi|^{p(r)-2}\xi$  for  $r \in [-1, 1]$  and  $\xi \in \mathbb{R}$ . Then for each  $r \in [-1, 1]$ ,  $\Phi(r, \cdot) : \mathbb{R} \rightarrow \mathbb{R}$  is a homeomorphism. Denote by  $\Phi_r^{-1}$  the inverse mapping of  $\Phi(r, \cdot)$ , that is

$$\Phi_r^{-1}(\eta) = \begin{cases} \eta^{\frac{1}{p(r)-1}} & \text{if } \eta \geq 0 \\ -|\eta|^{\frac{1}{p(r)-1}} & \text{if } \eta < 0. \end{cases}$$

Then we have

$$u_\lambda(r) = \int_r^1 \Phi_t^{-1} \left( \int_0^t \lambda h_\varepsilon(s) ds \right) dt \quad \text{for } r \in [0, 1]. \tag{2.4}$$

From the definition of  $h_\varepsilon$  we have

$$\int_0^t h_\varepsilon(s) ds \begin{cases} < 0 & \text{if } 0 < r < \frac{1}{2} + \frac{1}{2}\varepsilon, \\ \geq 0 & \text{if } \frac{1}{2} + \frac{1}{2}\varepsilon \leq r \leq 1, \end{cases}$$

and thus by (2.4),

$$\begin{aligned}
 u_\lambda(0) &= \int_0^1 \Phi_t^{-1} \left( \int_0^t \lambda h_\varepsilon(s) ds \right) dt \\
 &= \int_0^{\frac{1}{2} + \frac{1}{2}\varepsilon} \Phi_t^{-1} \left( \int_0^t \lambda h_\varepsilon(s) ds \right) dt + \int_{\frac{1}{2} + \frac{1}{2}\varepsilon}^1 \Phi_t^{-1} \left( \int_0^t \lambda h_\varepsilon(s) ds \right) dt \\
 &< \int_0^{\frac{1}{4}} \Phi_t^{-1} \left( \int_0^t \lambda h_\varepsilon(s) ds \right) dt + \lambda \int_{\frac{1}{2} + \frac{1}{2}\varepsilon}^1 \left( t - \frac{1}{2} - \frac{1}{2}\varepsilon \right) dt \\
 &\leq - \int_0^{\frac{1}{4}} (\lambda \varepsilon t)^{\frac{1}{3}} dt + \lambda \int_{\frac{1}{2}}^1 \left( t - \frac{1}{2} \right) dt \\
 &= -\frac{3}{4} \left( \frac{1}{4} \right)^{\frac{4}{3}} \varepsilon^{\frac{1}{3}} \lambda^{\frac{1}{3}} + \frac{1}{8} \lambda.
 \end{aligned}$$

This shows that, when  $\lambda \leq 6^{\frac{3}{2}} \left( \frac{1}{4} \right)^2 \varepsilon^{\frac{1}{2}}$ ,  $u_\lambda(0) < 0$ , that is, (2.2) holds.

**3. Existence of positive solutions.** Let us continue to use the notations as in Sections 1 and 2.

Let

$$\begin{aligned}
 \Gamma_{p(\cdot)}^\geq &= \{h \in L^\infty(\Omega) \mid S_{p(\cdot)}(h)(x) \geq 0 \text{ for } x \in \Omega\}, \\
 \Gamma_{p(\cdot)}^\gt &= \{h \in L^\infty(\Omega) \mid S_{p(\cdot)}(h)(x) > 0 \text{ for } x \in \Omega\}.
 \end{aligned}$$

It is clear that when  $a = 0$ , problem (1.1) has only a zero solution, and when  $a \geq 0$  and  $a(x) \not\equiv 0$  for  $x \in \Omega$ , using the strong maximum principle, we can easily obtain the existence of a positive solution to (1.1) for small  $\lambda > 0$ . In this section, we assume that  $a$  is sign-changed, that is,  $a$  satisfies the following condition:

$$(A_\infty^\pm) \quad a \in L^\infty(\Omega), a^+ \neq 0 \text{ and } a^- \neq 0.$$

**THEOREM 3.1.** *Let (P), (M), (F) and  $(A_\infty^\pm)$  hold. Suppose the following condition is satisfied:*

$(A_{\varepsilon,\delta}^\geq)$  (resp.  $(A_{\varepsilon,\delta}^\gt)$ ) *There are  $\varepsilon > 0$  and  $\delta > 0$  such that*

$$\mu(a^+ - (1 + \varepsilon)a^-) \in \Gamma_{p(\cdot)}^\geq \text{ (resp. } \in \Gamma_{p(\cdot)}^\gt) \text{ for } \mu \in (0, \delta].$$

*Then for sufficiently small  $\lambda > 0$ , problem (1.1) has a non-negative (resp. a positive) solution.*

*Proof.* We only consider the case of  $(A_{\varepsilon,\delta}^\gt)$  because the proof for the case of  $(A_{\varepsilon,\delta}^\geq)$  is similar. Let  $\varepsilon$  and  $\delta$  be as in condition  $(A_{\varepsilon,\delta}^\gt)$ . Define  $\tilde{f} : \mathbb{R} \rightarrow \mathbb{R}$  by

$$\tilde{f}(t) = \begin{cases} f(t) & \text{for } |t| \leq 1, \\ f(-1) & \text{for } t < -1, \\ f(1) & \text{for } t > 1. \end{cases}$$

Consider the following problem:

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p(x)-2} \nabla u) + m(x) |u|^{p(x)-2} u = \lambda a(x) \tilde{f}(u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \tag{3.1}$$

Define  $\tilde{F}(t) = \int_0^t \tilde{f}(s) ds$  for  $t \in \mathbb{R}$  and

$$J_\lambda(u) = \int_\Omega \left( \frac{1}{p(x)} |\nabla u|^{p(x)} + \frac{m(x)}{p(x)} |u|^{p(x)} - \lambda a(x) \tilde{F}(u) \right) dx, \quad \forall u \in W_0^{1,p(\cdot)}(\Omega).$$

Obviously, there exists a positive constant  $C$  such that  $|\tilde{f}(t)| \leq C$  for all  $t \in \mathbb{R}$ , this implies that  $|\tilde{F}(t)| \leq C|t|$  for all  $t \in \mathbb{R}$ . Noting that  $p_- > 1$ ,  $m \in L^\infty(\Omega)$ ,  $m(x) \geq 0$  and  $a \in L^\infty(\Omega)$ , we can see that, for each  $\lambda > 0$ , the functional  $J_\lambda : W_0^{1,p(\cdot)}(\Omega) \rightarrow \mathbb{R}$  is coercive and sequentially weakly lower semi-continuous, and consequently,  $J_\lambda$  has a global minimizer  $u_\lambda$  which is a weak solution of problem (3.1). Noting that  $|\lambda a(x) \tilde{f}(u_\lambda)|_{L^\infty(\Omega)} \rightarrow 0$  as  $\lambda \rightarrow 0$ , by 3) of Proposition 2.2, we have that  $|u_\lambda|_{L^\infty(\Omega)} \rightarrow 0$  as  $\lambda \rightarrow 0$ . Now we assume that  $\lambda > 0$  is small enough such that  $|u_\lambda|_{L^\infty(\Omega)} \leq 1$ . Then  $\tilde{f}(u_\lambda) = f(u_\lambda)$  and so  $u_\lambda$  is a solution of problem (1.1). Set  $\gamma = \frac{\varepsilon}{2+\varepsilon}$ . Since  $f$  is continuous at 0 and  $f(0) > 0$ , there is  $\rho \in (0, 1)$  such that

$$-f(0)\gamma < f(\xi) - f(0) < f(0)\gamma \quad \text{for } |\xi| \leq \rho.$$

Take  $\lambda_1 > 0$  small enough such that  $|u_\lambda|_{L^\infty(\Omega)} \leq \rho$  for  $\lambda \in (0, \lambda_1]$ . Then when  $\lambda \in (0, \lambda_1]$ ,

$$\begin{aligned} \lambda a(x) f(u_\lambda(x)) &= \lambda(a^+(x) - a^-(x)) f(u_\lambda(x)) \\ &= \lambda a^+(x) f(u_\lambda(x)) - \lambda a^-(x) f(u_\lambda(x)) \\ &\geq \lambda a^+(x) f(0)(1 - \gamma) - \lambda a^-(x) f(0)(1 + \gamma) \\ &= \lambda(1 - \gamma) f(0) \left( a^+(x) - \frac{1 + \gamma}{1 - \gamma} a^-(x) \right) \\ &= \lambda(1 - \gamma) f(0) (a^+(x) - (1 + \varepsilon) a^-(x)). \end{aligned} \tag{3.2}$$

Let  $\lambda_2 = \frac{\delta}{(1-\gamma)f(0)}$  and  $\lambda_3 = \min\{\lambda_1, \lambda_2\}$ . Then when  $\lambda \in (0, \lambda_3]$ , we have that  $\lambda(1 - \gamma) f(0) \leq \delta$ , and by condition  $(A_{\varepsilon, \delta}^>)$ ,

$$\lambda(1 - \gamma) f(0) (a^+(x) - (1 + \varepsilon) a^-(x)) \in \Gamma_{\rho(\cdot)}^>.$$

By (3.2) and the comparison principle,  $\lambda a(x) f(u_\lambda(x)) \in \Gamma_{\rho(\cdot)}^>$ , which shows that  $u_\lambda$  is a positive solution of problem (1.1). □

**REMARK 3.1.** In Section 1, we mentioned condition  $(A_\varepsilon^>)$  which was used in [6, 17] for the case that  $p = 2$ . We may extend it to the variable exponent case. For given variable exponent  $p(\cdot)$ , we say that  $a \in L^\infty(\Omega)$  satisfies condition  $(A_\varepsilon^>)$  (resp.  $(A_\varepsilon^>)$ ) if the following condition holds:

$(A_\varepsilon^>)$  (resp.  $(A_\varepsilon^>)$ ) there exists  $\varepsilon > 0$  such that

$$(a^+ - (1 + \varepsilon) a^-) \in \Gamma_{\rho(\cdot)}^> \quad (\text{resp. } \in \Gamma_{\rho(\cdot)}^>).$$

Obviously, condition  $(A_\varepsilon^>)$  implies condition  $(A_\varepsilon^>)$ . In the case when  $p = 2$ , from the strong comparison principle (i.e. the strong maximum principle) we may see that

when  $a \in L^\infty(\Omega) \setminus \{0\}$  satisfies condition  $(A_\varepsilon^\geq)$  with some  $\varepsilon > 0$ ,  $a$  must satisfy condition  $(A_{\varepsilon_1}^>)$  for every  $\varepsilon_1 \in (0, \varepsilon)$ . In other words, when  $p = 2$ ,  $(A_\varepsilon^\geq)$  and  $(A_\varepsilon^>)$  are essentially equivalent to each other. However, in the case when  $p \neq 2$ , because of lack of the general strong comparison principle, in general, condition  $(A_\varepsilon^\geq)$  does not imply condition  $(A_{\varepsilon_1}^>)$  for  $\varepsilon_1 \in (0, \varepsilon)$ . It is clear that, in the case when  $p$  is a constant,  $(A_\varepsilon^\geq)$  and  $(A_{\varepsilon,\delta}^\geq)$  (resp.  $(A_\varepsilon^>)$  and  $(A_{\varepsilon,\delta}^>)$ ) are essentially equivalent to each other. Thus our Theorem 3.1 is an extension of Theorem 2 in [6] and Theorem 1.1 in [17] to the  $p(x)$ -Laplacian case.

For  $h \in L^\infty(\Omega)$  and  $\varepsilon > 0$ , define

$$B_\infty(h, \varepsilon) = \{g \in L^\infty(\Omega) \mid |g - h|_{L^\infty(\Omega)} < \varepsilon\},$$

and for  $\delta > 0$ , define

$$K(B_\infty(h, \varepsilon), \delta) = \{\mu g \mid \mu \in (0, \delta] \text{ and } g \in B_\infty(h, \varepsilon)\}.$$

**COROLLARY 3.1.** *Let  $(P)$ ,  $(M)$ ,  $(F)$  and  $(A_\infty^\pm)$  hold. Suppose the following condition is satisfied:*

$(K_{\varepsilon,\delta}^\geq)$  (resp.  $(K_{\varepsilon,\delta}^>)$ ) *There are  $\varepsilon > 0$  and  $\delta > 0$  such that*

$$K(B_\infty(a, \varepsilon), \delta) \subset \Gamma_{p(\cdot)}^\geq \text{ (resp. } \subset \Gamma_{p(\cdot)}^>).$$

*Then  $a$  satisfies  $(A_{\varepsilon_1,\delta}^\geq)$  (resp.  $(A_{\varepsilon_1,\delta}^>)$ ) for some  $\varepsilon_1 > 0$ , and consequently, for sufficiently small  $\lambda > 0$ , problem (1.1) has a non-negative (resp. a positive) solution.*

*Proof.* Let  $a$  satisfy  $(K_{\varepsilon,\delta}^\geq)$  (resp.  $(K_{\varepsilon,\delta}^>)$ ). Take  $\varepsilon_1 \in (0, \frac{\varepsilon}{|a^-|_{L^\infty(\Omega)}})$ . Then

$$|(a^+ - (1 + \varepsilon_1)a^-) - a|_{L^\infty(\Omega)} = \varepsilon_1 |a^-|_{L^\infty(\Omega)} < \varepsilon,$$

which shows  $(a^+ - (1 + \varepsilon_1)a^-) \in B_\infty(a, \varepsilon)$ . For  $\mu \in (0, \delta]$ , we have that

$$\mu(a^+ - (1 + \varepsilon_1)a^-) \in K(B_\infty(h, \varepsilon), \delta) \subset \Gamma_{p(\cdot)}^\geq \text{ (resp. } \subset \Gamma_{p(\cdot)}^>).$$

This shows that  $(A_{\varepsilon_1,\delta}^\geq)$  (resp.  $(A_{\varepsilon_1,\delta}^>)$ ) is satisfied, and consequently, by Theorem 3.1, problem (1.1) has a non-negative (resp. a positive) solution for sufficiently small  $\lambda > 0$ . □

**REMARK 3.2.** Let  $p \in (1, \infty)$  be a constant and  $a \in L^\infty(\Omega)$  satisfy condition  $(A_*)$ , that is  $S_p(a) > 0$  in  $\Omega$  and  $\frac{\partial S_p(a)}{\partial \nu} < 0$  on  $\partial\Omega$ . Since  $S_p : L^\infty(\Omega) \rightarrow C^1(\overline{\Omega})$  is continuous, there exists  $\varepsilon > 0$  such that  $B_\infty(a, \varepsilon) \subset \Gamma_p^>$ . In this case, for any  $\delta > 0$ ,  $K(B_\infty(a, \varepsilon), \delta) \subset \Gamma_p^>$  holds. This shows that, when  $p$  is a constant, condition  $(A_*)$  implies condition  $(K_{\varepsilon,\delta}^\geq)$  for some  $\varepsilon > 0$  and any  $\delta > 0$ . Hence Theorem 1 of Hai and Xu [18] is a special case of Corollary 3.1.

Now let us consider the radially symmetric case. Suppose that the following condition is satisfied.

$(R)$   $\Omega = B(0, r_0) \subset \mathbb{R}^N$  is a ball,  $p(x) = p(|x|) = p(r)$  and  $a(x) = a(|x|) = a(r)$  are radially symmetric, and  $m = 0$ .



In this case, the solution of (1.1) is just the solution of the following problem:

$$\begin{cases} -(r^{N-1}|u'(r)|^{p(r)-2}u'(r))' = \lambda r^{N-1}a(r)f(u) & \text{in } (0, r_0), \\ u(r_0) = 0, \quad u'(0) = 0. \end{cases} \tag{3.3}$$

**COROLLARY 3.2.** *Let  $(P)$ ,  $(M)$ ,  $(F)$ ,  $(A_{\infty}^{\pm})$  and  $(R)$  hold. Suppose that  $a$  satisfies the following condition*

$(I_{\tau})$  *there exists  $\tau > 0$  such that*

$$\int_0^s t^{N-1} a^+(t) dt \geq (1 + \tau) \int_0^s t^{N-1} a^-(t) dt \quad \text{for } s \in (0, r_0].$$

*Then  $a$  satisfies condition  $(A_{\varepsilon, \delta}^{\geq})$  with  $\varepsilon = \frac{\tau}{2}$  and any  $\delta > 0$ , and consequently, for sufficiently small  $\lambda > 0$ , problem (1.1) has a positive solution.*

*Proof.* Put  $\varepsilon = \frac{\tau}{2}$ . Let any  $\mu > 0$  be given. Denote  $u = S_{p(\cdot)}(\mu(a^+ - (1 + \varepsilon)a^-))$ . Then

$$\begin{cases} -(r^{N-1}|u'(r)|^{p(r)-2}u'(r))' = \mu r^{N-1}(a^+ - (1 + \varepsilon)a^-) & \text{in } (0, r_0), \\ u(r_0) = 0, \quad u'(0) = 0. \end{cases}$$

Thus we have, for  $r \in (0, r_0]$ ,

$$\begin{aligned} -(r^{N-1}|u'(r)|^{p(r)-2}u'(r)) &= \mu \int_0^r t^{N-1} \left( a^+(t) - \left(1 + \frac{\tau}{2}\right) a^-(t) \right) dt \\ &\geq \frac{\mu\tau}{2} \int_0^r t^{N-1} a^-(t) dt \geq 0. \end{aligned}$$

This shows that  $u'(r) \leq 0$  for all  $r \in (0, r_0)$ . Noting that  $\int_0^{r_0} t^{N-1} a^-(t) dt > 0$ , we have  $u'(r_0) < 0$ , and therefore  $u(r) > 0$  for  $r \in [0, r_0)$  because  $u(r_0) = 0$ . This proves that  $\mu(a^+ - (1 + \varepsilon)a^-) \in \Gamma_{p(\cdot)}^{\geq}$  for any  $\mu > 0$ , that is, condition  $(A_{\varepsilon, \delta}^{\geq})$  with  $\varepsilon = \frac{\tau}{2}$  and any  $\delta > 0$  is satisfied, and consequently, by Theorem 3.1, problem (1.1) has a positive solution for sufficiently small  $\lambda > 0$ . □

**REMARK 3.3.** Condition  $(I_{\tau})$  was proposed by Cac, Fink and Gatica [5] for the case that  $p = 2$ . Note that condition  $(I_{\tau})$  used in this paper is the same as in [5], and it is independent of  $p(\cdot)$ . The verification of condition  $(I_{\tau})$  is often easy, for example, it is easy to see that, in the radially symmetric case, the function  $a$ , defined by

$$a(r) = \begin{cases} 1 & \text{if } |r| \leq \frac{r_0}{2}, \\ -\varepsilon & \text{if } \frac{r_0}{2} < |r| \leq r_0, \end{cases}$$

where  $\varepsilon \in (0, \frac{1}{2^{N-1}})$ , satisfies condition  $(I_{\tau})$  with  $\tau \in (0, \frac{1}{\varepsilon(2^N-1)} - 1)$ . Of course, as was mentioned in [2, 6],  $(I_{\tau})$  is a stronger condition to assure the existence of a positive solution to problem (3.4) for small values of  $\lambda$ .

**REMARK 3.4.** Let  $\Omega$ ,  $m$ ,  $p(\cdot)$  and  $a = h_{\varepsilon}$  be as in the example given in Section 2, where  $\varepsilon > 0$  is sufficiently small, and let  $f(t) = 1$  for all  $t \in \mathbb{R}$ . Proposition 2.5 shows

that, in this case, condition  $(A_*)$  as well as condition  $(A_{\varepsilon_1}^>)$  with small  $\varepsilon_1 > 0$  is satisfied but the corresponding problem (1.1) has no positive solution for sufficiently small  $\lambda > 0$ .

Finally, we give an example in which the condition  $(A_{\varepsilon,\delta}^>)$  put in Theorem 3.1 is satisfied but the condition  $(I_\tau)$  put in Corollary 3.2 is not satisfied.

EXAMPLE 3.5. Let  $N = 1, \Omega = (-1, 1), m = 0,$

$$p(r) = \begin{cases} 2, & \text{if } |r| \leq \frac{1}{2}, \\ 8\left(|r| - \frac{1}{2}\right) + 2, & \text{if } \frac{1}{2} \leq |r| \leq \frac{3}{4}, \\ 4, & \text{if } \frac{3}{4} \leq |r| \leq 1, \end{cases}$$

$$a(r) = \begin{cases} -\frac{1}{8}, & \text{if } |r| \leq \frac{1}{2}, \\ 1 & \text{if } \frac{1}{2} < |r| \leq 1. \end{cases}$$

Take  $\varepsilon = 1$ . we will show that there exists  $\delta > 0$  such that condition  $(A_{1,\delta}^>)$  is satisfied, that is,  $\mu(a^+ - (1 + 1)a^-) \in \Gamma_{p(\cdot)}^>$  for  $\mu \in (0, \delta]$ . Denote  $u_\mu = S_{p(\cdot)}(\mu(a^+ - 2a^-))$ . Then  $u_\lambda$  is radially symmetric and it is the unique solution of the following problem:

$$\begin{cases} -(|u'_\mu(r)|^{p(r)-2}u'_\mu(r))' = \mu(a^+ - 2a^-)(r) & \text{in } (0, 1), \\ u_\mu(1) = 0, \quad u'_\mu(0) = 0. \end{cases}$$

Thus, we have

$$u'_\mu(r) = -\Phi_r^{-1} \left( \int_0^r \mu(a^+(s) - 2a^-(s))ds \right) \quad \text{for } r \in (0, 1). \tag{3.4}$$

It is sufficient to prove that  $u_\mu(r) > 0$  for sufficiently small  $\mu > 0$  and all  $r \in [0, 1)$ . We may assume  $\mu \in (0, 1)$ . Noting that when  $r \in (0, \frac{1}{2}]$ ,

$$\int_0^r \mu(a^+(s) - 2a^-(s))ds = \int_0^r -\frac{1}{4}\mu ds = -\frac{1}{4}\mu r < 0,$$

and when  $r \in (\frac{1}{2}, 1)$ ,

$$\begin{aligned} \int_0^r \mu(a^+(s) - 2a^-(s))ds &= \int_0^{\frac{1}{2}} -\frac{1}{4}\mu ds + \int_{\frac{1}{2}}^r \mu ds \\ &= -\frac{1}{8}\mu + \left(r - \frac{1}{2}\right)\mu = \left(r - \frac{5}{8}\right)\mu, \end{aligned}$$

we can see that  $u'_\mu(r) > 0$  for  $r \in (0, \frac{5}{8})$ ,  $u'_\mu(r) < 0$  for  $r \in (\frac{5}{8}, 1)$ , and  $u_\mu$  attains its maximum at  $r = \frac{5}{8}$ . Since  $u_\mu(1) = 0$ , we have that  $u_\mu(r) > 0$  for  $r \in [\frac{5}{8}, 1)$  and

$$\begin{aligned} u_\mu \left(\frac{5}{8}\right) &> u_\mu \left(\frac{3}{4}\right) = -\int_{\frac{3}{4}}^1 u'_\mu(r)dr = \int_{\frac{3}{4}}^1 \Phi_r^{-1} \left( \left(r - \frac{5}{8}\right)\mu \right) dr \\ &\geq \int_{\frac{3}{4}}^1 \left(\frac{1}{8}\mu\right)^{\frac{1}{4-1}} dr = \frac{1}{4} \cdot \frac{1}{2}\mu^{\frac{1}{3}}. \end{aligned}$$

For  $r \in [0, \frac{5}{8}]$  we have

$$\begin{aligned} u_\mu(r) &\geq u_\mu(0) = u_\mu\left(\frac{5}{8}\right) - \int_0^{\frac{5}{8}} u'_\mu(r) dr \geq u_\mu\left(\frac{5}{8}\right) - \int_0^{\frac{5}{8}} \Phi_r^{-1}\left(\frac{1}{4}\mu\right) dr \\ &\geq u_\mu\left(\frac{5}{8}\right) - \int_0^{\frac{5}{8}} \left(\frac{1}{4}\mu\right)^{\frac{1}{p\left(\frac{5}{8}\right)-1}} dr \\ &= \frac{1}{8}\mu^{\frac{1}{3}} - \frac{5}{8} \cdot \left(\frac{1}{4}\mu\right)^{\frac{1}{2}}. \end{aligned}$$

It follows that when  $\mu \in (0, (\frac{2}{5})^6)$ ,  $u_\mu(r) > 0$  for all  $r \in [0, 1)$ . This shows that the condition  $(A_{1,\delta}^>)$  is satisfied for  $\delta \in (0, (\frac{2}{5})^6)$ . It is obvious that the condition  $(I_\tau)$  is not satisfied because for any  $\tau > 0$  and  $s \in (0, \frac{1}{2})$ ,

$$0 = \int_0^s a^+(t) dt < (1 + \tau) \int_0^s a^-(t) dt.$$

ACKNOWLEDGEMENTS. This research was supported by National Natural Science Foundation of China (10671084, 10971087). The author is grateful to the reviewer for valuable comments.

### REFERENCES

1. E. Acerbi and G. Mingione, Regularity results for a class of functionals with nonstandard growth, *Arch. Ration. Mech. Anal.* **156** (2001), 121–140.
2. G. A. Afrouzi and K. J. Brown, Positive solutions for a semilinear elliptic problem with sign-changing nonlinearity, *Nonlinear Anal.* **36** (1999), 507–510.
3. C. O. Alves and M. A. S. Souto, Existence of solutions for a class of problems in  $\mathbb{R}^N$  involving the  $p(x)$ -Laplacian, *Prog. Nonlinear Differ. Equ. Appl.* **66** (2005), 17–32.
4. S. Antontsev and S. Shmarev, Elliptic equations with anisotropic nonlinearity and nonstandard conditions, in *Handbook of differential equations, stationary partial differential equations*, vol. 3 (Chipot M. and Quittner P., Editors) (Elsevier B. V., North Holland, Amsterdam, 2006), 1–100.
5. N. P. Cac, A. M. Fink and J. A. Gatica, Nonnegative solutions to the radial Laplacian with nonlinearity that changes sign, *Proc. Amer. Math. Soc.* **123** (1995), 1393–1398.
6. N. P. Cac, J. A. Gatica and Y. Li, Positive solutions to semilinear problems with coefficient that changes sign, *Nonlinear Anal.* **37** (1999), 501–510.
7. L. Diening, P. Hasto and A. Nekvinda, Open problems in variable exponent Lebesgue and Sobolev spaces, in *FSDONA04 proceedings* (Drabek P. and Rakosnik J. Editors), The Conference held in Milovy, May 28–June 2, 2004, (Math. Inst. Acad. Sci. Czech Republic, Praha, 2005), 38–58.
8. T.-L. Dinu, On a nonlinear eigenvalue problem in Sobolev spaces with variable exponent, *Sib. Elektron. Mat. Izv.* **2** (2005), 208–217.
9. X. L. Fan, Global  $C^{1,\alpha}$  regularity for variable exponent elliptic equations in divergence form, *J. Differ. Equ.* **235** (2007), 397–417.
10. X. L. Fan, On the sub-supersolution method for  $p(x)$ -Laplacian equations, *J. Math. Anal. Appl.* **330** (2007), 665–682.
11. X. L. Fan, Remarks on eigenvalue problems involving the  $p(x)$ -Laplacian, *J. Math. Anal. Appl.* **352** (2009), 85–98.
12. X. L. Fan and Q. H. Zhang, Existence of solutions for  $p(x)$ -Laplacian Dirichlet problems, *Nonlinear Anal.* **52** (2003), 1843–1852.

13. X. L. Fan and D. Zhao, A class of De Giorgi type and Hölder continuity, *Nonlinear Anal.* **36** (1999), 295–318.
14. X. L. Fan and D. Zhao, On the spaces  $L^{p(x)}(\Omega)$  and  $W^{k,p(x)}(\Omega)$ , *J. Math. Anal. Appl.* **263** (2001), 424–446.
15. X. L. Fan, Y. Z. Zhao, Q. H. Zhang, A strong maximum principle for  $p(x)$ -Laplace equations, *Chin. Ann. Math. Ser. A* **24** (2003) 495–500 (in Chinese), English translation: *Chin. J. Contemp. Math.* **24** (2003), 277–282.
16. Y. Q. Fu and X. Zhang, A multiplicity result for  $p(x)$ -Laplacian problem in  $\mathbb{R}^N$ , *Nonlinear Anal.* **70** (2009), 2261–2269.
17. D. D. Hai, Positive solutions to a class of elliptic boundary value problems, *J. Math. Anal. Appl.* **227** (1998), 195–199.
18. D. D. Hai and X. Xu, On a class of quasilinear problems with sign-changing nonlinearities, *Nonlinear Anal.* **64** (2006), 1977–1983.
19. P. Harjulehto and P. Hästö, An overview of variable exponent Lebesgue and Sobolev spaces, in *Future Trends in Geometric Function Theory* (Herron D., Editor) (RNC Workshop, Jyväskylä, 2003), 85–93.
20. P. Harjulehto, P. Hästö, U. V. Lê and M. Nuortio, Overview of differential equations with non-standard growth, *Nonlinear Anal.* **72** (2010), 4551–4574.
21. V. V. Jikov, S. M. Kozlov and O. A. Oleinik, *Homogenization of differential operators and integral functional* (Springer-Verlag, Berlin, 1994). Translated from the Russian by G. A. Yosifan.
22. O. Kováčik and J. Rákosník, On spaces  $L^{p(x)}$  and  $W^{k,p(x)}$ , *Czech. Math. J.* **41**(116) (1991), 592–618.
23. P. Marcellini, Regularity and existence of solutions of elliptic equations with  $(p, q)$ -growth conditions, *J. Differ. Equ.* **90** (1991), 1–30.
24. M. Mihăilescu and V. Rădulescu, A multiplicity result for a nonlinear degenerate problem arising in the theory of electrorheological fluids, *Proc. R. Soc. Lond. Ser. A* **462** (2006), 2625–2641.
25. M. Mihăilescu and V. Rădulescu, On a nonhomogeneous quasilinear eigenvalue problem in Sobolev spaces with variable exponent, *Proc. Amer. Math. Soc.* **135** (2007), 2929–2937.
26. M. Mihăilescu and V. Rădulescu, Continuous spectrum for a class of nonhomogeneous differential operators, *Manuscr. Math.* **125** (2008), 157–167.
27. M. Růžička, *Electrorheological fluids: Modeling and mathematical theory* (Springer-Verlag, Berlin, 2000).
28. S. Samko, On a progress in the theory of Lebesgue spaces with variable exponent: maximal and singular operators, *Integral Transforms Spec. Funct.* **16** (2005), 461–482.
29. Q. H. Zhang, Existence and asymptotic behavior of positive solutions for variable exponent elliptic systems, *Nonlinear Anal.* **70** (2009), 305–316.
30. V. V. Zhikov, On some variational problems, *Russ. J. Math. Phys.* **5** (1997), 105–116.