Microhydrodynamics	The fluid dynamic equations	Properties of Stokes flow	Three Stokes-flow theorems	References
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# Basic concepts in viscous flow

### Élisabeth Guazzelli and Jeffrey F. Morris with illustrations by Sylvie Pic

Adapted from Chapter 1 of A Physical Introduction to Suspension Dynamics Cambridge Texts in Applied Mathematics

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A Physical Introduction to Suspension Dynamics

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  - Buoyancy and drag
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Microhydrodynamics, a term coined by G. K. Batchelor in the 1970s, deals with processes occurring in fluid flow when the characteristic length of the flow field is of the order of one micron

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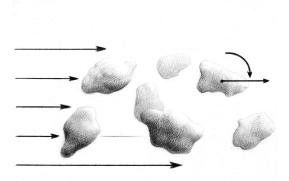
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# Many particles in a flow



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The fluid dynamic equations

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Three Stokes-flow theorems References

Navier-Stokes equations

# Equations for an incompressible fluid

Continuity equation for an incompressible fluid

$$abla \cdot \mathbf{u} = \mathbf{0}$$

Equation for conservation of momentum

$$\rho[\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla)\mathbf{u}] = \mathbf{f} + \nabla \cdot \boldsymbol{\sigma}^{\mathbf{a}}$$
$$= \mathbf{f} - \nabla \boldsymbol{\rho}^{\mathbf{a}} + \mu \nabla^{2} \mathbf{u}$$

The superscript a indicates an absolute pressure and a corresponding absolute stress tensor. The term 'absolute stress' is used to indicate the actual stress (with the absolute pressure being the true pressure) rather than a modified stress to be defined in slide 12 in which the hydrostatic pressure is removed.

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Navier-Stokes equation	IS			

# Newtonian fluid

#### Constitutive equation for a Newtonian fluid

$$\sigma^{a}_{ij} = -p^{a}\delta_{ij} + 2\mu e_{ij}$$

#### Symmetric stress tensor

$$\sigma^{a}_{ij} = \sigma^{a}_{ji}$$

Symmetric rate-of-strain tensor

$$e_{ij} = e_{ji} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

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Navier-Stokes equations

# Navier-Stokes equations

#### Incompressibility

$$\nabla\cdot {\bm u}=0$$

Momentum equation

$$\rho \frac{\partial \mathbf{u}}{\partial t} + \rho(\mathbf{u} \cdot \nabla)\mathbf{u} = \mathbf{f} - \nabla \rho^{a} + \mu \nabla^{2} \mathbf{u}$$

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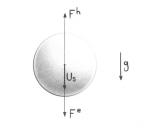
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Microhydrodynamics	The fluid dynamic equations	Properties of Stokes flow	Three Stokes-flow theorems	References
Dimensionless number	s			

# Reynolds number

$${\it Re} = rac{|
ho(\mathbf{u}\cdot
abla)\mathbf{u}|}{|\mu
abla^2\mathbf{u}|} = rac{UL}{
u}$$

For sedimenting (spherical) grain of sand of size  $L \sim 1 \mu m$  settling in water at velocity  $U \sim 1 \mu m/s$ ,  $Re \sim 10^{-6}$ 



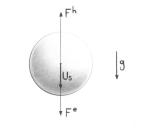
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Microhydrodynamics	The fluid dynamic equations	Properties of Stokes flow	Three Stokes-flow theorems	References
Dimensionless number	5			

# Stokes number

$$St = rac{|
ho \partial \mathbf{u} / \partial t|}{|\mu \nabla^2 \mathbf{u}|} = rac{L^2}{T 
u}$$

Sphere of radius  $a=1\mu$ m sedimenting in water at stationary regime when time  $T\gg a^2/
u\sim 10^{-6}$  s



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Microhydrodynamics	The fluid dynamic equations	Properties of Stokes flow	Three Stokes-flow theorems	References
Stokes equations				

# Stokes equations

Stokes equations: 
$$Re \ll 1$$
 and  $St \ll 1$   
 $\nabla \cdot \mathbf{u} = 0$   
 $\nabla \cdot \boldsymbol{\sigma}^a = -\nabla p^a + \mu \nabla^2 \mathbf{u} = \mathbf{f}$   
Homogeneous Stokes equations:  $\mathbf{f} = \rho \, \mathbf{g} \Rightarrow p = p^a - \rho \, \mathbf{g} \cdot \mathbf{x}$   
 $\nabla \cdot \mathbf{u} = 0$   
 $\nabla \cdot \boldsymbol{\sigma} = -\nabla p + \mu \nabla^2 \mathbf{u} = 0$ 

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The fluid dynamic equations

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Stokes equations

# Other expressions for Stokes equations

Stress tensor  $\sigma$ 

$$\sigma_{ij} = \sigma_{ji} = -p\delta_{ij} + 2\mu e_{ij}$$

Rate-of-strain tensor e

$$e_{ij} = e_{ji} = \frac{1}{2}(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i})$$

Stokes equations

$$abla \cdot \mathbf{u} = 0 \text{ or } e_{ii} = 0$$
 $abla \cdot \mathbf{\sigma}^a = \mathbf{f} \text{ or } \frac{\partial \sigma^a_{ij}}{\partial x_j} = f_i$ 

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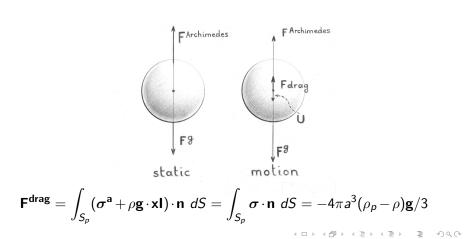
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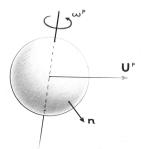
# Buoyancy and drag



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Boundary conditions				

# Boundary conditions



No-slip boundary condition on the particles:

$$\mathsf{u}(\mathsf{x}) = \mathsf{U}^{\mathsf{p}} + \omega^{\mathsf{p}} imes (\mathsf{x} - \mathsf{x}_{\mathsf{p}})$$

at the surface of a particle with center of mass at  $\boldsymbol{x}_p$ 

+ Outer boundary condition on a containing vessel or at infinity

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Linearity				

# Linearity

Linearity of the Stokes equations: no non-linear convective acceleration term  $(\bm{u}\cdot\nabla)\bm{u}$ 

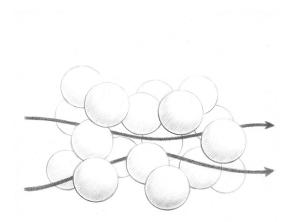
- Principle of superposition: by adding different solutions of the Stokes equations one obtains also a solution of the Stokes equations
- Reversibility: the motion is reversible in the driving force

Microhydrodynamics	The fluid dynamic equations	Properties of Stokes flow	Three Stokes-flow theorems	Re
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#### Linearity

# Streamlines in a porous medium

A doubling of the driving pressure gradient yields a doubling of the flow rate but no change to the streamlines



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The fluid dynamic equations 00000000

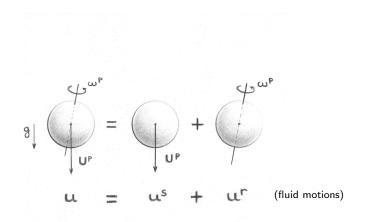
Properties of Stokes flow

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Linearity

# Principle of superposition

Summation of translation and rotation



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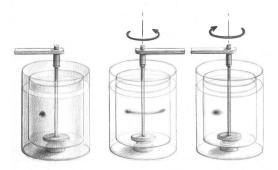
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Reversibility

# Description of G. I. Taylor film on reversibility



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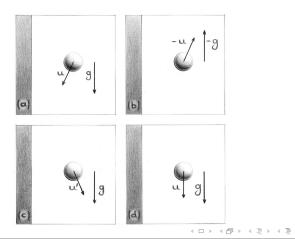
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Properties of Stokes flow

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Reversibility

#### Reversibility argument for a sphere settling near a wall A spherical particle falling adjacent to a wall falls at constant distance, as shown by the reversibility principle depicted visually here



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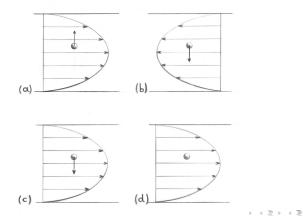
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Properties of Stokes flow

Reversibility

# Reversibility argument for a sphere in a Poiseuille flow

A single neutrally-buoyant spherical particle in Poiseuille flow stays at a fixed distance from the wall, as shown by the reversibility principle depicted visually here



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Instantaneity				

# Instantaneity

#### No history dependence $\partial \mathbf{u}/\partial t$

The flow is determined by the configuration given by the boundary conditions, coming both from the particle positions and outer boundaries

Information from boundary motion communicated to infinity instantly

- Divergence of the homogeneous momentum equation  $\Rightarrow \nabla^2 p = 0.$
- Curl of the homogeneous momentum equation  $\Rightarrow \nabla^2 \tilde{\omega} = 0$ with  $\tilde{\omega} = \nabla \times \mathbf{u}$ .
- Pressure p and vorticity  $ilde{\omega}$  are harmonic

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The fluid dynamic equations 00000000

Properties of Stokes flow

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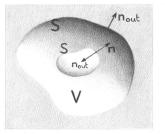
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Minimum dissipation

# Kinetic energy balance



Kinetic energy:

$$K = \int_{V} \rho \frac{\mathbf{u}^2}{2} dV$$

where V is the fluid volume

Calculation for unsteady Stokes case:

$$\rho \frac{\partial \mathbf{u}}{\partial t} = \mathbf{f} + \nabla \cdot \boldsymbol{\sigma}$$

$$\frac{\partial K}{\partial t} = \int_{V} \rho \, \mathbf{u} \cdot \frac{\partial \mathbf{u}}{\partial t} dV = \int_{V} f_{i} u_{i} dV + \int_{V} u_{i} \frac{\partial \sigma_{ij}}{\partial x_{j}} dV$$
$$= \int_{V} f_{i} u_{i} dV + \oint_{S} U_{i} \sigma_{ij} n_{j}^{out} dS - \int_{V} \frac{\partial u_{i}}{\partial x_{j}} \sigma_{ij} dV$$

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# Rate of energy dissipation

Rate of energy dissipation due to viscosity

$$\Phi = \int_{V} \frac{\partial u_{i}}{\partial x_{j}} \sigma_{ij} dV = \int_{V} e_{ij} \sigma_{ij} dV = \int_{V} 2\mu e_{ij} e_{ij} dV \ge 0$$

Steady Stokes flow 
$$(\partial K/\partial t = 0)$$
  
$$\int_{V} \rho \mathbf{u} \cdot \frac{D \mathbf{u}}{D t} dV = \int_{V} f_{i} u_{i} dV + \oint_{S} U_{i} \sigma_{ij} n_{j}^{out} dS - \Phi = 0$$

Rate of energy dissipation = rate of working by external forces  $\Phi = \int_{V} \mathbf{f} \cdot \mathbf{u} \, dV + \oint_{S} \mathbf{U} \cdot (\boldsymbol{\sigma} \cdot \mathbf{n}^{out}) dS$ 

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Minimum dissipation				

# Minimum dissipation theorem

Consider **u** and  $\mathbf{u}^{S}$  two velocity fields in the volume V such as

• 
$$\nabla \cdot \mathbf{u} = \nabla \cdot \mathbf{u}^{S} = 0$$
 in the volume V

• 
$$\mathbf{u} = \mathbf{u}^{S} = \mathbf{U}$$
 on the surface S limiting V

• **u**<sup>S</sup> satisfying the homogeneous Stokes equations (no external force **f**)

The minimum dissipation theorem states that the Stokes flow corresponds to the least dissipation

$$2\mu\int_{V}e_{ij}^{S}e_{ij}^{S}dV\leq 2\mu\int_{V}e_{ij}e_{ij}dV$$

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Minimum dissipation				

• Writing  $\delta \mathbf{u} = \mathbf{u} - \mathbf{u}^{S}$  and  $\delta e_{ij} = e_{ij} - e_{ij}^{S}$  with boundary conditions  $\delta \mathbf{u} = 0$ 

Difference between the two integrals

$$2\mu \int_{V} (e_{ij}e_{ij} - e_{ij}^{S}e_{ij}^{S})dV = 2\mu \int_{V} \delta e_{ij}(e_{ij} + e_{ij}^{S})dV$$
$$= \underbrace{2\mu \int_{V} \delta e_{ij}\delta e_{ij}dV}_{\geq 0} + \underbrace{4\mu \int_{V} \delta e_{ij}e_{ij}^{S}dV}_{=0}$$

Second integral

$$4\mu \int_{V} \delta e_{ij} e_{ij}^{S} dV = 2 \int_{V} \delta e_{ij} \sigma_{ij}^{S} dV \quad \text{using } \delta e_{kk} = 0$$

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Difference between the two integrals

$$2\mu \int_{V} (e_{ij}e_{ij} - e_{ij}^{S}e_{ij}^{S})dV = 2\mu \int_{V} \delta e_{ij}(e_{ij} + e_{ij}^{S})dV$$
$$= \underbrace{2\mu \int_{V} \delta e_{ij}\delta e_{ij}dV}_{\geq 0} + \underbrace{4\mu \int_{V} \delta e_{ij}e_{ij}^{S}dV}_{=0}$$

Second integral

$$4\mu \int_{V} \delta e_{ij} e_{ij}^{S} dV = 2 \int_{V} \frac{\partial \delta u_{i}}{\partial x_{j}} \sigma_{ij}^{S} dV \quad \text{using } \sigma_{ij}^{S} = \sigma_{ji}^{S}$$

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Difference between the two integrals

$$2\mu \int_{V} (e_{ij}e_{ij} - e_{ij}^{S}e_{ij}^{S})dV = 2\mu \int_{V} \delta e_{ij}(e_{ij} + e_{ij}^{S})dV$$
$$= \underbrace{2\mu \int_{V} \delta e_{ij}\delta e_{ij}dV}_{\geq 0} + \underbrace{4\mu \int_{V} \delta e_{ij}e_{ij}^{S}dV}_{=0}$$

Second integral

$$4\mu \int_{V} \delta \mathbf{e}_{ij} \mathbf{e}_{ij}^{S} dV = -2 \int_{V} \delta u_{i} \frac{\partial \sigma_{ij}^{S}}{\partial x_{j}} dV + 2 \int_{V} \frac{\partial \delta u_{i} \sigma_{ij}^{S}}{\partial x_{j}} dV$$

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Difference between the two integrals

$$2\mu \int_{V} (e_{ij}e_{ij} - e_{ij}^{S}e_{ij}^{S})dV = 2\mu \int_{V} \delta e_{ij}(e_{ij} + e_{ij}^{S})dV$$
$$= \underbrace{2\mu \int_{V} \delta e_{ij}\delta e_{ij}dV}_{\geq 0} + \underbrace{4\mu \int_{V} \delta e_{ij}e_{ij}^{S}dV}_{=0}$$

Second integral

$$4\mu \int_{V} \delta e_{ij} e_{ij}^{S} dV = 2 \int_{S} \delta u_{i} \sigma_{ij}^{S} n_{j}^{out} dS \quad \text{using } \frac{\partial \sigma_{ij}^{S}}{\partial x_{j}} = 0$$

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Difference between the two integrals

$$2\mu \int_{V} (e_{ij}e_{ij} - e_{ij}^{S}e_{ij}^{S})dV = 2\mu \int_{V} \delta e_{ij}(e_{ij} + e_{ij}^{S})dV$$
$$= \underbrace{2\mu \int_{V} \delta e_{ij}\delta e_{ij}dV}_{\geq 0} + \underbrace{4\mu \int_{V} \delta e_{ij}e_{ij}^{S}dV}_{=0}$$

Second integral

$$4\mu \int_V \delta e_{ij} e_{ij}^S dV = 0$$
 using boundary conditions  $\delta \mathbf{u} = 0$ 

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# Uniqueness of the Stokes equation

- (u<sup>(1)</sup>, p<sup>(1)</sup>) and (u<sup>(2)</sup>, p<sup>(2)</sup>) two solutions of the homogeneous Stokes equation satisfying the same boundary conditions u<sup>(1)</sup> = u<sup>(2)</sup> = U on the surface S limiting the volume V
- $(\mathbf{u}^{(1)}, p^{(1)})$  Stokes flow  $(\Rightarrow \Phi^{(1)} \le \Phi^{(2)})$  and  $(\mathbf{u}^{(2)}, p^{(2)})$ Stokes flow  $(\Rightarrow \Phi^{(2)} \le \Phi^{(1)}) \Rightarrow \Phi^{(1)} = \Phi^{(2)}$

• 
$$\Phi^{(1)} = \Phi^{(2)} \Rightarrow e^{(1)}_{ij} = e^{(2)}_{ij}$$

- $e_{ij}^{(1)} = e_{ij}^{(2)} \Rightarrow \mathbf{u}^{(1)} \mathbf{u}^{(2)}$  solid body motion
- Boundary conditions  $\mathbf{u}^{(1)} \mathbf{u}^{(2)} = \mathbf{0} \Rightarrow \mathbf{u}^{(1)} = \mathbf{u}^{(2)}$
- Homogeneous Stokes equations  $\Rightarrow p^{(1)} p^{(2)} = \text{constant}$

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Reciprocity				

# Reciprocal theorem

- $(\mathbf{u}^{(1)}, \sigma^{(1)})$  and  $(\mathbf{u}^{(2)}, \sigma^{(2)})$  Stokes flows driven respectively by the external forces  $\mathbf{f}^{(1)}$  and  $\mathbf{f}^{(2)}$  and by the boundary conditions  $\mathbf{u}^{(1)} = \mathbf{U}^{(1)}$  and  $\mathbf{u}^{(2)} = \mathbf{U}^{(2)}$  on the surface *S* limiting the fluid volume *V*
- The reciprocal theorem states that the rate of working by the flow u<sup>(2)</sup> against the forces of flow u<sup>(1)</sup> (f<sup>(1)</sup> in the volume and σ<sup>(1)</sup> · n<sup>out</sup> on the surface) is the same by interchanging (1) and (2)

$$\int_{V} f_{j}^{(1)} u_{j}^{(2)} dV + \oint_{S} \sigma_{ij}^{(1)} U_{j}^{(2)} n_{i}^{out} dS = \int_{V} f_{j}^{(2)} u_{j}^{(1)} dV + \oint_{S} \sigma_{ij}^{(2)} U_{j}^{(1)} n_{i}^{out} dS$$

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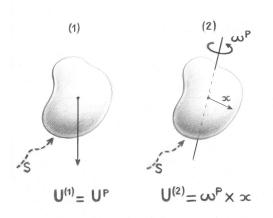
Properties of Stokes flow 0000000

Three Stokes-flow theorems

Reciprocity

# Example of flows for a general shape body

Translation without rotation (left) and rotation without translation (right)



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Reciprocity				

# Proof of reciprocal theorem

Writing the left-hand side of equation with use of divergence theorem as

$$\begin{split} \int_{V} f_{j}^{(1)} u_{j}^{(2)} dV + \oint_{S} \sigma_{ij}^{(1)} U_{j}^{(2)} n_{i}^{out} dS &= \int_{V} (f_{j}^{(1)} u_{j}^{(2)} + \frac{\partial (\sigma_{ij}^{(1)} u_{j}^{(2)})}{\partial x_{i}}) dV \\ &= \int_{V} (f_{j}^{(1)} u_{j}^{(2)} + \frac{\partial \sigma_{ij}^{(1)}}{\partial x_{i}} u_{j}^{(2)} + \sigma_{ij}^{(1)} \frac{\partial u_{j}^{(2)}}{\partial x_{i}}) dV \\ &= \int_{V} \sigma_{ij}^{(1)} \frac{\partial u_{j}^{(2)}}{\partial x_{i}} dV \quad \text{using } \frac{\partial \sigma_{ij}^{(1)}}{\partial x_{i}} + f_{j} = 0 \\ &= \int_{V} \sigma_{ij}^{(1)} e_{ij}^{(2)} dV \quad \text{using } \sigma_{ij}^{(1)} = \sigma_{ji}^{(1)} \\ &= 2\mu \int_{V} e_{ij}^{(1)} e_{ij}^{(2)} dV \quad \text{using } e_{kk}^{(1)} = 0 \end{split}$$

which, being symmetric, is also equal to the right-hand side of equation

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Microhydrodynamics	The fluid dynamic equations	Properties of Stokes flow	Three Stokes-flow theorems	References
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# Reciprocal theorem without external forces

Without external forces, the reciprocal theorem becomes

$$\oint_{S} \sigma_{ij}^{(1)} U_j^{(2)} n_i^{out} dS = \oint_{S} \sigma_{ij}^{(2)} U_j^{(1)} n_i^{out} dS$$

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- The fluid dynamic equations
  - Navier-Stokes equations
  - Dimensionless numbers
  - Stokes equations
  - Buoyancy and drag
  - Boundary conditions
- 2 Properties of Stokes flow
  - Linearity
  - Reversibility
  - Instantaneity
- 3 Three Stokes-flow theorems
  - Minimum dissipation
  - Uniqueness
  - Reciprocity



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