# ON THE CYCLIC COVERINGS OF THE KNOT $5_{2}$ 

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#### Abstract

We construct a family of hyperbolic 3 -manifolds whose fundamental groups admit a cyclic presentation. We prove that all these manifolds are cyclic branched coverings of $\mathbf{S}^{3}$ over the knot $S_{2}$ and we compute their homology groups. Moreover, we show that the cyclic presentations correspond to spines of the manifolds.


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## 1. Definitions and main results

In this paper we shall study a countable class of closed, connected, orientable 3manifolds $M_{n}$, whose fundamental groups are cyclically presented groups. We recall the notion of cyclic presentation of a group. Let $F_{n}$ be the free group on $n$ free generators $x_{0}, x_{1}, \cdots, x_{n-1}$, and let $\theta$ be the automorphism of $F_{n}$ defined by $\theta\left(x_{i}\right)=x_{i+1}$, for $i=0,1, \cdots, n-1$ (subscripts $\bmod n$ ). For any reduced word $w$ in $F_{n}$ define $G_{n}(w)=F_{n} / R$, where $R$ is the normal closure in $F_{n}$ of the set $\left\{w, \theta(w), \cdots, \theta^{n-1}(w)\right\}$. Then $G$ is said to be cyclically presented if $G$ is isomorphic to $G_{n}(w)$ for some $n$ and $w$. Some connections between cyclic presentations of groups and cyclic coverings of $\mathbf{S}^{3}$, branched over knots or links, have been studied in [2], [8] and [15].

A group presentation $\langle X \mid R\rangle$ is called geometric if there is a closed 3-manifold $M^{3}$ which admits a Heegaard diagram inducing $\langle X \mid R\rangle$ as a presentation of $\pi_{1}\left(M^{3}\right)$. Equivalently, $M^{3}$ admits a spine homeomorphic to the canonical complex associated to $\langle X \mid R\rangle$ (see [17]). As is well known, the canonical complex associated to a group presentation is a 2 -dimensional cell complex consisting of a unique vertex, a 1 -cell for each generator and a 2 -cell for each relator, whose boundary is glued to the 1 -skeleton according to the corresponding relator. Some relations between cyclic presentation of groups and spines of 3-manifolds are shown in [4].

Our main results show that the manifold $M_{n}$ is the $n$-fold cyclic covering of the 3 -sphere $\mathbf{S}^{3}$, branched over the knot $5_{2}$ (Rolfsen Notation [18]), and that $M_{n}$ is spherical for $n=1,2$ and hyperbolic for $n \geq 3$. Moreover, we find a cyclic presentation

[^0]for $\pi_{1}\left(M_{n}\right)$ and prove that such a presentation is geometric. Finally, since $5_{2}$ has the property of being a genus one knot, the homology characters of the manifolds can easily be computed as shown in Section 6.

## 2. Construction of a family of 3-manifolds $M_{n}$

The manifolds $M_{n}(n \geq 1)$ is defined by pairwise identification of the 2 -faces of a polyhedron $P_{n}$, which is homeomorphic to a 3-ball, whose boundary complex provides a tessellation of the 2 -sphere as depicted in Figure 1. The tessellation consists of $4 n$ quadrilaterals, $8 n$ edges and $4 n+2$ vertices. The $n$ quadrilaterals around the North Pole $N$ are labelled by $Q_{1}, Q_{2}, \ldots, Q_{n}$. The $n$ quadrilaterals around the South Pole $S$ which is the point at infinity in Figure 1 - are labelled by $R_{1}, R_{2}, \ldots, R_{n}$, and the other $2 n$ quadrilaterals are labelled by $Q_{1}^{\prime}, R_{1}^{\prime}, Q_{2}^{\prime}, R_{2}^{\prime}, \ldots, Q_{n}^{\prime}, R_{n}^{\prime}$, as indicated in Figure 1. To obtain $M_{n}$, we glue $Q_{i}$ with $Q_{i}^{\prime}$ (resp. $R_{i}$ with $R_{i}^{\prime}$ ), for each $i=1,2, \ldots, n$, by an orientation reversing identification which matches $N$ with $A_{i}$ (resp. $S$ with $B_{i}$ ). Via this glueing we get, for each $i=1,2, \ldots, n$, the following identifications on the edges: $N C_{i} \equiv A_{i} C_{i-1} \equiv A_{i-1} B_{i-2}$ (which we shall call $x_{i}$ ), $S A_{i+1} \equiv B_{i} A_{i+2} \equiv B_{i-1} D_{i} \equiv C_{i+1} D_{i+1}$ (which we shall call $y_{i}$ ), and $C_{1} D_{2} \equiv C_{2} D_{3} \equiv \cdots \equiv C_{n} D_{1}$ (which we shall call $z$ ). As a consequence the vertices match as follows: $N \equiv A_{i} \equiv D_{i}$ and $S \equiv B_{i} \equiv C_{i}$, for each $i=1,2, \ldots, n$. Observe that, here and in the following, subscripts are considered $\bmod n$. Thus, we obtain a 3-dimensional cellular complex $K_{n}$, having one 3 -cell, $2 n$ quadrilaterals, $2 n+1$ edges and two vertices. Since its Euler characteristic is


Figure 1
$\chi\left(K_{n}\right)=2-(2 n+1)+2 n-1=0$, the space $M_{n}=\left|K_{n}\right|$ is a genuine closed, connected, orientable 3-manifold according to the Seifert-Threlfall criterion (see [20, p. 216]).

## 3. $M_{n}$ as branched cyclic covering of the 3 -sphere

Let $\theta_{n}$ be the clockwise rotation of $2 \pi / n$ radians around the polar axis of the 3 -ball $P_{n}$. It is easy to see that all the above defined identifications are invariant with respect to this rotation; therefore $\theta_{n}$ induces an orientation preserving homeomorphism $g_{n}$ on $M_{n}$. The set Fix $\left(g_{n}\right)$ consists of the points of the polar diameter NS and the points of the edge $z$. Let $G_{n}$ be the cyclic group of homeomorphisms of $M_{n}$ generated by $g_{n}$. Of course, $G_{n}$ has order $n$ and $\operatorname{Fix}\left(g_{n}^{k}\right)=\operatorname{Fix}\left(g_{n}\right)$ for each $k=1,2, \ldots, n-1$. The quotient space $M_{n} / G_{n}$ is homeomorphic to $M_{1}$ and the canonical quotient map

$$
p_{n}: M_{n} / G_{n} \rightarrow M_{1}
$$

is an $n$-fold branched cyclic covering, whose branching set is the 1 -subcomplex of $M_{1}$ composed of $N S$ and $z$ (see Figure 2, where the branching set is shown by a thick line and each of the boundary quadrilaterals $Q, Q^{\prime}, R, R^{\prime}$ is subdivided into four triangles).

Figures 2-7 depict, in detail, the identifications performed on the 2-sphere of Figure 2 to obtain $M_{1}$, showing the development of the branching set. More precisely, we have successively performed the identifications between the following regions: $q_{1}$ and $q_{4}$ with $q_{1}^{\prime}$ and $q_{4}^{\prime}$ (Fig. $2 \rightarrow$ Fig. 3), $q_{2}$ and $q_{3}$ with $q_{2}^{\prime}$ and $q_{3}^{\prime}$ (Fig $3 \rightarrow$ Fig. 4), $r_{1}$ with $r_{1}^{\prime}$ (Fig. $4 \rightarrow$ Fig. 5), $r_{2}$ with $r_{2}^{\prime}$ (Fig. $5 \rightarrow$ Fig. 6). Notice that the complex is a three-ball at each of these stages. As a final step we identify $r_{3}$ and $r_{4}$ with $r_{3}^{\prime}$ and $r_{4}^{\prime}$ obtaining a threesphere, where the branching set is a knot embedded as in Figure 7.'

Hence, $M_{1}$ is homeomorphic to a 3 -sphere and the branching set is the two-bridge knot $\mathbf{b}(7,3)$, according to Schubert's notation (see [1. p. 181]), which is the knot $5_{2}$ of the Alexander, Briggs, Reidemeister table ([1, p. 312]).

So we have proved the following:

Theorem 1. The manifold $M_{n}$ is the $n$-fold cyclic covering of $\mathbf{S}^{3}$, branched over the two-bridge knot $\mathbf{b}(7,3)$.

As already known, the 2 -fold branched coverings of the two-bridge knot or link $\mathbf{b}(p, q)$ is the lens space $L(p, q)$ (see [19]). Therefore, we immediately have:

Corollary 2. The manifold $M_{2}$ is the lens space $L(7,3)$.
Remark 1. From a result of [16], each $M_{n}$ turns out to be an element of a certain class of manifolds $S(b, l, t, c)$, depending on four integer parameters, introduced in [13].

[^1]

Figure 2


Figure 3


Figure 4


Figure 5


Figure 6


Figure 7

In particular, $M_{n}$ is homeomorphic to the Lins-Mandel space $S(n, 7,3, n-1)=$ $S(n, 7,4,1)$.

## 4. Geometric structure on $M_{n}$

The topological properties of $M_{n}$ established by Theorem 1 easily allow us to derive its geometric structure:

Proposition 3. The manifold $M_{n}$ has a spherical structure for $n=1,2$ and $a$ hyperbolic structure for $n>2$.

Proof. As is well known, the $n$-fold cyclic covering of $S^{3}$ branched over a knot $K$ has the same geometric structure of the orbifold $(K, n)$, which has $\mathbf{S}^{3}$ as its underlying space and $K$ as its singular set with a cyclic isotropy group of order $n$ (for example, see [3, p. 69]). Since the orbifold (b(7,3),n) is hyperbolic for $n>2$ and spherical for $n=1,2([9$, Theorem 3.1]), the statement is proved.

Remark 2. Observe that $M_{3}$ is the Fomenko-Matveev-Weeks manifold $Q_{1}$, which is the hyperbolic 3 -manifold with the smallest known volume (vol. $=0.9427 \ldots$.). For more details, see [11], [14], [21] and Chapter 2 of [12].

## 5. A geometric cyclic presentation for $\boldsymbol{\pi}_{1}\left(\boldsymbol{M}_{n}\right)$

From the 2 -skeleton of $K_{n}$ it is easy to get a presentation of the fundamental group $\pi_{1}\left(M_{n}\right)$. Orienting the edges of $K_{n}$ as in Figure 1 and squeezing $z$ to a point, we get $2 n$ generators $x_{1}, x_{2}, \ldots, x_{n}, y_{1}, y_{2}, \ldots, y_{n}$ subject to $n$ relations of type $x_{i+1} y_{i} x_{i}^{-1}=1$ (derived from $Q_{i}$ ) and $n$ relations of type $y_{i} x_{i+2} y_{i} y_{i+1}^{-1}=1$ (derived from $R_{i}$ ). Since the


Figure 8
first relations give $y_{i}=x_{i+1}^{-1} x_{i}$, the second relations become $x_{i+1}^{-1} x_{i} x_{i+2} x_{i+1}^{-1} x_{i} x_{i+1}^{-1} x_{i+2}=1$. Hence, the fundamental group of $M_{n}$ admits the following cyclic presentation with $n$ generators:

$$
\begin{equation*}
\pi_{1}\left(M_{n}\right)=<\left\{x_{i}\right\}_{i \in \mathcal{Z}_{n}} \mid\left\{x_{i+1}^{-1} x_{i} x_{i+2} x_{i+1}^{-1} x_{i} x_{i+1}^{-1} x_{i+2}\right\}_{i \in \mathcal{Z}_{n}}>. \tag{1}
\end{equation*}
$$

A family of Heegaard diagrams $H_{n}, n \geq 1$, corresponding to such cyclic presentations is depicted in Figure 8 (where the circle $C_{i}$ must be identified with the circle $C_{i}^{\prime}$, for each $i=0, \ldots, n-1$, according to the labelling of their vertices). Note that this family has cyclic symmetry and it is a particular case of the ones studied in [4]. More precisely, it is exactly the ( $7,3,0,1,2,-2$ ) class of Table 1 of that paper.

It is easy to see that $H_{1}$ is a Heegaard diagram of $S^{3}$ and that it is the quotient of $H_{n}$ via the cyclic action. Therefore, $H_{n}$ is a Heegaard diagram of a 3-manifold, which is an $n$-fold cyclic covering of $\mathbf{S}^{3}$ with branching set independent of $n$. A simple test ${ }^{2}$ shows that $H_{2}$ is a Heegaard diagram of the lens space $L(7,3)$. Since $L(7,3)$ admits a unique representation as 2 -fold branched covering of $\mathbf{S}^{3}$ (namely, over the two-bridge knot $\mathbf{b}(7,3)$ ), we have the following result:

Proposition 4. The manifold $M_{n}$ admits a spine which corresponds to the cyclic presentation (1).

[^2]
## 6. Homology characters of $M_{n}$

The two-bridge $\operatorname{knot} \mathbf{b}(7,3)$ is a genus one knot (see [7, Satz 5.1]), and so the homology characters of $M_{n}$ can be computed:

Proposition 5. The first homology group of $M_{n}$ is

$$
H_{1}\left(M_{n}\right) \cong \begin{cases}\mathbf{Z}_{7\left|a_{n}\right|} \oplus \mathbf{Z}_{\left|a_{n}\right|} & \text { if } n \text { is even } \\ \mathbf{Z}_{\left|b_{n}\right|} \oplus \mathbf{Z}_{\left|b_{n}\right|} & \text { if } n \text { is odd }\end{cases}
$$

where, for each $n>0$ :

$$
\begin{aligned}
& a_{1}=1, a_{2}=1, a_{n+2}=a_{n+1}-2 a_{n} \\
& b_{1}=1, b_{2}=-3, b_{n+2}=b_{n+1}-2 b_{n}
\end{aligned}
$$

Proof. A Seifert matrix of $\mathbf{b}(7,3)$ is $V=\left(\begin{array}{cc}2 & -2 \\ -1 & 2\end{array}\right)$ (see Table II of [1]). Thus, Theorem 1 of [6] applies with $\gamma=\operatorname{det}(V)=2$ and $\omega=$ g.c.d. $\left(v_{11}, v_{12}+v_{21}, v_{22}\right)=1$.

The following table exhibits the torsion coefficients of $H_{1}\left(M_{n}\right)$, for $n \leq 15 .^{3}$

| $n$ | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| $\tau_{1}$ | 7 | 5 | 21 | 11 | 35 | 13 | 21 | 5 | 77 | 67 | 315 | 181 | 637 | 275 |  |
| $\tau_{2}$ | 1 | 5 | 3 | 11 | 5 | 13 | 3 | 5 | 11 | 67 | 45 | 181 | 91 | 275 |  |

Table 1

## 7. How many different "cyclic" identifications can be defined on $P_{n}$ ?

Finally, we examined which 3-manifolds arise from different identification-systems on the boundary of $P_{n}$. Of course, the general problem is intractable; therefore, we investigated cases that were quite similar to the one studied in the previous sections.

In fact, we defined the identification-system $t_{n}$ on $P_{n}$ as being admissible when the following conditions are fulfilled:
(a) $l_{n}$ is orientation reversing and invariant with respect to the action of $G_{n}$;
(b) the space $\left|\bar{K}_{1}\right|=\left|P_{1} / l_{1}\right|$ is homeomorphic to $S^{3}$;
(c) the space $\left|\bar{K}_{n}\right|=\left|P_{n} / l_{n}\right|$ is homeomorphic to a 3-manifold for each $n \geq 1$.

In this way, each element of the resulting (admissible) family is a cyclic covering of $\mathbf{S}^{3}$, branched over a suitable subcomplex of the 1 -skeleton of $\bar{K}_{1}$ and over the polar diameter NS. Moreover, since a cyclic covering of a graph (with some vertices of

[^3]

Figure 9
degree $>2$ ) cannot be a 3 -manifold, the branching set of an admissible family must be a knot or a link.

We developed this part of our research in two steps: first we studied all the possible orientation reversing identification-systems ${ }^{4}$ on $P_{1}$, checking that only three produced the 3 -sphere: $K_{1}, K_{1}^{\prime}$ and $K_{2}^{\prime \prime}$. Figure 9 shows the corresponding identification-systems on $P_{1}$, which glue $Q$ with $Q^{\prime}$ and $R$ with $R^{\prime}$, matching up their starred reference points.

In each of these three cases, the cellular complex has two vertices ( $N$ and $S$ ) and three edges connecting them ( $x, y$ and $z$ ). Hence, each family arising from these cases (admissible or not) consists of branched cyclic coverings of a knot, or of a graph with two vertices of degree $>2$ (the points $N$ and $S$ ). We then checked all 12 possible cases with $n=2$ arising from $K_{1}, K_{1}^{\prime}$ or $K_{1}^{\prime \prime}$. In detail, starting from the complex $\partial\left(P_{2}\right)$ depicted in Figure 10, we tested - in the same way of Section 5 - all the spaces obtained by gluing $Q_{1}$ with $T_{i}$ and $Q_{2}$ with $T_{i+2}$, for $i=1,3$ (note that the subscripts are $\bmod 4$ ), combined with all the identifications of $R_{1}$ and $R_{2}$, either with $T_{i-1}$ and $T_{i+1}$ or with $T_{i+1}$ and $T_{i-1}$. Among the resulting combinations, seven give $S^{3}$, two give the lens space $L(7,3)$ and the other three fail to produce 3 -manifolds. Because of the uniqueness of the representation of lens spaces (including the 3 -sphere) as 2 -fold coverings of knots or links [10], these different admissible identification-systems produce no non-trivial family of 3-manifolds, except the $M_{n}$ 's already studied.

[^4]

Figure 10

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[^1]:    'For the reader's convenience, the starred reference points in the figures underline the above identifications.

[^2]:    ${ }^{2}$ The test has been conducted with the aid of a computer program, written by the first author's research group, which checks topological and algebraic properties of (pseudo-) manifolds of relatively little "complexity" using combinatorial tools. See [5] for a survey of these techniques.

[^3]:    ${ }^{3}$ Compare Appendix of [13].

[^4]:    ${ }^{4}$ There are 32 of them, up to symmetry.

