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# *Ergodic theory and dynamical systems*

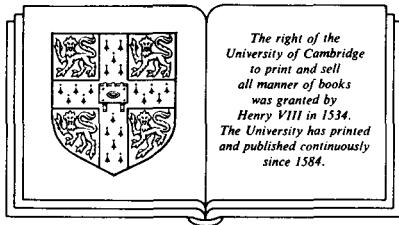
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