

CONSISTENCY IN THE RECONSTRUCTION OF PATTERNS FROM SAMPLE DATA

BY
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1. **Introduction and summary.** Let A be a k -dimensional Euclidean region having unit volume. An m -colors pattern is a partition P_A of A into m sets $A_i, i=1, \dots, m$ with positive volume. P_A is called a random pattern if in addition the partition of A is a realization of a random process with the following stationarity and isotropy properties:

- (i) for all points $s \in A, P(s \in A_i) = p_i, i=1, \dots, m$
- (ii) for all pair of points $s, s' \in A$ with distance $|s-s'| = d$ between them, $P(s' \in A_i | s \in A_j) = P_{ij}(d), i, j=1, \dots, m.$

In [1], Switzer defines a reconstruction rule which produces an estimated reconstruction of the pattern using information obtained from n fixed sample-points $s_1 \dots s_n$ of A . To evaluate the accuracy of a reconstruction rule δ , applied to n sample-points, he proposes the loss function:

$$L_n = 1 - \mu[{}_n P_A^\delta \cap P_A]$$

where ${}_n P_A^\delta$ is the partition of A obtained from the reconstruction rule δ applied to the n sample-points; ${}_n P_A^\delta \cap P_A$ is the set of points which have the same color in ${}_n P_A^\delta$ and P_A ; μ is the Lebesgue measure.

In this note we define a notion of consistency for a reconstruction rule when the number of fixed sample-points increase and we give sufficient conditions under which the simple nearest-point rule [1] is consistent.

2. Consistency for a Reconstruction rule

DEFINITION. A rule for the reconstruction of a random pattern is consistent if the corresponding sequence of random variables $\langle L_n \rangle$ converges in probability to zero.

THEOREM. *A reconstruction rule δ is consistent if and only if*

$$\lim_{n \rightarrow \infty} E\mu[{}_n P_A^\delta \cap P_A] = 1.$$

Proof. $\langle 1 - \mu[{}_n P_A^\delta \cap P_A] \rangle$ is a sequence of random variables taking all their values on $[0, 1]$; if $\lim_{n \rightarrow \infty} E\mu[{}_n P_A^\delta \cap P_A] = 1$ then $\lim_{n \rightarrow \infty} E(1 - \mu[{}_n P_A^\delta \cap P_A])^2 = 0$ and hence $\langle L_n \rangle$ converges in probability to zero.

Conversely suppose that for all positive ϵ and δ there is an $N_{\epsilon, \delta}$ such that for all $n > N_{\epsilon, \delta}$:

$$P(\mu_{[n]n}P_A^\delta \cap P_A) < 1 - \epsilon) < \delta.$$

Since

$$E\mu_{[n]n}P_A^\delta \cap P_A = \int_0^{(1-\epsilon)^-} x dQ_n(x) + \int_{(1-\epsilon)^+}^1 x dQ_n(x)$$

where Q_n is the distribution of $\mu_{[n]n}P_A^\delta \cap P_A$, then

$$(1 - \epsilon)[1 - P(\mu_{[n]n}P_A^\delta \cap P_A) < 1 - \epsilon)] \leq E\mu_{[n]n}P_A^\delta \cap P_A \leq 1.$$

Therefore for all $n > N_{\epsilon, \delta}$

$$(1 - \epsilon)(1 - \delta) < E\mu_{[n]n}P_A^\delta \cap P_A \leq 1$$

and

$$\lim_{n \rightarrow \infty} E\mu_{[n]n}P_A^\delta \cap P_A = 1.$$

Q.E.D.

3. **Application to the simple nearest-point rules δ' .** The color assigned to a point $s \in A$, by the simple nearest-point rule, is the color of the unique sample-point $N(s)$ nearest to s (if $s \in A$ has not a unique nearest-sample point we assign to s an arbitrary color). For that rule Switzer [1, p. 139, Theorem 1] has shown that

$$E\mu_{[n]n}P_A^{\delta'} \cap P_A = \sum_{j=1}^m p_j \sum_{i=1}^n \int_{S_i} P_{jj}[|s - s_i|] d\mu(s)$$

where $S_i = \{s \in A : N(s) = s_i\}$.

As a consequence of our theorem we obtain:

COROLLARY 1. δ' is consistent if and only if for all j such that $p_j > 0$,

$$\lim_{n \rightarrow \infty} \sum_{i=1}^n \int_{S_i} P_{jj}[|s - s_i|] d\mu(s) = 1.$$

From Corollary 1, the following corollary can be easily proved.

COROLLARY 2. If for all j such that $p_j > 0$, P_{jj} is a nonincreasing function, strictly decreasing in a neighbourhood of zero, and such that $P_{jj}(0) = 1$ then δ' is consistent if

$$(1) \quad \lim_{n \rightarrow \infty} \max_{1 \leq i \leq n} \sup_{S_i} |s - s_i| = 0.$$

In the case where $k = 2, m = 2$ and

$$(2) \quad \begin{aligned} P_{11}(d) &= p_1 + (1 - p_1) e^{-cd} \\ P_{22}(d) &= (1 - p_1) + p_1 e^{-cd} \quad c > 0. \end{aligned}$$

Switzer [1, p. 142] considers certain types of arrangements for the sample-points. Because the functions given by (2) satisfy the conditions of Corollary 2 we can make the following observations about some arrangements suggested by Switzer:

(1) If the sample-points are placed at the vertices of a square grid then δ' is

consistent ($n \rightarrow \infty$ means here that the number of squares in the grid goes to infinity).

(2) If the sample-points are placed at the vertices of an equilateral triangular grid then δ' is consistent ($n \rightarrow \infty$ means here that the number of triangles in the grid goes to infinity).

(3) In the case called "line sampling with spacing σ " the condition (1) of Corollary 2 is not satisfied. Moreover, we have

$$\lim_{n \rightarrow \infty} 1 - E\mu[nP_A^{\delta'} \cap P_A] = 2p_1(1-p_1)[1 - 2(1 - e^{-\frac{1}{2}c\sigma})(c\sigma)^{-1}]$$

which is not zero for any $\sigma > 0$, then in that case δ' is not consistent.

REMARK. We have supposed that the color observed at each sample-point is the color of that point (i.e. there is no "measurement error"). The following example shows that this assumption is important for the validity of Corollary 2. Denote by Y_{s_i} the observation made at the point s_i ; suppose that Y_{s_i} is a random variable with values in $\{1, \dots, m\}$ (the event $Y_{s_i} = j$ is interpreted as "the point s_i is observed to be in A_j "). In addition, suppose that for each $i = 1, \dots, n$,

$$P[Y_{s_i} = j \mid s_i \in A_k] = f_{jk}, \quad k, j = 1, \dots, m,$$

and that the distribution of Y_{s_i} does not depend on the pattern in any other way. It is easy (cf. [2]) to prove that

$$E\mu[nP_A^{\delta'} \cap P_A] = \sum_{j=1}^m p_j \sum_{i=1}^n \int_{S_i} \sum_{k=1}^m f_{jk} P_{kj}(|s - s_i|) d\mu(s).$$

Then, under the conditions of Corollary 2, if there exists a j such that $p_j > 0$ and $f_{jj} < 1$, δ' is not consistent even if (1) is satisfied.

ACKNOWLEDGEMENT. I wish to thank Professor Paul Switzer for having read the first draft of this note and for having called [2] to my attention.

REFERENCES

1. P. Switzer, *Reconstructing patterns from sample data*, Ann. Math. Statist. **38** (1967), 138-154.
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