## PARALLEL GURVES

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In the Euclidean plane a curve $C$ has a one-parameter family of parallel involutes and a unique evolute $C^{*}$ which coincides with the locus of the centres of the osculating circles of $C$. If $\bar{C}$ is parallel to $C, C^{*}$ is also the evolute of $\bar{C}$.

We will study parallel curves in $n$-dimensional Euclidean space and obtain generalizations of the properties given above.

Definition. Curves $C$ and $\bar{C}$ are parallel if there is a one-to-one correspondence between their points such that the tangents at corresponding points are parallel and such that the join of corresponding points is perpendicular to the tangents.

This definition was given by Da Cunha (1).
It follows at once that parallelism is an equivalence relation.
We denote the position vector of a point on a curve $C$ in $n$-space by $r$. We suppose that $r$ is an $(n+1)$-times differentiable function of the arc length $s$ of $C$. Let $C$ have the moving $n$-hedron $\xi_{1}, \ldots, \xi_{n}$ and non-vanishing curvatures $k_{1}, \ldots, k_{n-1}$. We use corresponding notations for curves $\bar{C}, \widetilde{C}$, etc.

If $C$ and $\bar{C}$ are parallel, the distance between corresponding points is constant as we see by differentiating $(\bar{r}-r)^{2}$.

To find the curves $\bar{C}$ parallel to a given curve $C$ we put

$$
\begin{equation*}
\bar{r}=r+\sum_{1}^{n} u_{i} \xi_{i} \tag{1}
\end{equation*}
$$

where $u_{1}, \ldots, u_{n}$ are scalar functions of $s$ to be determined. Since $(\bar{r}-r) \xi_{1}=0$, $u_{1}=0$. Differentiating (1) and using the Frenet formulae

$$
\begin{equation*}
\xi_{i}^{\prime}=-k_{i-1} \xi_{i-1}+k_{i} \xi_{i+1} \quad(i=1, \ldots, n) \tag{2}
\end{equation*}
$$

in which $k_{0}=k_{n}=0, k_{i}>0,(i=1, \ldots, n-1)$, we obtain

$$
\bar{\xi}_{1} \bar{s}^{\prime}=\left(1-k_{1} u_{2}\right) \xi_{1}+\sum_{2}^{n}\left(u_{i}^{\prime}-k_{i} u_{i+1}+k_{i-1} u_{i-1}\right) \xi_{1}
$$

Since

$$
\begin{equation*}
\bar{\xi}_{1}=\epsilon \xi_{1} \tag{3}
\end{equation*}
$$

$$
(\epsilon= \pm 1)
$$

we have

$$
\begin{equation*}
\bar{s}^{\prime}=\epsilon\left(1-k_{1} u_{2}\right) \tag{4}
\end{equation*}
$$

[^0]and
\[

$$
\begin{equation*}
u_{i}^{\prime}=-k_{i-1} u_{i-1}+k_{i} u_{i+1} \quad(i=2, \ldots, n) \tag{5}
\end{equation*}
$$

\]

These differential equations determine an $(n-1)$-parameter family $F_{n-1}$ of parallel curves. We see that there is exactly one $\bar{C}$ through every point of the common normal ( $n-1$ )-space $H_{n-1}(s)$.

We assume that $\bar{s}$ is defined so that $\bar{s}^{\prime}>0$. Differentiating (3) we find

$$
\begin{equation*}
\bar{\xi}_{i}=\epsilon \xi_{i}, \quad \bar{k}_{i} \bar{s}^{\prime}=k_{i} \quad(i=1, \ldots, n) \tag{6}
\end{equation*}
$$

In connection with these equations for $\bar{k}_{i}$, it should be mentioned that if the curvatures never vanish, the sense of the vectors of the moving $n$-hedron of a curve will be chosen so that the curvatures are positive.

Let $C_{\lambda}: r_{\lambda}=r_{\lambda}(s)$ be a set of curves parallel to $C$. Since the distances $\left|r_{\lambda}-r_{\mu}\right|$ are constant, the figure consisting of the points $r_{\lambda}$ will move rigidly as $s$ varies. If a subfamily $F_{p}$ of $F_{n-1}$ intersects say $H_{n-1}\left(s_{0}\right)$ in a linear $p$-space then $F_{p}$ intersects every $H_{n-1}(s)$ in a linear $p$-space $H_{p}(s)$. Thus the concept of linear dependence can be applied to parallel curves.

Lemma 1. Let

$$
C_{j}: r_{j}=r+\sum_{i=1}^{n} u_{i j} \xi_{i} \quad(j=1, \ldots, p)
$$

be $p$ curves in $F_{n-1} . C, C_{1}, \ldots, C_{p}$ span an $F_{p}$ if and only if the Wronskian of $u_{21}, \ldots, u_{2 p}$ does not vanish.

Proof. The equations (5) imply that the $u_{2 i}$ are ( $n-1$ )-times continuously differentiable solutions of a linear homogeneous differential equation of order $n-1$ with continuous coefficients. Hence if the Wronskian vanishes, the $u_{2 i}$ are linearly dependent ( 2, p. 116). That is, there exist constants $\alpha_{i}$, not all zero, such that

$$
\begin{equation*}
\sum_{1}^{p} u_{2 i} \alpha_{i}=0 \tag{7}
\end{equation*}
$$

and since $\left(r_{i}-r\right)^{\prime}=-k_{1} u_{2 i} \xi_{1}$, we have

$$
\sum_{1}^{p} \alpha_{i}\left(r_{i}-r\right)^{\prime}=0
$$

and

$$
\begin{equation*}
\sum_{1}^{p} \alpha_{i}\left(r_{i}-r\right)=r_{0}=\mathrm{a} \text { constant vector. } \tag{8}
\end{equation*}
$$

Since $\left(r_{i}-r\right) \xi_{1}=0, r_{0} \xi_{1}=0$; so that if $r_{0} \neq 0, C$ is in an $(n-1)$-space which contradicts $k_{n-1} \neq 0$. Hence $r_{0}=0$ and the $r_{i}-r$ are dependent. On the other hand (7) can be obtained from (8) by differentiating.

Lemma 2. The curves $C, C_{1}, \ldots, C_{p}$ of Lemma 1 span an $F_{p}$ if and only if the determinant $\left|u_{i j}\right| \neq 0(i=2, \ldots, p+1 ; j=1, \ldots, p)$.
Proof. Using (5) we find that $k_{2}{ }^{p-1} k_{3}{ }^{p-2} \ldots k_{p}\left|u_{i j}\right|$ is the Wronskian of $u_{21}$,

Lemma 3. If C is on a hypersphere, every curve $\bar{C}$ parallel to $C$ is on a concentric hypersphere.

Proof. Let $r_{0}$ be the centre of the hypersphere on which $C$ lies. Then $\left(r-r_{0}\right) \xi_{1}=0$ and $\left(\bar{r}-r_{0}\right) \bar{\xi}_{1}=\epsilon(\bar{r}-r) \xi_{1}+\epsilon\left(r-r_{0}\right) \xi_{1}=0$. Thus $\bar{C}$ is on a hypersphere with centre $r_{0}$.

Definition. ${ }^{1} C$ is a $p$ th involute of $C_{p}^{*}$ and $C^{*}{ }_{p}$ is a $p$ th evolute of $C$ if $C$ is an orthogonal trajectory of the osculating $p$-spaces of $C^{*}{ }_{p}(p=1, \ldots, n-1)$.

Theorem 1. The pth involutes of a curve form an $F_{p}$.
Proof. Let $\tilde{C}: \tilde{r}=\tilde{r}(s)$ be a $p$ th involute of $C$. We can write

$$
\tilde{r}=r+\sum_{i=1}^{p} a_{i} \xi_{i}
$$

in which the $a_{i}$ are to be determined so that $\tilde{\xi}_{1} \xi_{i}=0(i=1, \ldots, p)$. These conditions are satisfied if and only if

$$
\begin{align*}
a_{1}^{\prime}=k_{1} a_{2}-1, \quad a_{i}^{\prime}=k_{i} a_{i+1}-k_{i-1} a_{i-1}, \quad a_{p}^{\prime}=- & k_{p-1} a_{p-1}  \tag{9}\\
& (i=2, \ldots, p-1),
\end{align*}
$$

and when the $a_{i}$ are chosen in this way, $a_{p}$ does not vanish identically and $\tilde{\xi}_{1}=$ $\pm \xi_{p+1}$ whenever $a_{p} \neq 0$.

Let $\widetilde{C}_{(1)}$ and $\widetilde{C}_{(2)}$ be $p$ th involutes of C. $\tilde{\xi}_{1(1)}$ is parallel to $\tilde{\xi}_{1(2)}$ since each is parallel to $\xi_{p+1}$ and

$$
\left(\tilde{r}_{(1)}-\tilde{r}_{(2)}\right) \tilde{\xi}_{1(1)}= \pm\left(\tilde{r}_{(1)}-\tilde{r}_{(2)}\right) \xi_{p+1}=0
$$

Thus $\widetilde{C}_{(1)}$ and $\widetilde{C}_{(2)}$ are parallel.
Since (9) is a system of linear non-homogeneous differential equations for the $a_{i}$, we can determine $\tilde{r}_{(1)}, \ldots, \tilde{r}_{(p+1)}$ so that $\tilde{r}_{(1)}-\tilde{r}_{(i)}(i=2, \ldots, p+1)$ are independent. Then if $\tilde{r}$ is any other $p$ th involute $\tilde{r}_{(1)}-\tilde{r}, \tilde{r}_{(1)}-\tilde{r}_{(i)}$ are dependent. Thus the $p$ th involutes form an $F_{p}$.

Next we find some necessary conditions in order that $C^{*}{ }_{p}$ shall be a $p$ th evolute of $C$. Let $S^{*}{ }_{p}(s)$ be the osculating $p$-space of $C^{*}{ }_{p}$. Put

$$
\begin{equation*}
r_{p}^{*}=r+\sum_{1}^{n} b_{i} \xi_{i} . \tag{10}
\end{equation*}
$$

The $b_{i}$ are to be determined so that $r^{*}{ }_{p}-r$ is in $S^{*}{ }_{p}$ and so that $\xi_{1}$ is orthogonal to $S^{*}{ }_{p}$. We see that $b_{1}=0$ and differentiating (10) and using $r^{*}{ }^{(i)} \xi_{1}=0(i=$ $1, \ldots, p$ ) we obtain

$$
\begin{equation*}
b_{i}=c_{i} \quad(i=1, \ldots, p+1) \tag{11}
\end{equation*}
$$

where $c_{1}, \ldots, c_{n}$ are defined by

$$
\begin{equation*}
c_{1}=0, k_{1} c_{2}=1, c_{i}^{\prime}=-k_{i-1} c_{i-1}+k_{i} c_{i+1} \quad(i=2, \ldots, n-1) \tag{12}
\end{equation*}
$$

[^1]Hence $b_{1}, \ldots, b_{p+1}$ are known. We will show later that the remaining $b_{i}$ can be determined so that $C_{p}^{*}$ is a $p$ th evolute ( $p \neq n-1$ if $C$ is on a hypersphere).

Theorem 2. In general the curves of an $F_{p}$ have exactly one common pth evolute $C^{*}{ }_{p}$. There is an exception if and only if the members of $F_{p}$ are on concentric hyperspheres whose common centre lies on all the $H_{p}(s)$. In this case there is no common pth evolute.

Proof. Let $C, C_{1}, \ldots, C_{p}$ span $F_{p}$. If $C^{*}{ }_{p}$ is a common $p$ th evolute of these curves, then $C^{*}{ }_{p}$ is a $p$ th evolute of every member of $F_{p}$. For $r^{*}{ }_{p}-r, r^{*}{ }_{p}-r_{i}$, ( $i=1, \ldots, p$ ) are in $S_{p}^{*}$ and $\xi_{1}$ is orthogonal to $S^{*}{ }_{p}$. If

$$
\bar{r}=r+\sum_{1}^{p} \alpha_{i}\left(r_{i}-r\right)
$$

is any other curve in $F_{p}, r^{*}-\bar{r}$ is in $S_{p}^{*}$ and $\bar{\xi}_{1}$ is orthogonal to $S_{p}^{*}$. Thus as far as common $p$ th evolutes are concerned we can replace $F_{p}$ by $C, C_{1}, \ldots, C_{p}$.

Since $r_{p}^{*}-r, r_{p}^{*}-r_{j}(j=1, \ldots, p)$ are dependent and the $r_{j}-r$ are independent we can write

$$
\begin{equation*}
r_{p}^{*}=r+\sum_{1}^{p} \lambda_{j}\left(r_{j}-r\right) . \tag{13}
\end{equation*}
$$

Putting

$$
r_{j}=r+\sum_{i=2}^{n} u_{i j} \xi_{i}
$$

we have

$$
r_{p}^{*}=r+\sum_{j=1}^{p} \sum_{i=2}^{n} u_{i j} \lambda_{j} \xi_{i}
$$

But $C^{*}{ }_{p}$ is a $p$ th evolute of $C$. Hence by (11), $\left(r^{*}{ }_{p}-r\right) \xi_{i}=c_{i}(i=1, \ldots$. $p+1)$. Thus

$$
\begin{equation*}
\sum_{j=1}^{p} \lambda_{j} u_{i j}=c_{i} \quad(i=2, \ldots, p+1) \tag{14}
\end{equation*}
$$

By Lemma 2, the determinant $\left|u_{i j}\right|$ is not zero so these equations determine $\lambda_{j}$ uniquely. Thus there is not more than one common $p$ th evolute of the curves of $F_{p}$ and if there is one it is the curve $C^{*}{ }_{p}$ given by (13) and (14).

Suppose now, first, that the vectors $r^{*}{ }_{p}{ }^{(i)}(i=1, \ldots, p)$ are linearly independent. We then prove that $C^{*}{ }_{p}$ actually is a common $p$ th evolute. Differentiating (13) and using $r^{*}{ }_{p}{ }^{(i)} \xi_{1}=0$, we obtain

$$
r_{p}^{*(i)}=\sum_{j=1}^{p} \lambda_{j}^{(i)}\left(r_{j}-r\right), \quad(i=1, \ldots, p)
$$

Since the $r^{*}{ }_{p}^{(i)}$ are independent, we can solve these equations for the vectors $r_{j}-r$ in terms of $r^{*}{ }^{\left({ }^{(i)}\right.}$. Now writing
$r_{j}=r+\left(r_{j}-r\right)=r_{p}^{*}-\sum_{i=1}^{p} \lambda_{i}\left(r_{i}-r\right)+\left(r_{j}-r\right)=r_{p}^{*}+$ a vector in $S_{p}^{*}$,
we see that the point $r_{j}$ is in $S_{p}^{*}$. Since we also have $\xi_{1}$ perpendicular to $S^{*}{ }_{p}$, $C^{*}{ }_{p}$ is the common $p$ th evolute.

Suppose next that the vectors $r^{*}{ }_{p}{ }^{(i)}$ are dependent so that $C^{*}{ }_{p}$ is less than $p$-dimensional. We can write

$$
r_{p}^{*}{ }_{(p)}=\sum_{i=1}^{p-1} d_{i} r_{p}^{*}{ }^{(i)}
$$

and differentiating this,

$$
r_{p}^{*}{ }_{p}^{(p+1)}=\sum_{i=1}^{p-1} d_{i} r_{p}^{*}{ }_{p}^{(i)}+d_{i} r_{p}^{*}{ }^{(i+1)} .
$$

Since $r^{*}{ }^{(i)} \xi_{1}=0(i=1, \ldots, p), r^{*}{ }_{p}{ }^{(p+1)} \xi_{1}=0$. Further differentiations yield $r^{*}{ }_{p}{ }^{(i)} \xi_{1}=0(i=1, \ldots, n)$. When we differentiate $r^{*}{ }_{p}{ }^{(i)} \xi_{1}=0$ we obtain $r^{*} p^{(i)} \xi_{2}=0(i=1, \ldots, n-1)$. Continuing this, we have $r^{*}{ }_{p} \xi_{j}=0(j=1$, $\ldots, n$ ); hence $r^{*}{ }_{p}{ }^{\prime}=0$ and $C^{*}{ }_{p}$ reduces to a point. Thus there is no common $p$ th evolute. By (13), $r^{*}$ is on $H_{p}(s)$ and since $\left(r^{*}{ }_{p}-r\right) \xi_{1}=0, C$ is on a hypersphere with centre $r^{*}{ }_{p}$.

Finally we show that if $C$ is on a hypersphere with centre $r_{0}$ and if $r_{0}$ is in $H_{p}(s)$, there is no common $p$ th evolute. We can write

$$
r_{0}=r+\sum_{1}^{p} \mu_{i}\left(r_{i}-r\right), \quad r_{0}^{(j)} \xi_{1}=0 \quad(j=1, \ldots, p)
$$

But these are the conditions which determine $r^{*}{ }_{p}$ and $\lambda_{i}$. Thus $r^{*}{ }_{p}=r_{0}$, and the result follows.

We observe that there is a $(1-1)$ correspondence between $p$ th evolutes of $C$ and $p$-spaces in $H_{n-1}(s)$ through $r$.

Theorem 3. The hypersphere with centre $r^{*}{ }_{p}$ and radius $\left|r_{p}{ }_{p}-r\right|$ has at least $(p+1)$ th order contact with $C$ at $r$.
Proof. The points of intersection of $C$ and the hypersphere with centre $r_{p}^{*}\left(s_{0}\right)$ and radius $\left|r^{*}{ }_{p}\left(s_{0}\right)-r\left(s_{0}\right)\right|$ are obtained by solving the equation

$$
f(s) \equiv\left[r(s)-r_{p}^{*}\left(s_{0}\right)\right]^{2}-\left[r\left(s_{0}\right)-r_{p}^{*}\left(s_{0}\right)\right]^{2}=0
$$

for $s$. We find

$$
f^{(i)}(s)=2\left[r_{p}^{*}(s)-r_{p}^{*}\left(s_{0}\right)\right] r^{(i)}(s) \quad(i=1, \ldots, p+1) .
$$

Therefore

$$
f^{(i)}\left(s_{0}\right)=0 \quad(i=1, \ldots, p+1)
$$

Consider the $(n-1)$ th evolute $C^{*}{ }_{n-1}=C^{*}$. Assuming that $C$ is not on a hypersphere, $C^{*}$ is the $(n-1)$ th evolute of every member of $F_{n-1}$ and by Theorem $3, C^{*}$ is the locus of the centres of the osculating hyperspheres of every curve in $F_{n-1}$. Thus the family of parallel curves has a common locus of centres of osculating hyperspheres. (This is true even in $C$ if on a hypersphere).

Next we obtain the relationship between the moving $n$-hedrons of $C$ and $C^{*}$. Since

$$
r^{*}=r+\sum_{2}^{n} c_{i} \xi_{i}
$$

$r^{* \prime}=\left(c_{n}^{\prime}+k_{n-1} c_{n-1}\right) \xi_{n}$, and we see that $C$ is on a hypersphere if and only if
$c_{n}^{\prime}+k_{n-1} c_{n-1}=0$. We will assume that this expression never vanishes and that $s^{*}$ is defined so that $s^{* \prime}<0$. Then $s^{* \prime}=\left(c_{n}^{\prime}+k_{n-1} c_{n-1}\right) \epsilon^{*}$ and $\xi^{*}{ }_{1}=\epsilon^{*} \xi_{n}$, where $\epsilon^{*}= \pm 1$. Further differentiations yield

$$
\begin{equation*}
\xi_{i}^{*}=\epsilon^{*} \xi_{n+1-i}, \quad k_{i}^{*} s^{*}=-k_{n-i} \quad(i=1, \ldots, n) \tag{15}
\end{equation*}
$$

Definition. The $p$ th polar developable $D_{p}$ of $F_{n-1}(p=1, \ldots, n-1)$ is the surface

$$
\begin{equation*}
z_{p}=r+\sum_{1}^{p+1} c_{i} \xi_{i}+\sum_{p+2}^{n} y_{i} \xi_{i} \tag{16}
\end{equation*}
$$

in which $s, y_{p+2}, \ldots, y_{n}$ are parameters.
A particular curve $C$ of $F_{n-1}$ has been used in this definition. In order to justify this we will prove that the same surface is obtained if we use any other curve

$$
\bar{C}: \bar{r}=r+\sum_{1}^{n} u_{i} \xi_{i}
$$

of $F_{n-1}$. We now have

$$
\begin{aligned}
\bar{z}_{p} & =\bar{r}+\sum_{1}^{p+1} \bar{c}_{i} \bar{\xi}_{i}+\sum_{p+2}^{n} \bar{y}_{i} \bar{\xi}_{i} \\
& =r+\sum_{i}^{p+1}\left(\epsilon \bar{c}_{i}+u_{i}\right) \xi_{i}+\sum_{p+2}^{n}\left(\epsilon \bar{y}_{i}+u_{i}\right) \xi_{i}
\end{aligned}
$$

Using (4), (5), (6) and (12) we obtain $\epsilon \bar{c}_{i}+u_{i}=c_{i}(i=1, \ldots, n)$ so that $\bar{z}_{p}=z_{p}$.

Theorem 4. (a) The $p$ th evolutes of a member of $F_{n-1}$ are on $D_{p}$.
(b) $D_{p+1}$ is the envelope of the $(n-p-1)$-spaces which generate $D_{p}(p=1$, $\ldots, n-2)$.
(c) If $C$ is not on a hypersphere, $D_{p}$ is generated by the $(n-p-1)$-dimensional osculating spaces of $C^{*}=D_{n-1}$.
(d) If $F_{p}$ has a pth evolute, this evolute is the locus of the point of intersection of $H_{p}(s)$ and the corresponding generator of $D_{p}$.
(e) The first evolutes of the curves in $F_{n-1}$ are geodesics on $D_{1}$.
(f) If $x=x(s)$ is a geodesic on $D_{1}$ and is not a straight line, $x$ is a first evolute of some member of $F_{n-1}$.

Proof. (a) Compare (10), (11) and (16).
(b) The equations of a generator of $D_{p}$ are $(R-r) \xi_{i}=c_{i}(i=1, \ldots$, $p+1)$. Differentiating these, we see that there is an envelope and that it is $D_{p+1}$.
(c) The $(n-p-1)$-dimensional osculating spaces of $C^{*}$ are

$$
R=r^{*}+\sum_{i}^{n-p-1} y_{i}^{*} \xi_{i}^{*}
$$

in which the $y^{*}{ }_{i}$ are parameters. This is

$$
R=r+\sum_{i}^{n} c_{i} \xi_{i}+\sum_{p+2}^{n} \epsilon^{*} y_{n+1-i}^{*} \xi_{i},
$$

using (15). When we put

$$
c_{i}+\epsilon_{\epsilon^{*}}^{y_{n+1-i}}=y_{i} \quad(i=p+2, \ldots, n)
$$

$R$ becomes $z_{p}$.
(d) Let $C, C_{1}, \ldots, C_{p}$ span $F_{p}$ and let the point of intersection of $H_{p}(s)$ and the generator be $R$. Since $R$ is in $H_{p}$,

$$
R=r+\sum_{1}^{p} \mu_{i}\left(r_{i}-r\right)
$$

The generator is $(R-r) \xi_{j}=c_{j}(j=1, \ldots, p+1)$. The unique solution of these equations is $\mu_{i}=\lambda_{i}, R=r^{*}{ }_{p}$.
(e) The principal normal of $C^{*}{ }_{1}$ is $\pm \xi_{1}$ which is normal to $D_{1}$. Hence $C^{*}{ }_{1}$ is a geodesic.
(f) We will show that every first involute of $x=x(s)$ is parallel to $C$. Let $y=y(s)$ be a first involute of $x$. Since $x$ is a geodesic, $\xi_{2(x)}= \pm \xi_{1}$ and since $y$ is a first involute of $x, \xi_{1(y)}= \pm \xi_{2(x)}$. Thus $\xi_{1(y)}$ is parallel to $\xi_{1}$. Also $(y-r) \xi_{1}$ $=(y-x) \xi_{1}+(x-r) \xi_{1}$. The first term of this is zero because $y-x$ is parallel to $\xi_{1(x)}$ and the second term is zero because $x$ is on $D_{1}$. Hence $y=y(s)$ is parallel to $C$.

Next we want to develop $D_{1}$ on an ( $n-1$ )-space and determine the point of the $(n-1)$-space which corresponds to $\left(s, y_{3}, \ldots, y_{n}\right)$ of $D_{1}$. Since $D_{1}$ is the tangent hypersurface of $C^{*}{ }_{n-1}$ (provided $C$ is not on a hypersphere) we will first see how to develop the tangent hypersurface of a given curve $C$ on an ( $n-1$ )-space $H$. Vectors in $H$ will be denoted by capital letters.
$C$ will roll along a curve $R=R(s)$ in $H$ and $R$ will have arc length $s$. The point

$$
z=r+\sum_{1}^{n-2} y_{i} \xi_{i}
$$

of the tangent hypersurface is mapped on

$$
Z=R+\sum_{1}^{n-2} y_{i} T_{i}
$$

where $\left(T_{1}, \ldots, T_{n-1}\right)$ is the moving $(n-1)$-hedron of $R$. Now using the fact that the line element is invariant under this transformation we find that $k_{i}$ for $R$ is equal to $k_{i}$ for $C(i=1, \ldots, n-2)$.

Turning now to the first polar developable of $C$, the point

$$
z=r^{*}+\sum_{1}^{n-2} y_{i}^{*} \xi_{i}^{*}=r+c_{2} \xi_{2}+\sum_{3}^{n}\left(c_{i}+\epsilon^{*} y_{n+1-i}^{*}\right) \xi_{i}
$$

of $D_{1}$ corresponds to

$$
Z=R^{*}+\sum_{1}^{n-2} y_{i}^{*} T_{i}^{*}
$$

where $R^{*}$ and $T^{*}{ }_{i}$ are determined by

$$
\begin{array}{r}
\frac{d R^{*}}{d s^{*}}=T_{1}^{*}, \quad \frac{d T_{i}^{*}}{d s^{*}}=-k_{i-1}^{*} T_{i-1}^{*}+k_{i}^{*} T_{i+1}^{*}, \quad \frac{d T_{n-1}^{*}}{d s^{*}}=-k_{n-2}^{*} T_{n-2}^{*} \\
(i=1, \ldots, n-2)
\end{array}
$$

Now

$$
R^{*}=\int T_{1}^{*} d s^{*}=\int \epsilon \epsilon^{*}\left(c_{n-1} k_{n-1}+c_{n}^{\prime}\right) T_{1}^{*} d s
$$

and after integrating by parts $n-1$ times we obtain

$$
R^{*}=\epsilon^{*} \sum_{2}^{n} c_{i} T_{n+1-i}^{*}
$$

Let us put

$$
{ }_{\epsilon}^{*} T_{n-i}^{*}=T_{i}, \quad c_{j}+\epsilon^{*} y^{*}{ }_{n+1-j}=y_{j} \quad(i=1, \ldots, n-1 ; j=3, \ldots, n) .
$$

The point

$$
r+c_{2} \xi_{2}+\sum_{3}^{n} y_{i} \xi_{i}
$$

of $D_{1}$ corresponds to

$$
\begin{equation*}
c_{2} T_{1}+\sum_{3}^{n} y_{i} T_{i-1} \tag{17}
\end{equation*}
$$

where $T_{1}, \ldots, T_{n-1}$ are solutions in $H$ of

$$
\begin{equation*}
T_{1}^{\prime}=k_{2} T_{2}, \quad T_{i}^{\prime}=-k_{i} T_{i-1}+k_{i+1} T_{i+1} \quad(i=2, \ldots, n-1) . \tag{18}
\end{equation*}
$$

We have assumed above that $C$ is not on a hypersphere. However, once we have (17) and (18) we can easily verify, by comparing line elements, that they are correct in this case also.

Let $A$ be an arbitrary constant vector in $H$. The general solution of the differential equations (5) is

$$
u_{i+1}=A T_{i} \quad(i=1, \ldots, n-1)
$$

Thus we have a $(1-1)$ correspondence between points of $H$ and curves of $F_{n-1}$. The geometrical significance of the point $A$ which corresponds to $\bar{C}$ of $F_{n-1}$ is that if the whole $n$-space is moved rigidly when we are developing $D_{1}$, $\bar{C}$ cuts $H$ in the fixed point $A$. This follows from the fact that the point of intersection of $\bar{C}$ and the tangent $(n-1)$-space of $D_{1}$ is

$$
r+\sum_{2}^{n} u_{i} \xi_{i}
$$

and since $T_{1}=\epsilon^{*} T^{*}{ }_{n-1}=\epsilon^{*} \xi^{*}{ }_{n-1}=\xi_{2}$, the transform of this point is

$$
\sum_{2}^{n} u_{i} T_{i-1}=\sum_{2}^{n}\left(A T_{i-1}\right) T_{i-1}=A .
$$

Theorem 5. When $D_{1}$ is developed on $H$, the pth evolutes of curves of $F_{n-1}$ become p-dimensional curves in $H$.

Proof. We may assume that the $p$ th evolute under consideration is the common $p$ th evolute $C^{*}{ }_{p}$ of $C_{1}, \ldots, C_{p+1}$ where $C_{1}, \ldots, C_{p+1}$ are parallel curves which span an $F_{p}$. Let $C_{i}$ correspond to the point $A_{i}$ of $H$.

$$
\begin{aligned}
r_{p}^{*}=r_{1}+\sum_{2}^{p+1} \lambda_{i}\left(r_{i}-r_{1}\right)=r & +\sum_{j=2}^{n}\left(A_{1} T_{j-1}\right) \xi_{j} \\
& +\sum_{i=2}^{p+1} \sum_{j=2}^{n} \lambda_{i}\left\{\left(A_{i}-A_{1}\right) T_{j-1}\right\} \xi_{j}
\end{aligned}
$$

which transforms to

$$
\begin{aligned}
R_{p}^{*} & =\sum_{j=2}^{n}\left(A_{1} T_{j-1}\right) T_{j-1}+\sum_{i=2}^{p+1} \sum_{j=2}^{n} \lambda_{i}\left\{\left(A_{i}-A_{1}\right) T_{j-1}\right\} T_{j-1} \\
& =A_{1}+\sum_{2}^{p+1} \lambda_{i}\left(A_{i}-A_{1}\right)
\end{aligned}
$$

Thus the transform is in the $p$-space determined by $A_{1}, \ldots, A_{p+1}$. (If the $A_{i}$ were in a ( $p-1$ )-space, $C_{1}, \ldots, C_{p+1}$ would not span an $F_{p}$ ). If $R_{p}^{*}$ were in a ( $p-1$ )-space the determinant $\left|\lambda_{i}{ }^{(j)}\right|(i=2, \ldots, p+1 ; j=1, \ldots, p$ ) would be identically zero; the vectors $r^{*}{ }_{p}{ }^{(j)}$ would be dependent, and $C_{1}, \ldots, C_{p+1}$ would have no common $p$ th evolute.

We now have a $(1-1)$ correspondence between $p$ th evolutes of curves of $F_{n-1}$ and $p$-spaces in $H$.

Consider the case $p=1$. The transform of the common first evolute of $C_{1}$ and $C_{2}$ is $R^{*}{ }_{1}=A_{1}+\lambda_{2}\left(A_{2}-A_{1}\right)$, the straight line through $A_{1}$ and $A_{2}$. $C^{*}{ }_{1}$ actually corresponds to a segment of this line. The segment includes $A_{1}$ if and only if $\lambda_{2}=0$ for some $s$. The family of first evolutes of $C_{1}$ corresponds to the family of straight lines through $A_{1}$. Thus we have the following theorem.

Theorem 6. The family of geodesics (which are not straight lines) through a point of $D_{1}$ is the family of first evolutes of some curve of $F_{n-1}$.

Theorem 7. The angle between the tangents at corresponding points of two first evolutes of a given curve is constant. This angle is equal to the angle between the lines in $H$ which correspond to the two first evolutes.

Proof. Let the given curve be $C$ and let $C^{*}{ }_{1(i)}(i=1,2)$ be the common first evolute of $C$ and $C_{i}$. Since the tangent of $C^{*}{ }_{1(i)}$ is parallel to $r_{i}-r$, the cosine of the angle between the tangents is

$$
\begin{aligned}
\frac{\left(r_{1}-r\right)\left(r_{2}-r\right)}{\left|r_{1}-r\right|\left|r_{2}-r\right|} & =\frac{\left[\sum_{1}^{n-1}\left(A_{1} T_{i}\right) \xi_{i+1}\right]\left[\sum_{1}^{n-1}\left(A_{2} T_{j}\right) \xi_{j+1}\right]}{\sqrt{\left[\sum_{1}^{n-1}\left(A_{1} T_{i}\right) \xi_{i+1}\right]^{2}\left[\sum_{1}^{n-1}\left(A_{2} T_{j}\right) \xi_{j+1}\right]^{2}}} \\
& =\sum_{1}^{n-1}\left(A_{1} T_{i}\right)\left(A_{2} T_{i}\right) / \sqrt{\sum_{1}^{n-1}\left(A_{1} T_{i}\right)^{2} \sum_{1}^{n-1}\left(A_{2} T_{i}\right)^{2}} \\
& =A_{1} A_{2} / \sqrt{A_{1}^{2} A_{2}^{2}}
\end{aligned}
$$

## References

1. P. J. Da Cunha, Du parallelisme dans l'espace Euclidien, Portugaliae Math., 2 (1941), 181-246.
2. E. L. Ince, Ordinary differential equations (London, 1927).

[^0]:    Received November 1, 1951 ; in revised form May 22,1952 . In the first version of this paper only the case $n=4$ was considered; most of the results being from a Ph.D. thesis written under the direction of Professor H. S. M. Coxeter. The referee suggested that the theorems be generalized and stated many of the results that could be proved. I take this opportunity to thank him for his assistance.

[^1]:    ${ }^{1}$ At first only the cases $n=4, p=1$ and 3 were considered. The referee suggested that involutes and evolutes of other orders be introduced.

