

A note on generalised linear complementarity problems

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Given an $n \times n$ matrix A , an n -dimensional vector q , and a closed, convex cone S of R^n , the generalized linear complementarity problem considered here is the following: find a $z \in R^n$ such that

$$\begin{aligned}Az - q &\in S^*, \quad z \in S, \\ \langle Az - q, z \rangle &= 0,\end{aligned}$$

where S^* is the polar cone of S . The existence of a solution to this problem for arbitrary vector q has been established both analytically and constructively for several classes of matrices A . In this note, a new class of matrices, denoted by J , is introduced. A is a J -matrix if

$$Az \in S^*, \quad z^T Az \leq 0, \quad z \in S \quad \text{imply that} \quad z = 0.$$

The new class can be seen to be broader than previously studied classes. We analytically show that for any A in this class, a solution to the above problem exists for arbitrary vector q . This is achieved by using a result on variational inequalities.

1. Introduction

The generalized linear complementarity problem is to find a $z \in R^n$ satisfying

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$$(1.1) \quad \begin{aligned} Az - q &\in S^* , \quad z \in S , \\ \langle Az - q, z \rangle &= 0 , \end{aligned}$$

where A is a given $n \times n$ matrix, q is a given n -dimensional vector, S is a closed, convex cone in R^n , and S^* is the polar cone of S .

For $S = R_+^n$, the complementarity problem (1.1) has been extensively studied in the literature. The existence of a unique solution to this problem has been shown by Dantzig, Cottle [2] for P -matrices, which include all the previously studied matrices for which there is a unique solution. Karamardian [7] has solved this problem for the class of regular matrices, and thus has enlarged the class of matrices each of which guarantees a solution (but not necessarily unique).

Habetler and Price [4] have shown that the problem (1.1) has a solution when S is a pointed, closed, convex cone with nonempty interior, A is a strictly S -copositive matrix, and either

- (i) $q \in \text{int } S^*$ or
- (ii) $S \subset S^*$.

Karamardian [6] has generalized this result, and shown that strict S -copositeness of A is sufficient to ensure the existence of a solution to (1.1). In [9], the authors have shown that the linear complementarity problem defined over polyhedral cones in a complex n -space possesses a solution when A is a strictly S -copositive complex matrix.

In this note, we define a new class J of matrices A such that: if $A \in J$, then

$$Az \in S^* , \quad z^T Az \leq 0 , \quad z \in S \quad \text{imply that} \quad z = 0 .$$

The classes of P - and regular matrices become proper subclasses of this class when S is taken as R_+^n . It is also found that the class J includes the class of strictly S -copositive matrices, and thus becomes a broader class than previously studied ones.

We show that if $A \in J$ and there exists a vector $p \in \text{int } S^*$ such that the system $0 \neq z \in S$, $Az + p \in S^*$, $z^T(Az + p) = 0$ is not consistent, then (1.1) possesses a solution for every vector $q \in R^n$.

2. Notations and definitions

Throughout this note, R^n will denote euclidean n -space with the usual inner product $\langle x, y \rangle = y^T x$ of $x, y \in R^n$ and norm $\|x\|$ of $x \in R^n$. R_+^n denotes the nonnegative orthant of R^n . A subset S of R^n will be called a closed, convex cone if, and only if,

(i) S is closed, and

(ii) $\alpha x + \beta y \in S$ for $\alpha, \beta \geq 0$ and $x, y \in S$.

The polar of a cone S is the cone S^* defined by

$$S^* = \{x \in R^n : \langle x, y \rangle \geq 0 \text{ for all } y \in S\}.$$

The interior of S^* is given by

$$\text{int } S^* = \{x \in S^* : \langle x, y \rangle > 0 \text{ for all } 0 \neq y \in S\}.$$

A cone is said to be pointed if whenever $x \neq 0$ is in the cone, $-x$ is not in the cone. For a closed, convex cone S , $\text{int } S^*$ is nonempty if, and only if, S is pointed.

A square matrix A is a P -matrix if all its principal minors are positive.

For every $x \geq 0$, let $I_+(x)$ and $I_0(x)$ denote the set of indices corresponding to the positive and zero components of x ; that is, $I_+(x) = \{i : x_i > 0\}$ and $I_0(x) = \{i : x_i = 0\}$. A square matrix A is said to be regular if the system

$$(Ax)_i + t = 0 \text{ for } i \in I_+(x),$$

$$(Ax)_i + t \geq 0 \text{ for } i \in I_0(x),$$

$$0 \neq x \geq 0, \quad t \geq 0,$$

is inconsistent. Here $(Ax)_i$ denotes the i th component of the vector Ax .

A square matrix A is said to be strictly S -copositive if $x^T Ax > 0$ for all $0 \neq x \in S$.

3. Preliminary results

LEMMA 3.1. *Let A be an $n \times n$ matrix, and let S be a closed, convex cone in \mathbb{R}^n .*

(a) *If A is strictly S -copositive, then $A \in J$.*

(b) *If $S = \mathbb{R}_+^n$, then A is in J whenever A is either*

(i) *a P -matrix or*

(ii) *a regular matrix.*

Proof. (a) It immediately follows from the definitions of J - and S -copositive matrices given above.

(b) Let A be a P -matrix. The conclusion (b) for P -matrices follows from the following result of Fiedler and Pták [3]: if A is a P -matrix, then for each $0 \neq x \in \mathbb{R}^n$, there is an index i for which $x_i(Ax)_i > 0$.

To prove the second part of (b), we observe that when $S = \mathbb{R}_+^n$, the system $x \in S$, $Ax \in S^*$, $x^T Ax \leq 0$, reduces to $x \geq 0$, $Ax \geq 0$, $x^T Ax \leq 0$, the consistency of which implies that $x_i(Ax)_i = 0$ for $1 \leq i \leq n$. If $x \neq 0$, we will have $(Ax)_i = 0$ for $i \in I_+(x)$ and $(Ax)_i \geq 0$ for $i \in I_0(x)$, which is a contradiction to the regularity of A .

REMARK 3.2. It is interesting to note that the class of regular matrices is properly included in J . For example, the matrix

$\begin{pmatrix} -2 & 2 \\ -1 & 2 \end{pmatrix}$ is a J -matrix, but not regular.

LEMMA 3.3. *Let C be a closed, convex cone in \mathbb{R}^n with nonempty interior, $d \in \mathbb{R}^n$, and let $x \in \text{int } C$. Then there is a $\lambda_0 > 0$ such that $\lambda x + d \in C$ for every $\lambda \geq \lambda_0$.*

Proof. Since $x \in \text{int } C$, there is a $\delta > 0$ such that $u \in C$ whenever $\|u-x\| \leq \delta$. Consider the vector $w = x + d/\mu$ for some $\mu > 0$. Now

$\|w-x\| = \|d\|/\mu \leq \delta$ if $\mu \geq \|d\|/\delta$. Taking $\lambda_0 = \|d\|/\delta$, we see that $x + d/\lambda \in C$ for every $\lambda \geq \lambda_0$. Since C is a cone, $\lambda x + d = \lambda(x + (d/\lambda))$ will be in C for all $\lambda \geq \lambda_0$.

LEMMA 3.4. *Let C be a closed, convex cone in \mathbb{R}^n with nonempty interior, $d \in C$, and let $x \in \text{int } C$. Then $x + d \in \text{int } C$.*

Proof. If $x, d \in C$, then $x + d \in C$ because C is a convex cone. Further, if $0 \neq y \in C^*$, then we have $\langle d, y \rangle \geq 0$, $\langle x, y \rangle > 0$, and hence $\langle x+d, y \rangle > 0$, from which it follows that $(x+d)$ is in $\text{int } C$.

We shall make use of the following results.

LEMMA 3.5 [4, Lemma 5.1, p. 227]. *Let S be a pointed, closed, convex cone in \mathbb{R}^n , and let $p \in \text{int } S^*$. Then the set*

$$V = \{x : x \in S, \langle p, x \rangle = 1\}$$

is bounded.

THEOREM 3.6. *If $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a continuous mapping on the nonempty, compact, convex set C in \mathbb{R}^n , then there is an x^0 in C such that*

$$\langle F(x^0), x-x^0 \rangle \geq 0 \text{ for all } x \in C.$$

REMARK 3.7. Theorem 3.6 was first stated and proved in [5]. A complex version of this result has been used by the present authors to obtain some existence theorems for nonlinear complementarity problems in complex space [8].

4. Solvability of the complementarity problem

THEOREM 4.1. *Let S be a pointed, closed, convex cone in \mathbb{R}^n . If $A \in J$ and there exists a vector $p \in \text{int } S^*$ such that the system $0 \neq z \in S$, $Az + p \in S^*$, $z^T(Az+p) = 0$ is not consistent, then for each $q \in \mathbb{R}^n$ there is a vector z^0 satisfying $Az - q \in S^*$, $z \in S$.*

Proof. Consider the set $V = \{z : z \in S, \langle p, z \rangle = 1\}$. It is clear that V is a closed, convex set, and by Lemma 3.5, it is also bounded.

Thus V is a nonempty, compact, convex set in \mathbb{R}^n . Now applying Theorem

3.6, we get a point \bar{z} in V such that

$$(4.1) \quad \langle A\bar{z}, z - \bar{z} \rangle \geq 0 \quad \text{for all } z \in V .$$

It follows from (4.1) that

$$\langle A\bar{z}, \bar{z} \rangle = \min_{z \in V} \langle A\bar{z}, z \rangle ,$$

and therefore, the following set of necessary conditions [1] is satisfied:

$$(4.2) \quad \begin{aligned} A\bar{z} + \eta p &\in S^* , \quad \langle A\bar{z} + \eta p, \bar{z} \rangle = 0 , \\ \bar{z} &\in S , \quad \langle p, \bar{z} \rangle = 1 , \quad \eta \in R . \end{aligned}$$

Obviously $\bar{z} \neq 0$. Now the consistency of (4.2) for a vector $0 \neq \bar{z} \in S$ and $\eta \geq 0$ will contradict the assumptions made in the statement of the theorem. So $\eta < 0$, and thus we have a $0 \neq y = \bar{z}/\eta \in S$ satisfying $Ay - p \in S^*$. Since $p \in \text{int } S^*$, it follows from Lemma 3.4 that

$Ay \in \text{int } S^*$. Now, for any given vector $q \in R^n$, Lemma 3.3 will determine a $\lambda > 0$ such that $\lambda(Ay) - q \in S^*$. Since S is a cone, $\lambda y \in S$. The proof of the theorem is then completed by writing $z^0 = \lambda y$.

Now we give the following existence theorem.

THEOREM 4.2. *Let S be a pointed, closed, convex cone in R^n , and let p be a vector in $\text{int } S^*$ such that the system $0 \neq z \in S$, $Az + p \in S^*$, $z^T(Az+p) = 0$ is inconsistent. Then there is a solution to (1.1) for each $q \in R^n$ if A is a J -matrix.*

Proof. Consider the function

$$F(z, t) = \begin{bmatrix} Az + t(p - q) \\ t \end{bmatrix}$$

defined over the set

$$C = \{(z, t) : z \in S, t \geq 0, \langle p, z \rangle + t = 1\} .$$

From Lemma 3.5, it is clear that C is a nonempty, compact, convex set in R^{n+1} . It is also evident that $F(z, t)$ and C satisfy the conditions of Theorem 3.6, and hence, there exists a point (\bar{z}, \bar{t}) in C such that

$$\langle A\bar{z} + \bar{t}(p - q), z - \bar{z} \rangle + \bar{t}(t - \bar{t}) \geq 0 \quad \text{for all } (z, t) \in C .$$

But this means that

$$\langle A\bar{z} + \bar{t}(p-q), \bar{z} \rangle + \bar{t} \cdot \bar{t} = \min_{(z,t) \in C} (\langle A\bar{z} + \bar{t}(p-q), z \rangle + \bar{t} \cdot t) .$$

Now using the Kuhn-Tucker necessary conditions of optimality [1] for cone domains, we have a ζ_0 in R such that

$$(4.3) \quad \begin{aligned} A\bar{z} + \bar{t}(p-q) + \zeta_0 p &\in S^* , \quad \bar{t} + \zeta_0 \geq 0 , \\ \langle A\bar{z} + \bar{t}(p-q) + \zeta_0 p, \bar{z} \rangle &= 0 , \quad \bar{t}(\bar{t} + \zeta_0) = 0 \\ \bar{z} \in S , \quad \bar{t} &\geq 0 , \quad \langle p, \bar{z} \rangle + \bar{t} = 1 . \end{aligned}$$

Suppose that $\bar{t} = 0$. Since $\langle p, \bar{z} \rangle + \bar{t} = 1$ and $p \in \text{int } S^*$, $\bar{z} \neq 0$. If this is the case, then (4.3) will imply that the system

$$(4.4) \quad \begin{aligned} 0 \neq \bar{z} \in S , \quad A\bar{z} + \zeta_0 p &\in S^* , \\ \langle A\bar{z} + \zeta_0 p, \bar{z} \rangle = 0 , \quad \zeta_0 &\geq 0 , \end{aligned}$$

is consistent. When $\zeta_0 = 0$, the consistency of (4.4) will contradict the assumption that A is a J -matrix. Further, when $\zeta_0 > 0$, (4.4) will yield a nonzero vector $\bar{y} = \bar{z}/\zeta_0 \in S$ satisfying $A\bar{y} + p \in S^*$,

$\bar{y}^T(A\bar{y} + p) = 0$, again a contradiction. Hence, $\bar{t} > 0$, and since $\bar{t}(\bar{t} + \zeta_0) = 0$, therefore, we have $\bar{t} + \zeta_0 = 0$. Now substituting $\zeta_0 = -\bar{t}$ in (4.3), and then dividing throughout the resulting relations by \bar{t} , we get the desired solution.

REMARK 4.3. We do not require any other assumption for the cone S , except that it is to be pointed in the statement of Theorem 4.2. But for q , we impose the restriction that when $-q = p \in \text{int } S^*$, there is no nonzero solution to (1.1). For this value of q , zero is obviously a solution. This restriction is automatically satisfied when A is strictly S -copositive, whereas if A is a regular matrix and $S = R_+^n$, (1.1) has no nonzero solution for the vector $-q = et$, $t \geq 0$, with $e^T = (1, 1, \dots, 1)$.

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