# INTEGRAL p-adic NORMAL MATRICES SATISFYING THE INCIDENCE EQUATION 

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1. Introduction. The problem of arranging $v$ elements into $v$ sets in such a way that every set contains exactly $k$ distinct elements and that every pair of sets has exactly $\lambda=k(k-1) /(v-1)$ elements in common, where $0<\lambda<$ $k<v$, is equivalent to finding a normal integral $v$ by $v$ matrix $A$ such that $A^{T} A=B$, where $B$ is the $v$ by $v$ matrix having $k$ in every position on the main diagonal and $\lambda$ in all other positions (10). Utilizing the fact that for the existence of a $\lambda, k, v$ design it is necessary that $I$ (the $v$ by $v$ identity matrix) represent $B$ rationally, (2) and (3) have proved the non-existence of certain $\lambda, k, v$ designs. Neither of the proofs utilize the fact that it is necessary that $A$ be normal. However, Albert (1) for the projective plane case and Hall and Ryser (5) for the general design proved that if there exists a rational $A$ such that $A^{T} A=B$ then there exists a normal rational matrix satisfying the same equation. Thus the requirement of normality does not exclude any $\lambda, k, v$ which were not previously excluded.

It is evident that for the existence of a $\lambda, k, v$ design it is necessary that for every prime $p$ there exist an integral $p$-adic normal matrix $A$ satisfying $A^{T} A=$ $B$. Assuming that $(k, k-\lambda)=1$, we prove in $\S 2$ that if $I$ represents $B$ rationally then this necessary condition is satisfied. Thus, once again, no additional designs are excluded. It does follow, however, that if $I$ represents $B$ rationally then $I$ represents $B$ without essential denominator and, furthermore, that there is a form in the genus of $I$ which represents $B$ integrally.

In § 3 we consider a modified incidence equation which is satisfied by every incidence matrix and which, if $I$ represents $B$ rationally, has integral solutions. Sufficient conditions for the existence of a $\lambda, k v$ design in terms of these integral solutions are given.
2. The incidence equation examined locally. We assume throughout this paper that $(k, k-\lambda)=1$. Thus, since $\lambda v=k^{2}-(k-\lambda)$ we have $(\lambda, k)=(\lambda, k-\lambda)=(v, k)=(v, k-\lambda)=1$. The matrices $I$ and $B$ are as above. We prove

Theorem 1. If I represents $B$ rationally then for every prime $p$ there exists a matrix $A$ with elements in the ring $R(p)$ of $p$-adic integers such that $A^{T} A=A A^{T}$ $=B$.

[^0]We show first that there exists a matrix $C$ (not necessarily normal) with elements in $R(p)$ such that $C^{T} C=B$. It follows from well-known theorems on quadratic forms (7) and the fact that $I$ and $B$ are both positive definite that it is sufficient to show this for all primes $p \in P$, where $P$ is the set of all prime divisors of $2 \cdot \operatorname{det} B=2 k^{2}(k-\lambda)^{v-1}$. Let $T$ be the $v$ by $v$ matrix

$$
\left[\begin{array}{rrrrr}
1 & -1 & -1 & -1 & -1 \\
1 & 1 & 0 & 0 & 0 \\
1 & 0 & 1 & 0 & 0 \\
1 & 0 & 0 & 1 & 0 \\
. & . & . & . & . \\
. & . & . & . & . \\
. & . & . & . & . \\
1 & 0 & 0 & 0 & 1
\end{array}\right] .
$$

Then

$$
T^{T} T=\left[\begin{array}{cc}
v & 0 \\
0 & I_{1}+S_{1}
\end{array}\right]
$$

where $I_{1}$ is the $(v-1)$ by $(v-1)$ identity matrix and $S_{1}$ is the $(v-1)$ by ( $v-1$ ) matrix each of whose entries is 1 . Also,

$$
T^{T} B T=\left[\begin{array}{lc}
k^{2} v & 0 \\
0 & (k-\lambda)\left(I_{1}+S_{1}\right)
\end{array}\right] .
$$

Since $(k, k-\lambda)=1, v$ is a $p$-adic unit for all odd $p \in P . v$ is also a 2 -adic unit in the case that $v$ is odd. Hence, for odd $p, X^{T} X=B$ is solvable in $R(p), p \in P$, if and only if $X^{T}\left(T^{T} T\right) X=T^{T} B T$ is solvable in $R(p)$; and for odd $v, X^{T} X=B$ is solvable in $R(2)$ if and only if $X^{T}\left(T^{T} T\right) X=T^{T} B T$ is solvable in $R(2)$.

We first dispose of the case when $v$ is even. Since $I$ represents $B$ rationally, ( $k-\lambda$ ) is a square (3); whence, obviously $T^{T} T$ represents $T^{T} B T$ in $R(p)$ for all odd $p \in P$. Furthermore, since $v$ is even and $(k, k-\lambda)=1$ it follows that $k$ and $k-\lambda$ are both odd. Thus $I$ and $B$ are properly primitive forms (that is, each has a 2 -adic unit element on its main diagonal) with unit 2 -adic determinants which, since they are rationally congruent, are congruent over the 2 -adic field. Hence (7, Theorem 36) they are equivalent in $R(2)$. Thus, if $v$ is even $I$ represents $B$ in $R(p)$ all $p \in P$.

Suppose now that $v$ is odd. It is clearly sufficient to show that $I_{1}+S_{1}$ represents $(k-\lambda)\left(I_{1}+S_{1}\right)$ in $R(p)$ for all $p \in P$.
(i) $I_{1}+S_{1}$ represents $(k-\lambda)\left(I_{1}+S_{1}\right)$ in $R(2)$.
(a) Suppose $(k-\lambda)=2^{2 b} m$ where $b \geqslant 0$ and $m$ is odd. We make use here, and below, of the following known theorem (6):

Two improperly primitive forms (that is, each form has some 2 -adic unit element but no 2 -adic unit element on its main diagonal) in the same number
of variables and of odd determinants are equivalent in $R(2)$ if and only if their determinants are congruent mod 8.

From this it follows that $I_{1}+S_{1}$ and $m\left(I_{1}+S_{1}\right)$ are equivalent in $R(2)$. But then, obviously, $I_{1}+S_{1}$ represents $2^{2 b} m\left(I_{1}+S_{1}\right)$ in $R(2)$.
(b) Suppose $k-\lambda=2^{2 b+1} m$ where $m$ is odd. We shall show below that in this case the assumption that $I$ represents $B$ rationally implies that $v= \pm 1$ $\bmod 8$.

If $v \equiv 1 \bmod 8$ then $I_{1}+S_{1}$ and $m\left(I_{1}+S_{1}\right)$ are both equivalent to the $\frac{1}{2}(v-1)$ fold direct sum of the matrix

$$
\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right]
$$

Call the direct sum matrix $K$. It is thus sufficient to show that $K$ represents $2^{2 b+1} K$. Since $v \equiv 1 \bmod 8,4 \mid v-1$. Let $L$ be the $\frac{1}{4}(v-1)$ fold direct sum of

$$
\left[\begin{array}{rrrr}
0 & 1 & 0 & 1 \\
1 & 0 & 1 & 0 \\
0 & 1 & 0 & -1 \\
1 & 0 & -1 & 0
\end{array}\right] .
$$

Then $\left(2^{b} L\right)^{T} K\left(2^{b} L\right)=2^{b+1} K$ as desired.
If $v \equiv-1 \bmod 8$ then $I_{1}+S_{1}$ and $m\left(I_{1}+S_{1}\right)$ are both equivalent in $R(2)$ to $K_{1} \oplus K_{2}$. Here $\oplus$ denotes direct sum, $K_{1}$ is the $\frac{1}{2}(v-7)$ fold direct sum of

$$
\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right]
$$

and $K_{2}$ is the 6 by 6 matrix having each entry on its main diagonal equal to 2 and all other entries equal to 1 . Note that $4 \mid v-7$. Let $L_{1}$ be the $\frac{1}{4}(v-7)$ fold direct sum of the 4 by 4 matrix given in the preceding paragraph, and let $L_{2}$ be the matrix

$$
\left[\begin{array}{rrrrrr}
-1 & 0 & -1 & -1 & -1 & 0 \\
1 & 0 & 0 & 0 & 1 & 1 \\
-1 & -1 & -1 & 0 & 0 & -1 \\
0 & 0 & 1 & 1 & 0 & 1 \\
0 & 1 & 1 & 0 & 1 & 0 \\
1 & 1 & 0 & 1 & 0 & 0
\end{array}\right]
$$

Then $\left[2^{b}\left(L_{1} \oplus L_{2}\right)\right]^{T}\left(K_{1} \oplus K_{2}\right)\left[2^{b}\left(L_{1} \oplus L_{2}\right)\right]=2^{2 b+1}\left(K_{1} \oplus K_{2}\right)$; whence, $I_{1}+S_{1}$ represents $(k-\lambda)\left(I_{1}+S_{1}\right)$ in $R(2)$ as desired.

It remains to show that if $I$ represents $B$ rationally and if $k-\lambda=2^{2 b+1} m$, $m$ odd, then $v \equiv \pm 1 \bmod 8$. Since $\lambda v=k^{2}-(k-\lambda)$ we have

$$
\left(\frac{k-\lambda}{\lambda}\right)=\left(\frac{2}{\lambda}\right)\left(\frac{m}{\lambda}\right)=1
$$

where $(a / b)$ is the Jacobi symbol. (Since $(k, k-\lambda)=1, \lambda$ is odd.) We thus have

$$
\left(\frac{\lambda}{m}\right)=\left(\frac{2}{\lambda}\right)(-1)^{\frac{m-1}{2} \cdot \frac{\lambda-1}{2}}
$$

We consider the cases $b \geqslant 1, b=0$ separately.
If $b \geqslant 1$ then $\lambda \equiv v \bmod 8$. If $v=3 \bmod 8$ then $(-\lambda / m)=-1$ but this is impossible since $I$ represents $B$ rationally (3). The case $v \equiv 5 \bmod 8$ is disposed of similarly.

If $b=0$ then $\lambda v \equiv-1$ or $3 \bmod 8$ according as $k-\lambda \equiv 2$ or $6 \bmod 8$. If $k-\lambda \equiv 2 \bmod 8$ and $v \equiv 3 \bmod 8$ then $(-\lambda / m)=-1$ which is impossible. Similar easy computations exclude all possibilities other than $v \equiv \pm 1 \mathrm{mod}$ 8.
(ii) $I_{1}+S_{1}$ represents $(k-\lambda)\left(I_{1}+S_{1}\right)$ in $R(p)$ for all odd $p$ such that $p \mid k$. We make use here, and below, of the following known theorem ( $\mathbf{6}, 11$ ).
For odd $p$, two forms, $f$ and $g$, in the same number of variables and of unit determinants in $R(p)$ are equivalent in $R(p)$ if and only if

$$
\left(\frac{\operatorname{det} f}{p}\right)=\left(\frac{\operatorname{det} g}{p}\right)
$$

The desired result is an immediate consequence of this theorem. We actually have somewhat more; namely, $I_{1}+S_{1}$ represents $(k-\lambda)\left(I_{1}+S_{1}\right)$ in $R(p)$ for all odd $p$ such that $p \nmid(k-\lambda) v$.
(iii) $I_{1}+S_{1}$ represents $(k-\lambda)\left(I_{1}+S_{1}\right)$ in $R(p)$ for all odd $p$ such that $p \mid(k-\lambda)$. Suppose $(k-\lambda)=p^{b} m$ where $(p, m)=1$ and $b>0$. We consider two cases: $(a) v \equiv 1 \bmod 4$, and (b) $v \equiv 3 \bmod 4$.
(a) Since $I$ represents $B$ rationally we must have $(v / p)=(\lambda / p)=1$, (2). Thus det $\left(I_{1}+S_{1}\right)=v$ and $\operatorname{det}\left[m\left(I_{1}+S_{1}\right)\right]=m^{v-1} v$ are both units and perfect squares in $R(p)$. Therefore, $I_{1}+S_{1}$ and $m\left(I_{1}+S_{1}\right)$ are both equivalent in $R(p)$ to $I_{1}$. It is thus sufficient to show that $I_{1}$ represents $p^{b} I_{1}$ in $R(p)$. If $b$ is even, this is obvious. Suppose then that $b=2 c+1$. We use the device employed in (3). There exist integers $a_{i}, i=1,2,3,4$, such that $\sum_{1}{ }^{4} a_{i}{ }^{2}=p$. Let $L$ be the $\frac{1}{4}(v-1)$ fold direct sum of

$$
p^{c} \cdot\left[\begin{array}{rrrr}
a_{1} & a_{2} & a_{3} & a_{4} \\
a_{2} & -a_{1} & -a_{4} & a_{3} \\
a_{3} & a_{4} & -a_{1} & -a_{2} \\
a_{4} & -a_{3} & a_{2} & -a_{1}
\end{array}\right] .
$$

Then $L^{T} L=p^{2 c+1} I_{1}$ as desired.
(b) For $v \equiv 3 \bmod 4$ we must have

$$
\left(\frac{v}{p}\right)=\left(\frac{\lambda}{p}\right)=(-1)^{\frac{p-1}{2}}
$$

(3). Thus $I_{1}+S_{1}$ and $m\left(I_{1}+S_{1}\right)$ are both equivalent to the $(v-1)$ $(v-1)$ diagonal matrix $\left[1,1, \ldots, 1,(-1)^{\frac{1}{p} p-\frac{1}{2}}\right]=J$. We must show that $J$ represents $p^{b} J$. For even $b$ this is obvious and so we may take $b=2 c+1$. If $p \equiv 3 \bmod 4$ then let $L_{1}$ be the $\frac{1}{4}(v-3)$ fold direct sum of the 4 by 4 matrix given in the previous paragraph and let

$$
L_{2}=p^{c}\left[\begin{array}{ll}
a & 1 \\
1 & a
\end{array}\right]
$$

where $a$ is a $p$-adic integer such that $a^{2}=1+p$. Then $\left[\left(L_{1} \oplus L_{2}\right)\right]^{T} J\left[\left(L_{1} \oplus\right.\right.$ $\left.\left.L_{2}\right)\right]=p^{b} J$. If $p=1 \bmod 4$ then there exist integers $a_{1}$ and $a_{2}$ such that $a_{1}{ }^{2}+$ $a_{2}{ }^{2}=p$. Let $L$ be the $\frac{1}{2}(v-1)$ fold direct sum of

$$
p^{c}\left[\begin{array}{rr}
a_{1} & a_{2} \\
a_{2} & -a_{1}
\end{array}\right]
$$

Then $L^{T} J L=p^{b} J$.
It follows from all the above that for every $p$ there exists a matrix $C$ with elements in $R(p)$ such that $C^{T} C=B$. It remains to show that there exists a normal matrix with the desired properties. If $p \nmid v$ this is clear. In fact, we have seen above that for every $p \nmid v$ there exists a $C_{1}$ with elements in $R(p)$ such that $C_{1}{ }^{T}\left(I_{1}+S_{1}\right) C_{1}=(k-\lambda)\left(I_{1}+S_{1}\right)$. Let $A=T\left(k \oplus C_{1}\right) \quad T^{-1}$. Then $A^{T} A=B$ and $A S=k S$, where $S$ is the $v$ by $v$ matrix composed entirely of ones; whence by (5, Theorem 3.1) $A$ is normal. Since $p \nmid v, A$ has its elements in $R(p)$.

Suppose $p \mid v$. We know that there exists a matrix $C=\left(c_{i j}\right)$ with elements in $R(p)$ such that $C^{T} C=B$. Let $\alpha$ be the column vector $\left[r_{1}, r_{2}, \ldots, r_{v}\right]$ where $r_{i}=\sum_{j} c_{i j}$, and let $\beta$ be the $v$ by 1 column vector each of whose entries is $k$. We will show that there exists an orthogonal matrix $O$ with elements in $R(p)$ such that $O \alpha=\beta$. It will follow that $A=O C$ is such that $A^{T} A=B, A S=k S$; and again by (5), $A$ is normal as desired.

We use the following theorem (4, Satz 10.4). It is stated here more concretely and in a less general form that in (4).

Let $V$ be a $v$ dimensional vector space of column vectors over the $p$-adic field with a non-degenerate ground form given by the $v$ by $v$ symmetric matrix $G$. Let $\mathscr{F}$ be a lattice in $V$ and let $\mathscr{D}$ be its different. If $\alpha$ and $\beta$ are primitive vectors in $\mathscr{F}$ such that $\alpha^{T} G \alpha=\beta^{T} G \beta$ and $\alpha-\beta \in \mathscr{D}$ then there exists a $v$ by $v$ matrix $O$ with elements in $R(p)$ such that $O^{T} G O=G$ and $O \alpha=\beta$.

For our purposes we take $G$ to be the identity matrix, $\mathscr{F}$ as the lattice which has as a basis the column vectors of the identity matrix $I$, and $\alpha$ and $\beta$ as above. We note that if $p$ is odd then $\mathscr{D}=\mathscr{F}$, and if $p=2$ then $\mathscr{D}$ is the lattice which has as a basis the column vectors of $2 I$. From the fact that $C^{T} C=B$ it follows easily (10) that $\sum_{j} c_{j i} r_{j}=k^{2}$ and $\sum_{i} r_{i}{ }^{2}=k^{2} v$. From the first of the latter equations and the facts that $p \mid v,(k, v)=1$ it follows that $\alpha$ and $\beta$ are both primitive. From the second of these equations it follows that $\alpha^{T} \alpha=\beta^{T} \beta$. Hence if $p$ is odd the desired $O$ exists.

In order to complete the proof for $p=2$ it is sufficient to show that $r_{i}{ }^{2} \equiv 1$ $\bmod 2$. Let $t_{i j}$ be the inner product of the $i$ th and $j$ th rows of $C$. Again as in (10) we have

$$
k^{2} t_{i j}=\lambda r_{i} r_{j}+k^{2}(k-\lambda) \delta_{i j} .
$$

If $r_{i}{ }^{2} \equiv 0 \bmod 2$ then $t_{i i} \equiv 1 \bmod 2$ and we would have

$$
0 \equiv r_{i}^{2} \equiv \sum_{j} c_{i j}^{2} \equiv t_{i i} \equiv 1 \bmod 2
$$

which is clearly absurd.
This completes the proof of Theorem 1.
As immediate consequences we have
Corollary 1. If I represents $B$ over the rational field then $I$ represents $B$ rationally without essential denominator, that is, for every positive integer $m$ there is a matrix $D$ with rational elements whose denominators are prime to $m$ such that $D^{T} D=B$.

Corollary 2. If I represents $B$ rationally then there exists a form in the genus of $I$ which represents $B$ integrally.
3. A modified incidence equation. Since the genus of the identity contains more than one class for $v>8$ (8) Corollary 2 does not yield any new designs. It is natural, therefore, to examine a matric equation, akin to $X^{T} X=$ $B$, which is still satisfied by every incidence matrix, has integral solutions, and then to examine the relationship of these integral solutions to incidence matrices.

Theorem 2. Let $t=a / b$ be a rational number greater than $1 / v$ such that $(a v-b) b$ is odd. Let $S$ be the $v$ by v matrix composed entirely of ones. If I represents $B$ rationally then $I-t S$ represents $B-t k^{2} S$ integrally.

For by Theorem 1, $b I-a S$ represents $b B-a k^{2} S$ in every $R(p)$. (The normality of $A$ implies that $S A=A S=k S$ and therefore $A^{T}(b I-a S) A=$ $b B-a k^{2} S$.) Hence there exists a form in the genus of $b I-a S$ which represents $b B-a k^{2} S$ integrally. Since the genus of an indefinite form of odd determinant in $v>2$ variables consists of exactly one class (9) Theorem 2 follows.

Let $\mathscr{S}$ be the set of all rationals which have the properties stated in Theorem 2. For $t \in \mathscr{S}$ let $A(t)=\left(a_{i j}(t)\right)$ denote an arbitrary but fixed integral solution of $X^{T}(I-t S) X=B-t k^{2} S$. Let $r_{i}(t)=\sum_{j} a_{i j}(t)$, and $s_{j}(t)=\sum_{i} a_{i j}(t)$.

Theorem 3: (i) If $A\left(t_{0}\right)$ is normal and $t_{0} \neq\left(k+(k-\lambda)^{\frac{1}{2}}\right) / k v$ then $A\left(t_{0}\right)$ is an incidence matrix or the negative of one.
(ii) If for $t_{1}, t_{2} \in \mathscr{S}, t_{1} \neq t_{2}$ we have $r_{i}\left(t_{1}\right)=r_{i}\left(t_{2}\right)\left(s_{i}\left(t_{1}\right)=s_{i}\left(t_{2}\right)\right)$ for $i=1,2,3, \ldots, v$, then $A\left(t_{1}\right)$ is an incidence matrix or the negative of one.
(iii) If there exists an $M$ and a subset $\mathscr{S}_{1}$ of $\mathscr{S}$ containing sufficiently many distinct elements (see below) such that $\left|r_{i}(t)\right|<M\left(\left|s_{i}(t)\right|<M\right)$ for $t \in \mathscr{S}^{\prime}$ and
$i=1,2, \ldots, v$ then there exists a $t_{0} \in \mathscr{S}^{\prime}$ such that $A\left(t_{0}\right)$ is an incidence matrix or the negative of one.
(iv) If $r_{i}\left(t_{0}\right)>0$ for $i=1,2, \ldots$, v and for $t_{0}>1$ then $A\left(t_{0}\right)$ is an incidence matrix.
(i) As in (10) the following relations may be established: For every $t \in \mathscr{S}$,

$$
\begin{gathered}
\sum r_{i}^{2}(t)-t\left(\sum r_{i}(t)\right)^{2}=k^{2} v(1-t v) \\
k^{2}(1-t v)\left(\sum s_{i}^{2}(t)\right)+\left(k^{2} t-\lambda\right)\left(\sum r_{i}(t)\right)^{2}=k^{2}(k-\lambda) v
\end{gathered}
$$

Now the normality of $A\left(t_{0}\right)$ implies that $\sum r_{i}{ }^{2}\left(t_{0}\right)=\sum s_{i}{ }^{2}\left(t_{0}\right)$. Since $t_{0} \neq(k+$ $\left.(k-\lambda)^{\frac{1}{2}}\right) / k v$, the above equations imply that $\sum r_{i}{ }^{2}\left(t_{0}\right)=k^{2} v$ and $\sum s_{i}\left(t_{0}\right)=$ $\sum r_{i}\left(t_{0}\right)= \pm k v$. Whence $r_{i}\left(t_{0}\right)=s_{i}\left(t_{0}\right)=k$ or $r_{i}\left(t_{0}\right)=s_{i}\left(t_{0}\right)=-k$ for all $i$. But then $A^{T} A=A A^{T}=B$ and the result follows by (10, Theorem 2.1).
(ii) The proof of this result is analogous to the proof of (i).
(iii) The number of lattice points in $v$ dimensional space over the reals with components having absolute value less than $M$ is finite. Hence if $\mathscr{S}^{\prime}$ contains more elements than the number of such lattice points then there exist $t_{1}$, $t_{2} \in \mathscr{S}^{\prime}, t_{1} \neq t_{2}$, such that $r_{i}\left(t_{1}\right)=r_{i}\left(t_{2}\right)$ for $i=1,2, \ldots, v$. The desired result follows from (ii).
(iv) Once again as in (10) it may be shown that $r_{i}(t) \equiv 0 \bmod k$. Since $r_{i}(t)>0$ it follows that

$$
\left(\sum r_{i}(t)\right)^{2} \geqslant\left(\sum r_{i}^{2}(t)\right)+v(v-1) k^{2} .
$$

From the first of the equation given in (i) above it follows that

$$
k^{2} v(1-t) \leqslant(1-t) \sum r_{i}^{2}(t)
$$

Since $t>1$ we have $\sum r_{i}{ }^{2}(t) \leqslant k^{2} v$. But also

$$
k^{2} v^{2} \leqslant\left(\sum r_{i}(t)\right)^{2} \leqslant v\left(\sum r_{i}^{2}(t)\right)
$$

Hence $\sum r_{i}{ }^{2}(t)=k^{2} v$ and the proof may be completed as was the proof of (i).
We remark that if $v>k+1$ and $t>1$ then $r_{i}(t) \neq 0$ for $i=1,2, \ldots, v$.
Theorem 3 gives sufficient conditions for the existence of a $\lambda, k, v$ design in terms of integral solutions, which by Theorem 2 are known to exist, of the matric equation

$$
X^{T}(I-t S) X=B-t k^{2} S
$$

The problem of determining the nature of these solutions appears to be extremely difficult. Also of interest, and possibly a more pliable problem, is the determination of the integral automorphs of $I-t S$ and $B-t k^{2} S$.

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